

# Completely Blind Quality Assessment of User Generated Video Content

Invited Talk at SPCOM 2022

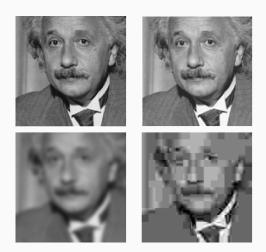
Sumohana S. Channappayya July 13, 2022

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### Outline

- · Introduction to Quality Assessment
- · Perceptual Straightening Hypothesis
- · Proposed Blind Video Quality Assessment Algorithm
- Results
- Concluding Remarks

# What is Quality Assessment?



# Why Quality Assessment?

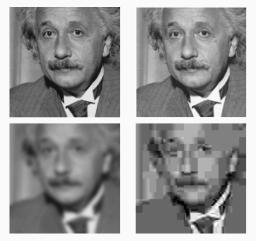


Table 1: Distorted images have same mean squared error (MSE)! L<sup>p</sup> norms fail! [12] <sup>1</sup>

<sup>&</sup>lt;sup>1</sup>Z Wang and A C Bovik. "Mean squared error: Love it or leave it? A new look at signal fidelity measures". In: IEEE Signal Processing Magazine 26.1 (2009), pp. 98-117.

### Why Quality Assessment?



Figure 1: Guarantee visual quality. Why?  $\approx$  6.6 billion smart-phones in 2021!<sup>2</sup>

 $<sup>^{2} {\</sup>rm http://www.statista.com/statistics/330695/number-of-smartphone-users-worldwide/}$ 

 $<sup>^{3} {\</sup>rm http://www.nytimes.com/2015/07/23/arts/international/photos-photos-everywhere.html} \\$ 

# Why Quality Assessment?



Figure 1: Guarantee visual quality. Why?  $\approx$  6.6 billion smart-phones in 2021!<sup>2</sup>



Figure 2: Optimal resource usage. Why? More than 1 trillion photos per year in recent years!<sup>3</sup>

 $<sup>^{2} {\</sup>rm http://www.statista.com/statistics/330695/number-of-smartphone-users-worldwide/}$ 

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Measured in terms of mean opinion score (MOS) and difference MOS (DMOS). It forms the ground truth in all QA work.

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- Reduced-reference (RR):  $Q_{test} = g(\hat{M}_{ref}, M_{test}; \theta)$
- No-reference (NR):  $Q_{test} = h(M_{test}; \theta)$

6

### **Performance Measures**

- Linear Correlation Coefficient (LCC)
- · Spearman Rank Ordered Correlation Coefficient (SROCC)
- Root Mean Squared Error (RMSE)

### Blind Video Quality Assessment

- How do we assess the perceptual quality of natural videos in the blind (NR) setting?
- · Natural videos have rich temporal information
- · How do we leverage this rich temporal information?
- Straightness principle: Predictions of future samples can be formulated as linear operations in the latent space/representation space<sup>4</sup>

<sup>&</sup>lt;sup>4</sup>Goroshin, Ross, Mathieu, Michael, and LeCun, Yann. "Learning to linearize under uncertainty." NeurIPS 2015.

# Perceptual Straightening in the Human Visual System

### Perceptual Straightening Hypothesis [2] 5

"Many behaviors rely on predictions derived from recent visual input, but the temporal evolution of those inputs is generally complex and difficult to extrapolate. We propose that the visual system transforms these inputs to follow straighter temporal trajectories."

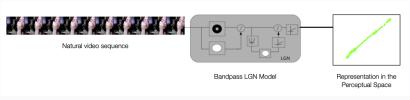


Figure 3: Illustration of the perceptual straightening hypothesis

<sup>&</sup>lt;sup>5</sup>Olivier J Hénaff, Robbe LT Goris, and Eero P Simoncelli. "Perceptual straightening of natural videos". In: *Nature Neuroscience* 22.6 (2019), p. 984.

# Two Simple Questions

- 1. What happens to the perceptual straightness of distorted natural videos?
- 2. Is the perceptual straightness a function of video quality?

# **Empirical Analysis of Q1**

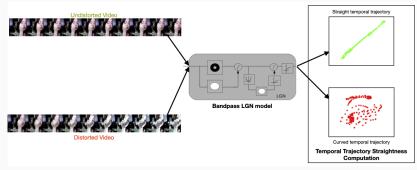


Figure 4: Effect of distortion on perceptual domain representation

# Empirical Analysis of Q2

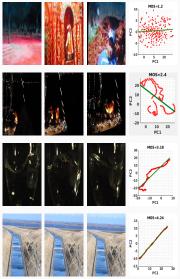


Figure 5: Straightness increases with MOS

### **Temporal Quality Estimation**

- The input frame  $X_t$  is passed through the LGN model to find the perceptual domain representation  $F_t$ , followed by PCA-based dimensionality reduction to give a d-dimensional vector  $\mathbf{f}_t$
- · Estimate the feature at current time using a linear model

$$\hat{\mathbf{f}}_t = \beta_0 \mathbf{1} + \sum_{i=1}^K \beta_i \mathbf{f}_{t-i},$$

- $\beta_0, \beta_1, \beta_2, \dots, \beta_K$ : scalar model parameters
- 1: d-dimensional vector of ones
- $\mathbf{f}_t$ : ground truth representation of frame at time t
- $\hat{\mathbf{f}}_t$ : prediction at time t
- *K* is a tunable parameter

### **Temporal Quality Estimation**

Frame level error:

$$D_t = ||\mathbf{f}_t - \hat{\mathbf{f}}_t||_1$$

• Temporal quality estimate over an N-frame video:

$$Q_{\text{temporal}} = \log(\frac{1}{N} \sum_{t=1}^{N} D_t)$$

### Spatial Quality Estimation <sup>6</sup>

· Estimate the frame level quality

$$q_t = \sum_{i=t-\frac{N}{3}+1}^t w_{t-i+1} \cdot \text{NIQE}(X_i),$$

where  $NIQE(X_i)$  is the NIQE score of frame  $X_i$ ,

$$w_j = \frac{\exp(-\alpha j)}{\sum_{j=1}^{\frac{N}{3}} \exp(-\alpha i)}, 1 \le j \le \frac{N}{3}.$$

Spatial quality estimate over an N-frame video:

$$Q_{\text{spatial}} = \frac{1}{N} \sum_{i=1}^{N} q_i.$$

<sup>&</sup>lt;sup>6</sup> Z. Tu, C-J. Chen, L-H. Chen, N. Birkbeck, B. Adsumilli, and A. C.Bovik, "A comparative evaluation of temporal pooling methods for blind video qua- Spatial Quality" arXiv preprint arXiv:2002.10651, 2020

### STraightness Evaluation Metric (STEM)

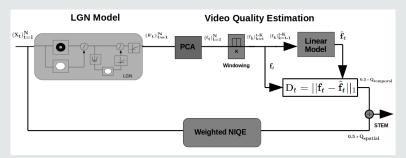


Figure 6: Block diagram of the proposed BVQA algorithm STEM.

$$STEM = \frac{Q_{temporal} + Q_{spatial}}{2}$$

# User Generated Video Quality Assessment Datasets

- KoNViD-1K dataset [3]: 1200 videos, > 960 × 540, 8 sec, 24/25/30 fps, various attributes (blur, contrast, colourfulness, etc.), CC attributed source videos, Crowdsourced, MOS
- VQC dataset [9]: 585 videos, 404 × 720, 10 sec, HD, Full HD, 43 mobile devices, Crowdsourced (AMT), MOS
- CVD dataset [7]: 234 videos, QCIF to Full HD, 10-25 sec, 10-31 fps, 78 cameras, Crowdsourced, MOS
- YouTube-UGC dataset [11]: 1380 videos, 360p to 4K, 20 sec, Gaming, Sports, Music Video etc., Crowdsourced, MOS
- LIVE Qualcomm dataset [1]: 208 videos, Full HD, 8 cameras, 15 sec, 30 fps, Crowdsourced, MOS, artifacts, color, exposure, focus, sharpness, stabilization

# Performance Evaluation on the KoNViD-1K Dataset [3]

**Table 2:** Performance evaluation results and comparison with representative supervised (italics) and unsupervised/completely blind VQA algorithms on the KoNViD-1K dataset [3] (K=6,d=10)

Method	LCC	SROCC	RMSE
V-BLIINDS [8]	0.565	0.572	0.526
TL-VQM [4]	0.79	0.80	0.406
VIIDEO [5]	-0.015	0.013	0.639
NIQE [6]	0.544	0.542	0.537
NIQE Hysteresis pooling [10]	0.563	0.569	-
Q <sub>temporal</sub>	0.444	0.450	0.574
$Q_{spatial}$	0.547	0.546	0.534
STEM	0.629	0.629	0.497

# Performance on the VQC Dataset [9]

**Table 3:** Performance evaluation results and comparison with representative supervised (italics) and unsupervised/completely blind VQA algorithms on the LIVE VQC dataset [9] (K = 6, d = 10).

Method	LCC	SROCC	RMSE
V-BLIINDS [8]	0.718	0.707	11.546
VIIDEO [5]	0.137	0.029	16.882
NIQE [6]	0.610	0.563	13.890
NIQE Percentile pooling [10]	0.630	0.634	-
Q <sub>temporal</sub>	0.454	0.466	15.148
$Q_{ m spatial}$	0.613	0.594	13.467
STEM	0.670	0.656	12.649

### Performance Evaluation on the CVD Dataset [7]

**Table 4:** Performance evaluation results and comparison with representative supervised (italics) and unsupervised/completely blind VQA algorithms on the CVD dataset [7] (K = 6, d = 10).

Method	LCC	SROCC	RMSE
V-BLIINDS [8]	0.71	0.70	15.222
TL-VQM [4]	0.85	0.83	11.33
VIIDEO [5]	-	-	
NIQE [6]	0.61	0.58	17.15
Q <sub>temporal</sub>	0.361	0.355	20.507
Q <sub>spatial</sub>	0.619	0.580	16.834
STEM	0.629	0.593	16.664

### Performance Evaluation on the YouTube-UGC Dataset [11]

**Table 5:** Performance evaluations results and comparison with supervised (italics) and unsupervised/completely blind VQA algorithms on the YouTube-UGC dataset [11] (K = 6, d = 10).

Method	LCC	SROCC	RMSE
V-BLIINDS [8]	0.559	0.555	0.535
VIIDEO [5]	0.146	0.130	0.637
NIQE [6]	0.105	0.236	0.640
$Q_{temporal}$	0.272	0.321	0.636
$Q_{\rm spatial}$	0.286	0.239	0.6221
STEM	0.318	0.284	0.623

### Performance Evaluation on the LIVE Qualcomm Dataset [1]

Table 6: LCC performance results on the LIVE Qualcomm dataset [1] (K=6, d=10). Representative supervised VQA algorithms are in italics.

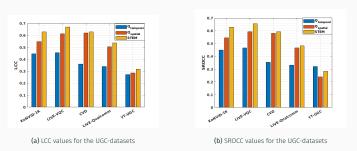
Method	artifacts	color	focus	sharpness	stabilization	exposure	all
V-BLIINDS [8]	0.8386	0.664	0.807	0.684	0.713	0.690	0.665
TL-VQM [4]	-	-	-	-	-	-	0.81
VIIDEO [5]	0.288	0.331	0.251	0.3012	0.369	0.207	0.098
Q <sub>temporal</sub>	0.566	0.304	0.280	0.475	0.423	0.749	0.339
Q <sub>spatial</sub>	0.4638	0.4703	0.4523	0.619	0.596	0.526	0.504
STEM	0.725	0.493	0.563	0.638	0.631	0.587	0.537

### Performance Evaluation on the LIVE Qualcomm Dataset [1]

**Table 7:** SROCC performance results on the LIVE Qualcomm dataset [1] (K=6, d=10). Representative supervised VQA algorithms are in italics.

Method	artifacts	color	focus	sharpness	stabilization	exposure	all
V-BLIINDS [8]	0.732	0.607	0.803	0.678	0.660	0.642	0.617
TL-VQM [4]	-	-	-	-	-	-	0.84
VIIDEO [5]	-0.178	0.142	0	-0.178	-0.107	-0.071	-0.141
Q <sub>temporal</sub>	0.432	0.381	0.428	0.491	0.521	0.446	0.332
Q <sub>spatial</sub>	0.450	0.341	0.556	0.505	0.338	0.297	0.467
STEM	0.646	0.527	0.549	0.593	0.412	0.555	0.483

# The Contributions of $Q_{temporal}$ and $Q_{spatial}$ to Performance



**Figure 7:** Bar graphs illustrating the ablation study involving the components  $Q_{\text{temporal}}$ ,  $Q_{\text{spatial}}$  and their combination in STEM on the five UGC datasets considered in this work.

# **Concluding Remarks**

- Explainable approach to NRVQA inspired by the idea of perceptual straightening
- STEM is completely blind and it is computationally not very expensive
- · Few parameters in the computational models
- STEM delivers competitive performance on the authentic VQA datasets

# <u>Acknowledgements</u>

- · Part of Parimala Kancharla's PhD work
- $\boldsymbol{\cdot}$  Thanks to the SPCOM 2022 organizers for the invitation!

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# Tuning of the Parameters K, d

 $\cdot$  Performance of the proposed blind VQA algorithm on various UGC datasets different values of the hyperparameter K with d=10

Dataset	Method	K = 2				K = 4			K = 6			K = 8		
		LCC	SROCC	RMSE										
KoNViD-1K	$Q_{\text{temporal}}$	0.426	0.435	0.579	0.441	0.448	0.572	0.444	0.450	0.574	0.446	0.451	0.574	
	STÉM	0.628	0.628	0.498	0.635	0.633	0.498	0.629	0.629	0.497	0.628	0.626	0.498	
LIVE-VQC	$Q_{\text{temporal}}$	0.460	0.462	15.143	0.461	0.467	14.553	0.459	0.466	15.148	0.448	0.457	15.143	
	STÉM	0.671	0.657	12.639	0.669	0.655	12.399	0.670	0.656	12.649	0.670	0.653	12.639	
CVD	$Q_{\text{temporal}}$	0.29	0.279	20.519	0.355	0.350	20.037	0.361	0.315	20.507	0.264	0.263	20.651	
	STEM	0.626	0.588	16.717	0.623	0.593	16.905	0.629	0.593	16.664	0.619	0.567	16.834	
LIVE-Qualcomm	$Q_{\text{temporal}}$	0.275	0.241	11.745	0.339	0.332	11.702	0.285	0.244	11.745	0.299	0.281	11.901	
	STEM	0.537	0.483	10.125	0.537	0.483	10.102	0.537	0.483	10.102	0.537	0.483	10.101	
YouTube - UGC	Q <sub>temporal</sub>	0.218	0.213	0.631	0.225	0.215	0.636	0.272	0.321	0.6273	0.269	0.327	0.628	
	STÉM	0.295	0.294	0.624	0.296	0.292	0.623	0.318	0.284	0.618	0.318	0.285	0.618	

# Tuning of the Parameters K, d

• Performance of the proposed blind VQA algorithm on various UGC datasets different values of the hyperparameter d with K = 6

Dataset	Method	d = 10				d = 30		d = 50			d = 80		
		LCC	SROCC	RMSE	LCC	SROCC	RMSE	LCC	SROCC	RMSE	LCC	SROCC	RMSE
KoNViD-1K	$Q_{\text{temporal}}$	0.444	0.450	0.574	0.440	0.446	0.575	0.440	0.451	0.574	0.436	0.435	0.575
	STÉM	0.629	0.629	0.497	0.627	0.626	0.499	0.629	0.629	0.497	0.628	0.628	0.498
LIVE-VQC	$Q_{\text{temporal}}$	0.459	0.466	15.148	0.455	0.461	15.189	0.450	0.449	15.227	0.459	0.445	15.150
	STEM	0.670	0.656	12.649	0.665	0.648	12.726	0.664	0.645	12.753	0.663	0.649	12.765
CVD	Q <sub>temporal</sub>	0.361	0.315	20.507	0.324	0.275	20.282	0.332	0.326	20.217	0.345	0.344	20.123
	STÉM	0.629	0.593	16.664	0.626	0.564	16.928	0.614	0.562	16.919	0.662	0.582	16.721
LIVE-Qualcomm	$Q_{\text{temporal}}$	0.285	0.244	11.745	0.312	0.254	11.683	0.327	0.324	11.674	0.294	0.255	11.702
	STEM	0.537	0.483	10.102	0.537	0.483	10.123	0.537	0.483	10.125	0.537	0.483	10.118
YouTube - UGC	$Q_{\text{temporal}}$	0.272	0.321	0.627	0.214	0.248	0.646	0.235	0.271	0.646	0.244	0.3516	0.632
	STÉM	0.318	0.284	0.618	0.305	0.292	0.621	0.307	0.274	0.620	0.317	0.296	0.618