

Machine learning for Dynamic Social Network Analysis

Applications: Models

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2017

Outline of the Seminar

REPRESENTATION: TEMPORAL POINT

- PROCESSES
1. Intensity function
 2. Basic building blocks
 3. Superposition
 4. Marks and SDEs with jumps

APPLICATIONS: MODELS

1. Information propagation
2. Opinion dynamics
3. Information reliability
4. Knowledge acquisition

APPLICATIONS:

CONTROL

1. Influence maximization
2. Activity shaping
3. When to post
4. When to fact check

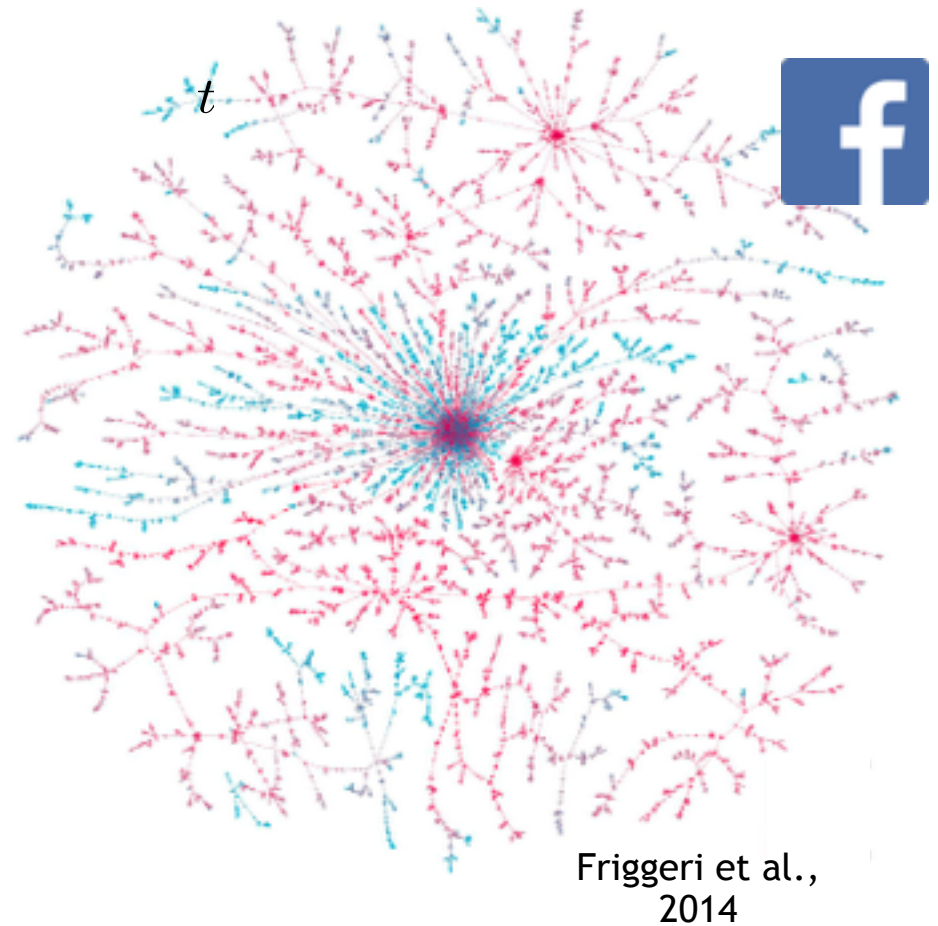
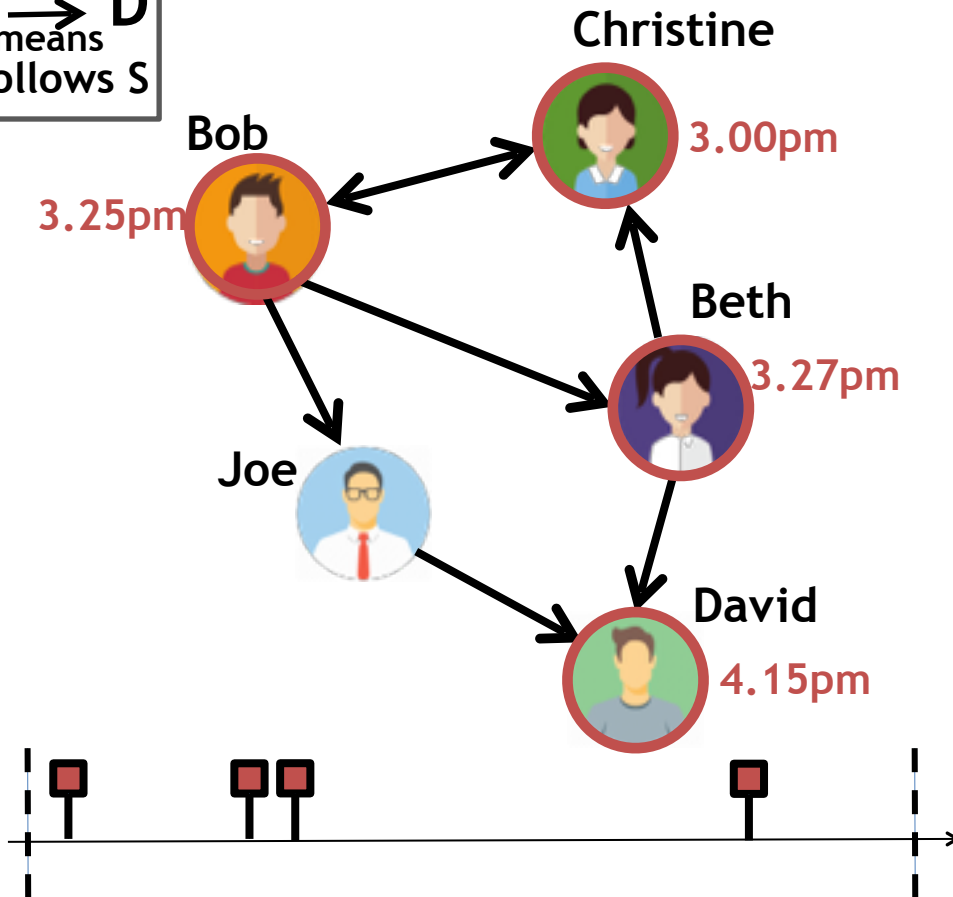
**This
lecture**

Applications: Models

- 1. Idea adoption**
2. Opinion dynamics
3. Information reliability
4. Knowledge acquisition

Idea adoption: an example

$S \rightarrow D$
means
D follows S



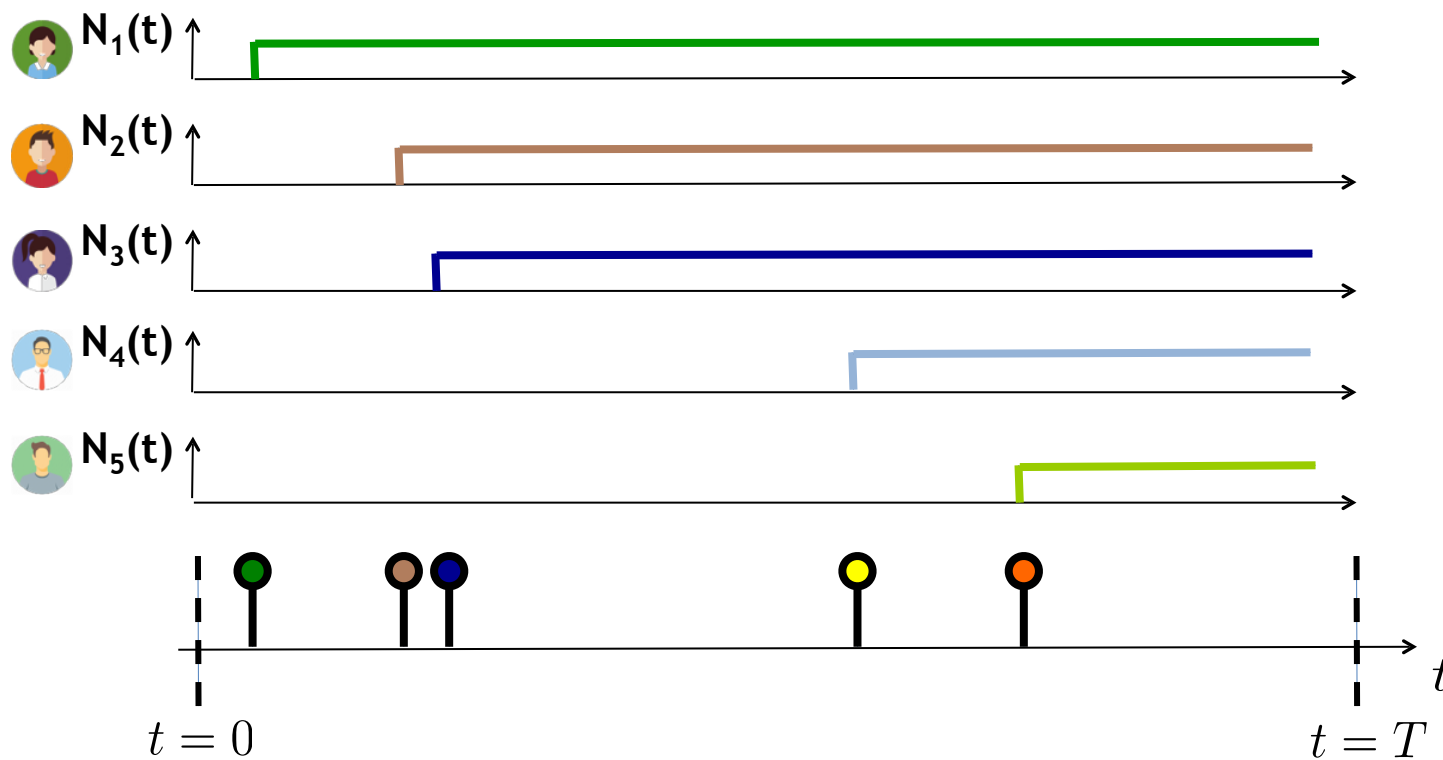
They can have an
impact
in the off-line world

theguardian

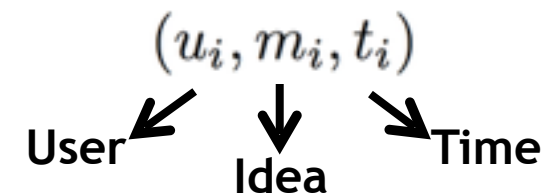
Click and elect: how fake news helped Donald Trump win a real election

Idea adoption representation

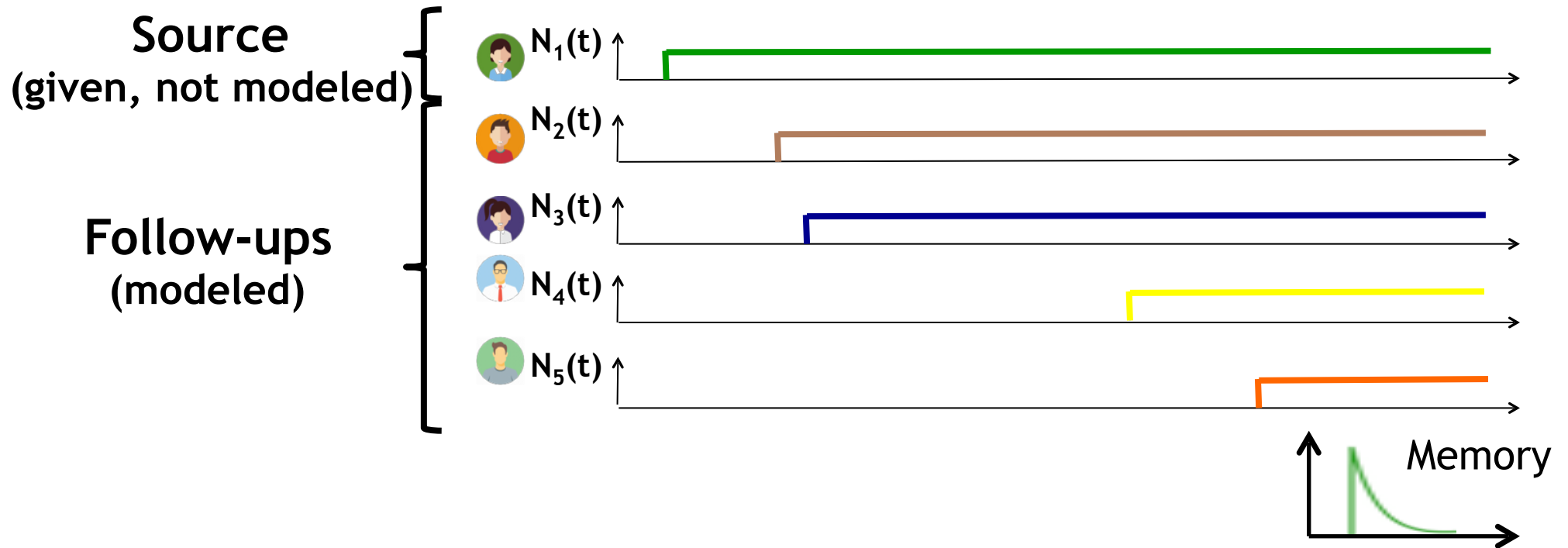
We represent an idea adoption using terminating temporal point processes:



Idea adoption:



Idea adoption intensity



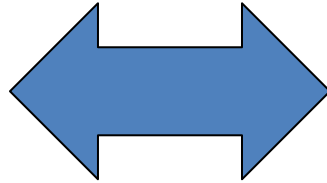
$$\lambda_u^*(t) = \underbrace{(1 - N(t))}_{\text{Adopt idea only once}} \sum_{v \in [m]} b_{vu} \underbrace{\sum_{e_i \in \mathcal{H}_v(t)} \kappa(t - t_i)}_{\text{Previous messages by user v}}$$

Influence from user v on user u

Model inference from multiple adoptions

Conditional intensities

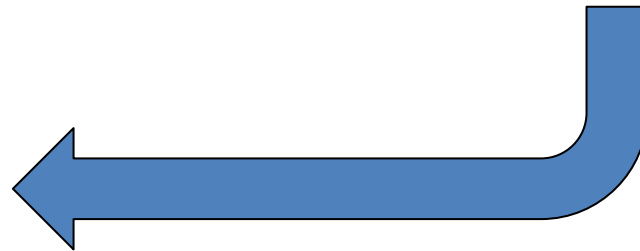
$$\lambda_u^*(t)$$



Idea adoption log-likelihood

$$\mathcal{L} = \sum_{u=1}^n \log \lambda_u^*(t_u) - \int_0^T \lambda_u^*(\tau) d\tau$$

Maximum likelihood approach to find model parameters!



Sum up log-likelihoods of multiple ideas!

Theorem. For any choice of parametric memory, the maximum likelihood problem is **convex in B.**

Topic-sensitive rates

Topic-modulated influence:

$$b_{vu} = \sum_{l=1}^K b_{vu}^l m_l$$

↑
LDA
weight
for topic l

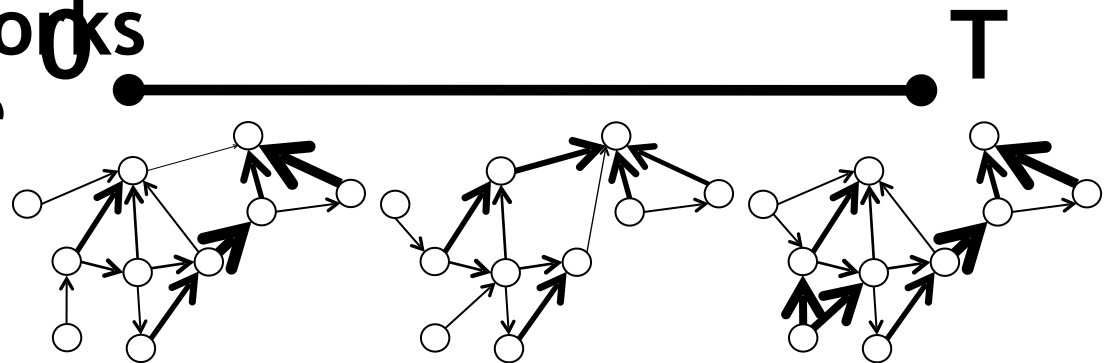


Dynamic influence

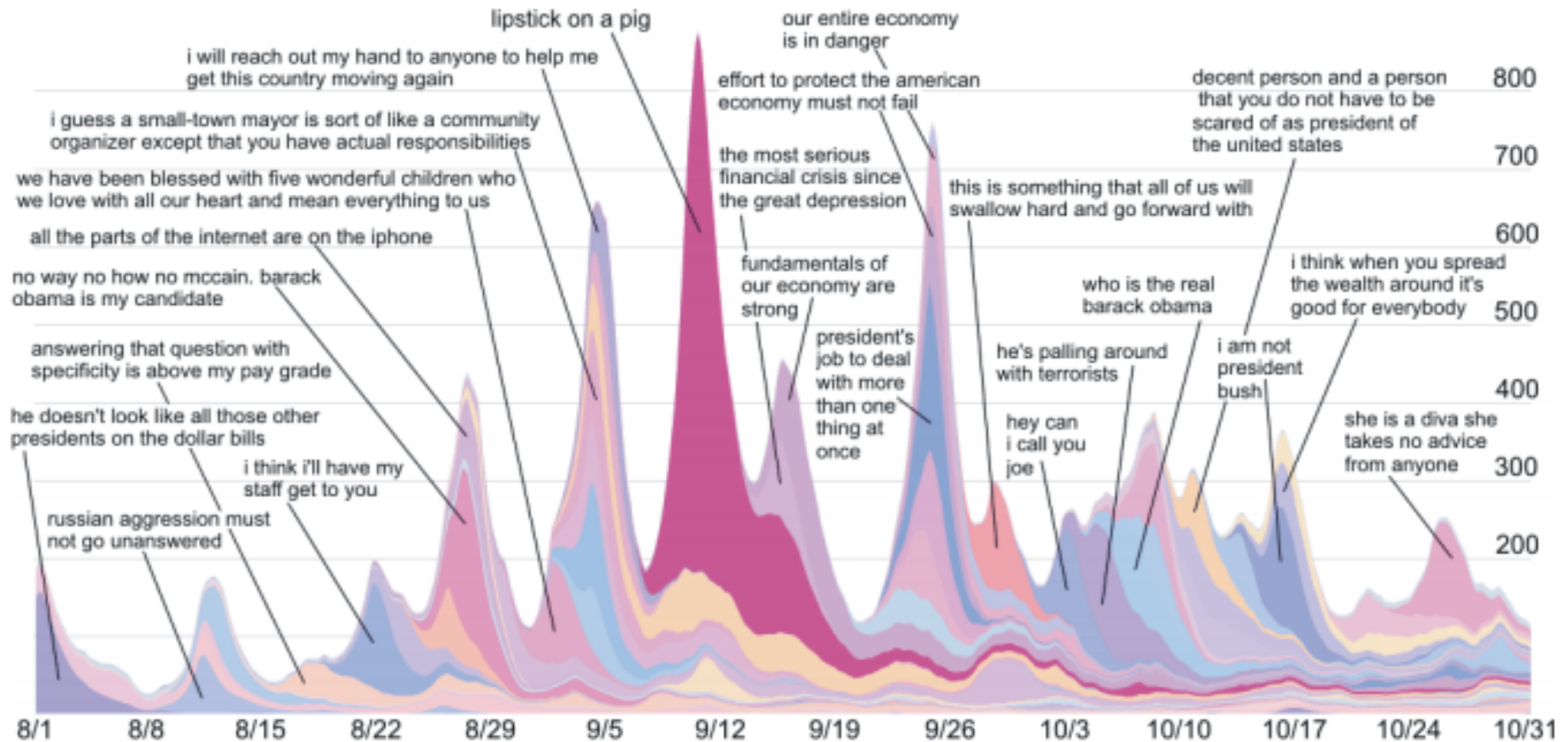
In some cases, influence change over time:



Propagation over networks
with variable influence



Memetracker



[Leskovec et al., KDD '09]

Insights I: real world events

Youtube video: <http://youtu.be/hBeaSfRCU4c>

Insights II: dynamic clusters

Youtube video: <http://youtu.be/hBeaSfRCU4c>

Cascades and network evolution

Recent empirical studies [Antoniades and Dovrolis, Myers & Leskovec] show that **cascades also change the structure of social networks:**

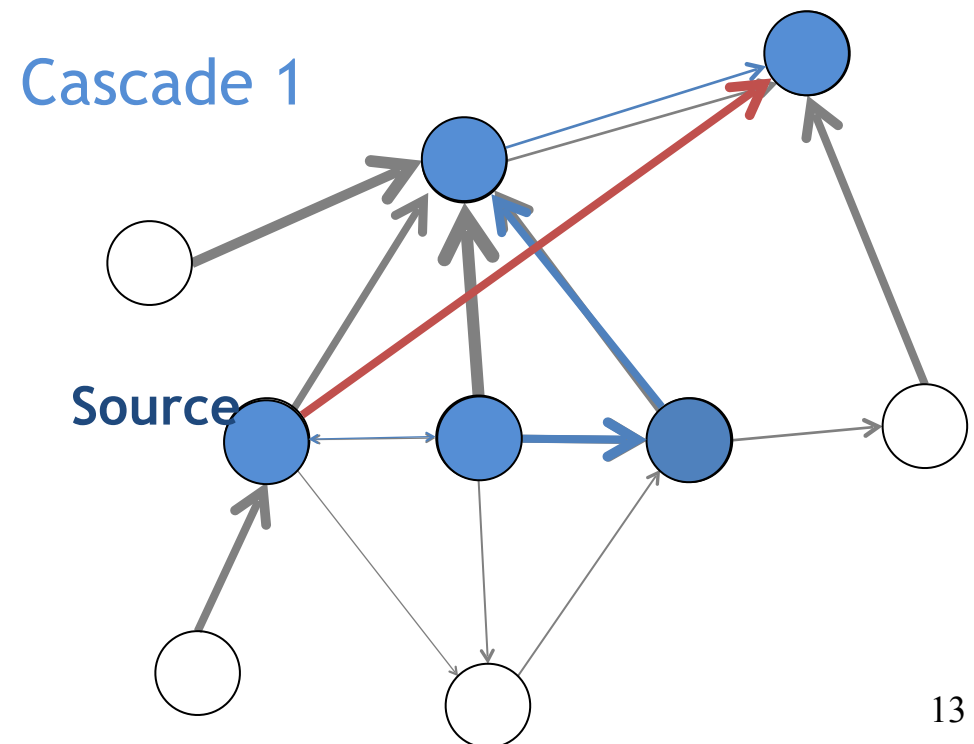
Information propagation triggers new links

Esteban Moro retweeted a Tweet you were mentioned in
Nov 17: Tuesday 18Nov at @uc3m: Manuel Gómez @autreche on "Shaping Social Activity by Incentivizing Users". If you're around. gts.tsc.uc3m.es/?p=1232



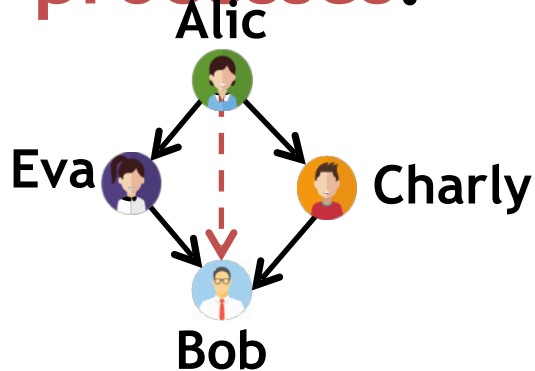
↓ 1 hour later

Data Beers and Edu López-Larraz followed you



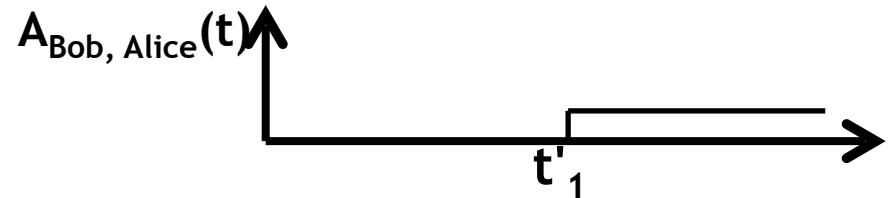
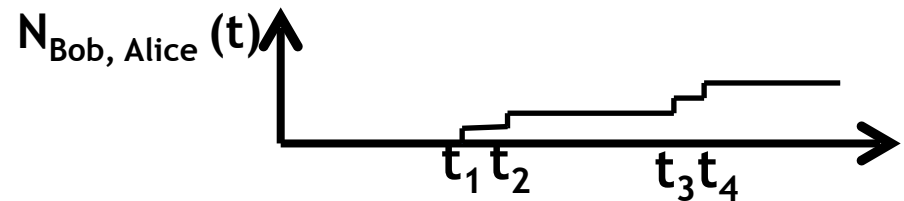
Co-evolution as interwoven point processes (I)

We model user's retweet and link events as nonterminating and terminating **counting processes**:



Bob *retweets* (is exposed to) Alice

Bob follows Alice



Key idea

Both counting processes have memory and depend on each other

Esteban Moro retweeted a Tweet you were mentioned in
Nov 17: Tuesday 18Nov at @uc3m: Manuel Gómez @autreche on "Shaping Social Activity by Incentivizing Users". If you're around. gts.tsc.uc3m.es/?p=1232



↓ 30 min later

Data Beers and Edu López-Larraz followed you



Co-evolution as interwoven point processes (II)

We characterize retweet and link counting processes using their respective **conditional intensities**:

Changes on retweets in $[t, t+dt]$

$$\mathbb{E}[dN(t) \mid \underbrace{\mathcal{H}^r(t) \cup \mathcal{H}^l(t)}_{\substack{\text{History of retweets} \\ \text{and links up to } t}}] = \underbrace{\Gamma^*(t)}_{\substack{\text{Instantaneous} \\ \text{rates or } \text{intensities}}} dt$$

$$\mathbb{E}[dA(t) \mid \underbrace{\mathcal{H}^r(t) \cup \mathcal{H}^l(t)}_{\substack{\text{History of retweets} \\ \text{and links up to } t}}] = \underbrace{\Lambda^*(t)}_{\substack{\text{Instantaneous} \\ \text{rates or } \text{intensities}}} dt$$

Changes on links in $[t, t+dt]$

They are coupled through the histories

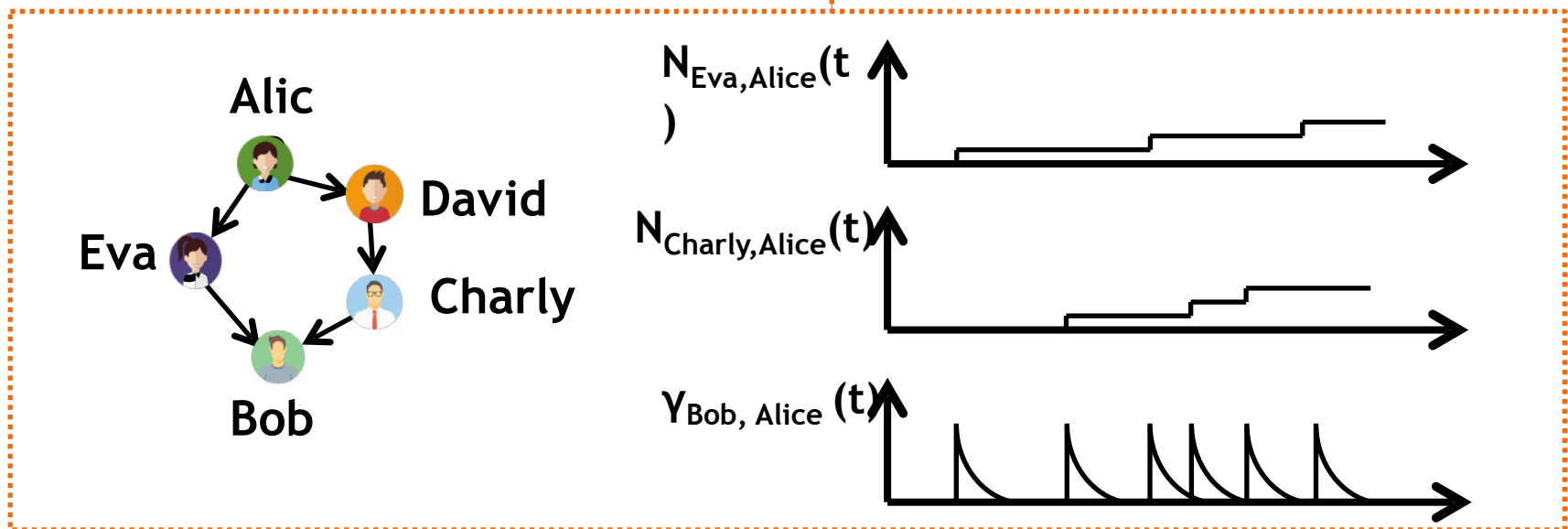
$$\mathcal{H}^r(t) \cup \mathcal{H}^l(t)$$

Intensity for information propagation

$$N_{us}(t) \leftrightarrow \gamma_{us}^*(t) = \begin{cases} \eta_u & \text{Tweets on her own initiative} & u = s \\ \beta_s \sum_{v \in \mathcal{F}_u(t)} \kappa_{\omega_1}(t) \star (A_{uv}(t) dN_{vs}(t)) & \text{Time-varying network topology} & u \neq s \end{cases}$$

Node u does not need to follow s!

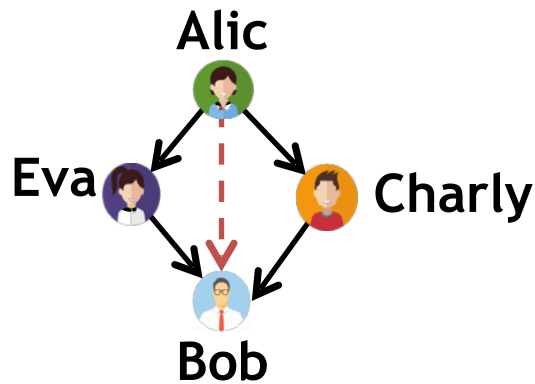
Propagation of peer influence over the network



Intensity for network evolution

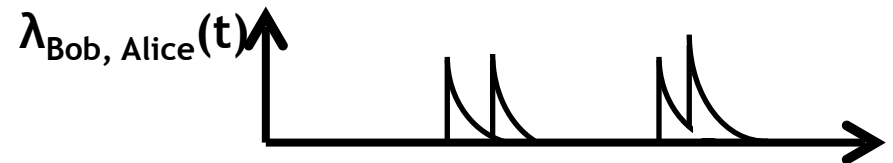
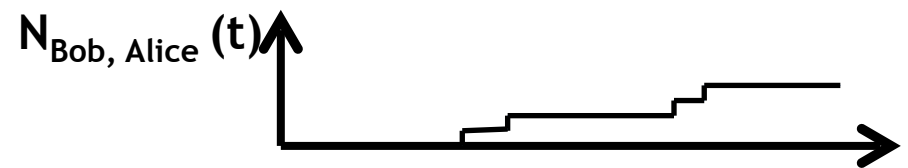
$$\lambda_{us}^*(t) = (1 - A_{us}(t)) (\underbrace{\mu_u}_{\text{Ensures a link is created only once}} + \underbrace{\alpha_u \kappa_{\omega_2}(t)}_{\text{Influence of retweet intensity on the link creation}} \star \underbrace{dN_{us}(t)}_{\text{Links on her own initiative}})$$

\updownarrow
 $A_{us}(t)$



Bob *retweets* (is exposed to) Alice

Bob's *risk* of following Alice



Model inference from historical data

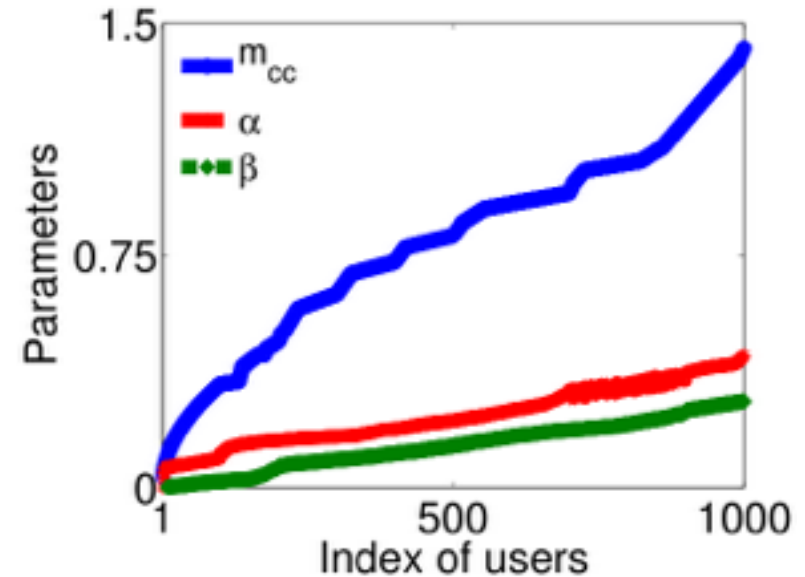
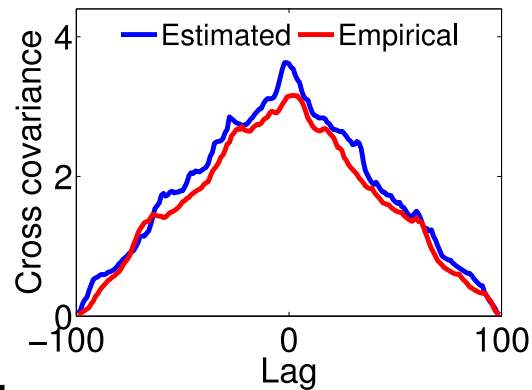
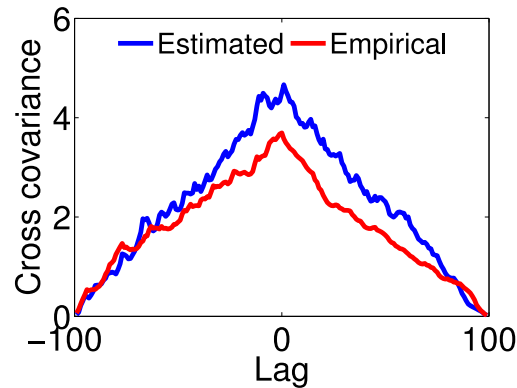
Find *optimal* parameters using maximum likelihood estimation (MLE):

$$\begin{aligned} \mathcal{L}(\{\mu_u\}, \{\alpha_u\}, \{\eta_u\}, \{\beta_s\}) = & \underbrace{\sum_{e_i^r \in \mathcal{E}} \log(\gamma_{u_i s_i}^*(t_i)) - \sum_{u, s \in [m]} \int_0^T \gamma_{us}^*(\tau) d\tau}_{\text{tweet / retweet}} + \\ & \underbrace{\sum_{e_i^l \in \mathcal{A}} \log(\lambda_{u_i s_i}^*(t_i)) - \sum_{u, s \in [m]} \int_0^T \lambda_{us}^*(\tau) d\tau}_{\text{links}} \end{aligned}$$

For the choice of information propagation and link intensities, the MLE problem above is **parallelizable & convex**.

Retweet and link coevolution

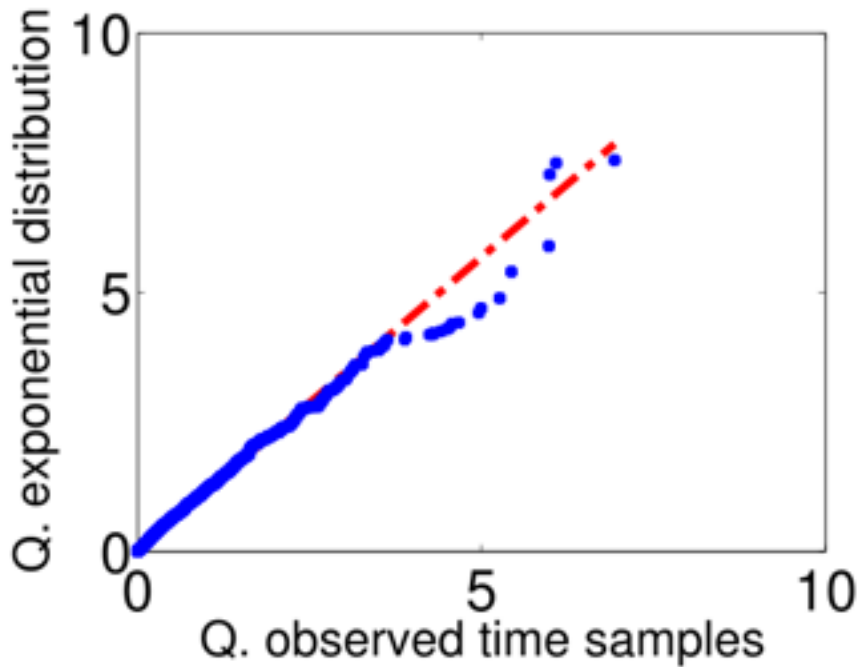
Cross-covariance
for two users



Average cross-covariance
vs model parameters

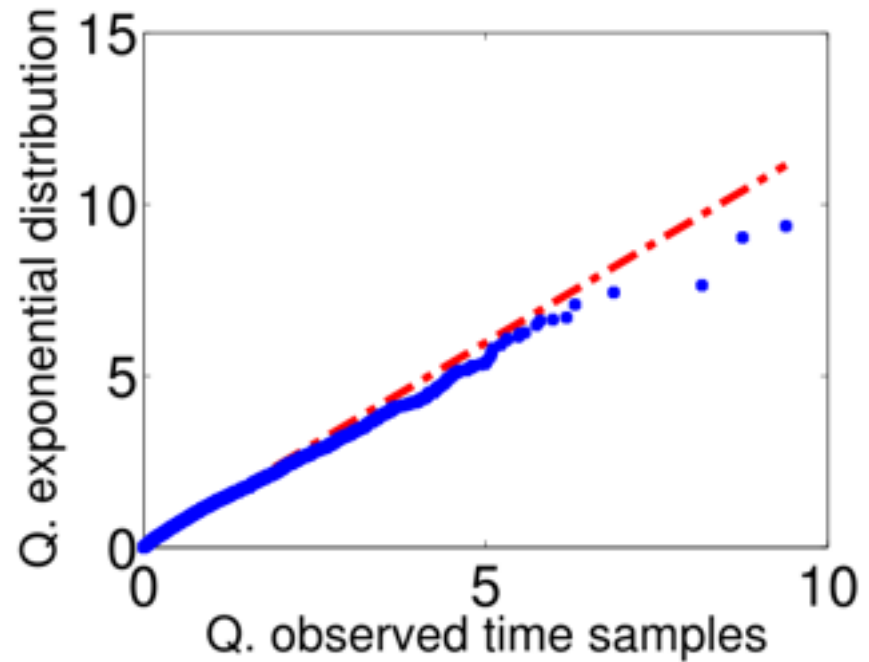
The fitted model generate link and information diffusion events that coevolve similarly (in terms of cross-covariance) as real events.

Model checking



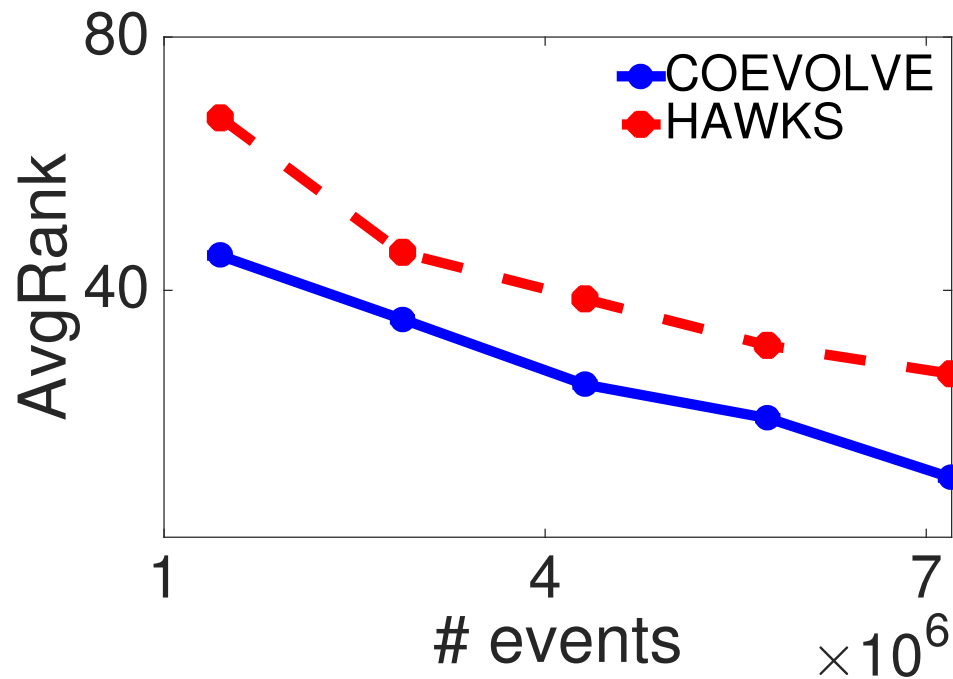
Link events

The quantiles of the intensity integ $\int_{t_i}^{t_{i+1}} \lambda(t) dt$ computed using the fitted intensities match the quantiles of the unit-rate exponential distribution

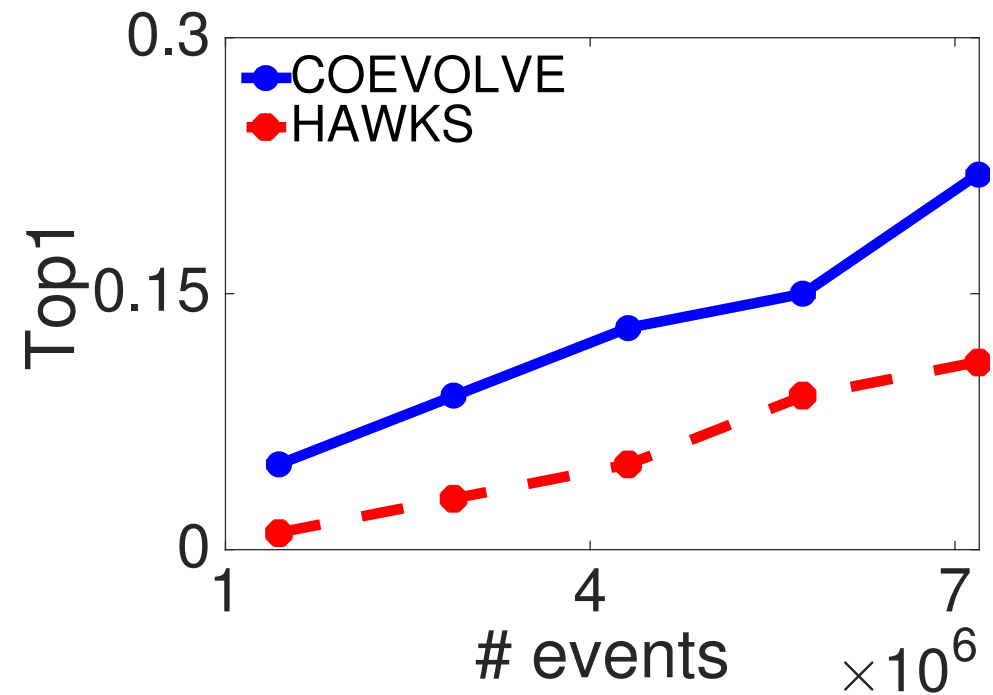


Retweet events

Information diffusion prediction



**Average
rank**



**Success
probability**

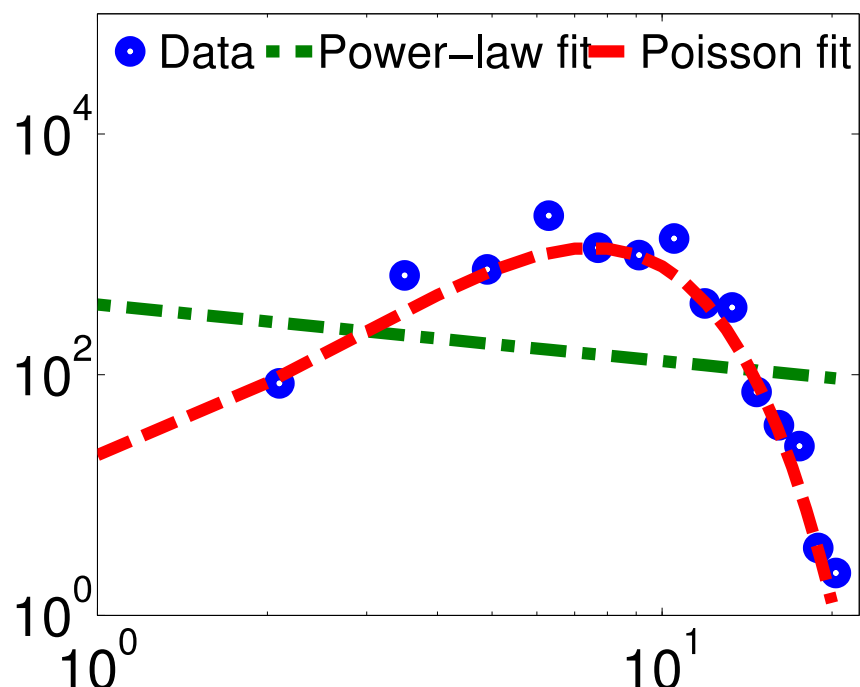
The model beats the predictions given by a standard Hawkes process

Network properties & cascade patterns

Can the model generate realistic macroscopic static and temporal network patterns and information cascades?

Network	Cascade
Degree distributions	Cascade size distribution
Network diameter	Cascade depth distribution
Level of triadic closure	Cascade structure

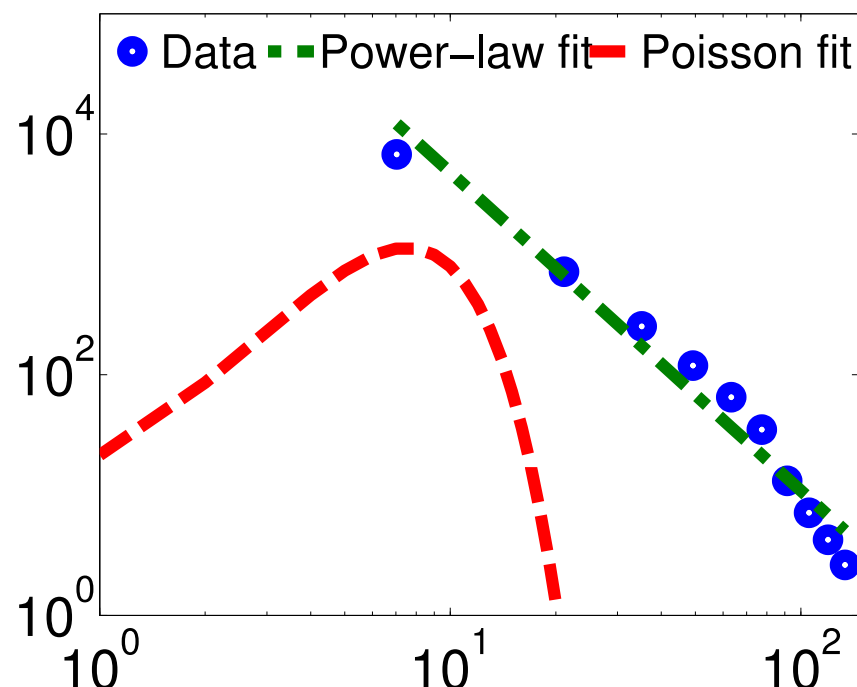
Degree distributions



Poisson, $\alpha =$

0

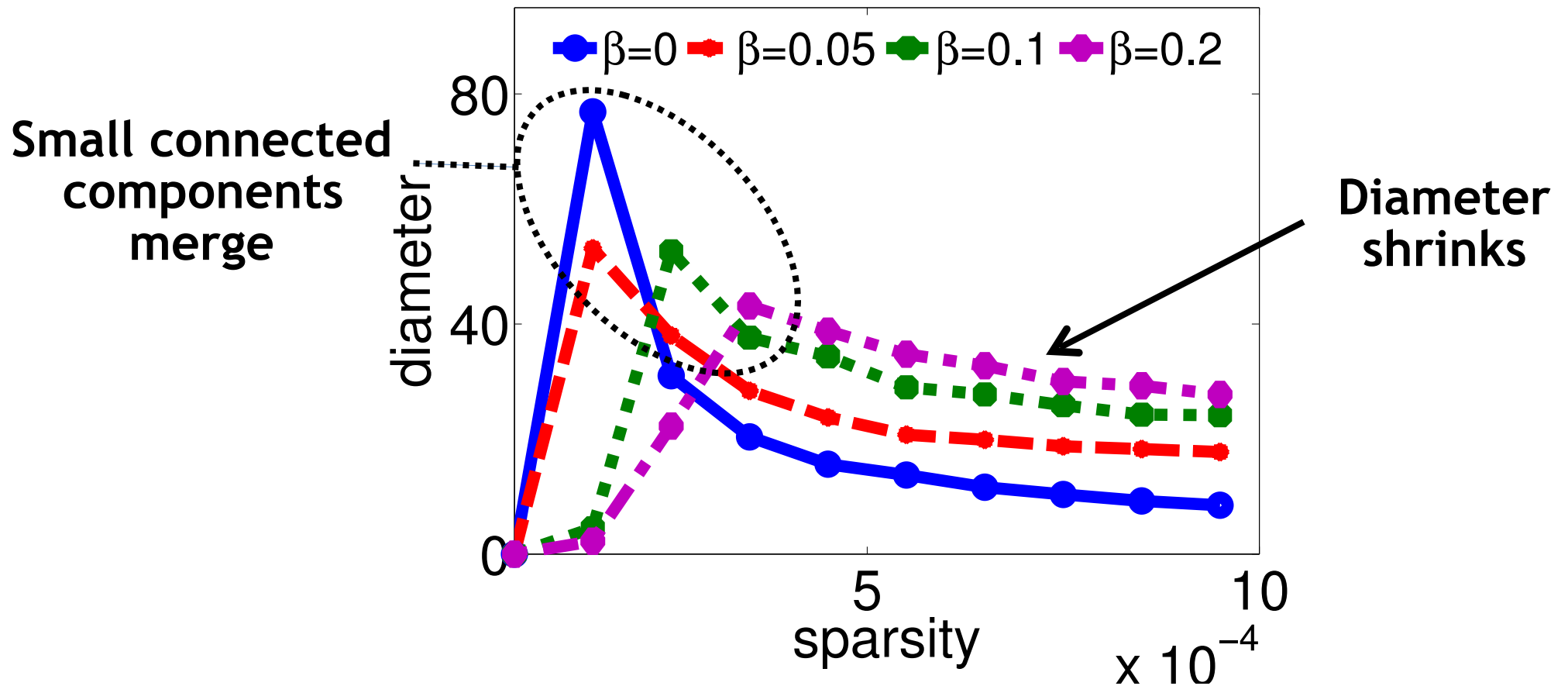
The higher the parameter α (or β), the closer the degree distribution is to a power-law



Power-law, $\alpha =$

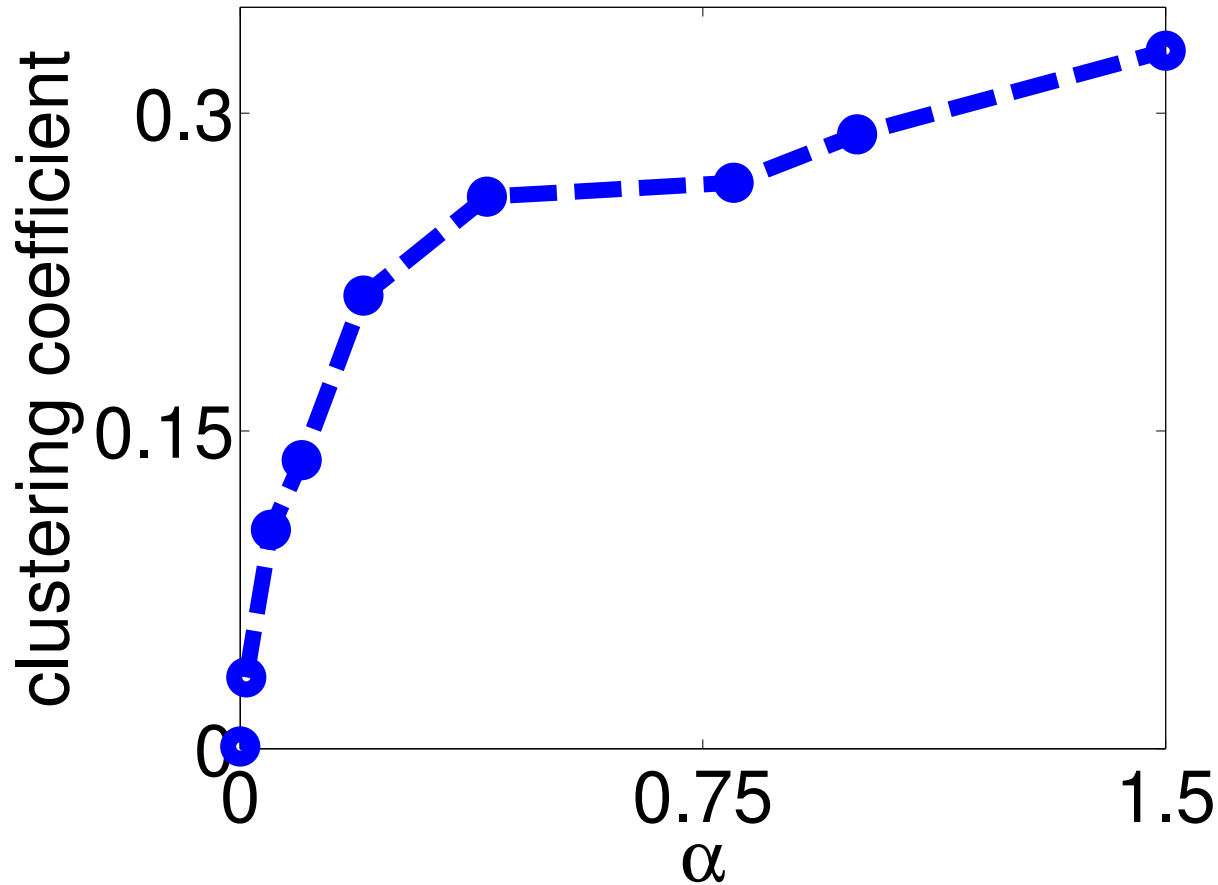
0.2

Small (shrinking) diameters



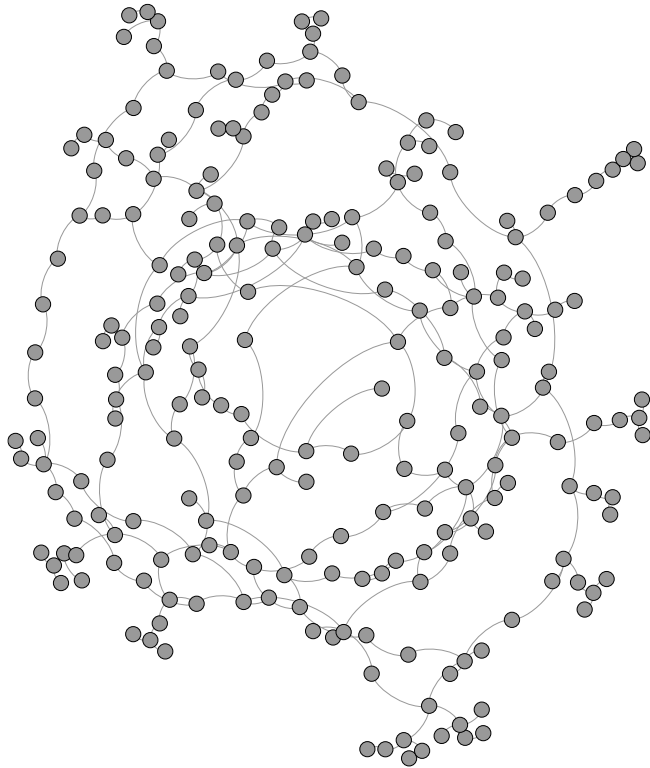
Our model generate networks with **small shrinking (or flattening) diameter over time**, as observed empirically.

Clustering coefficient



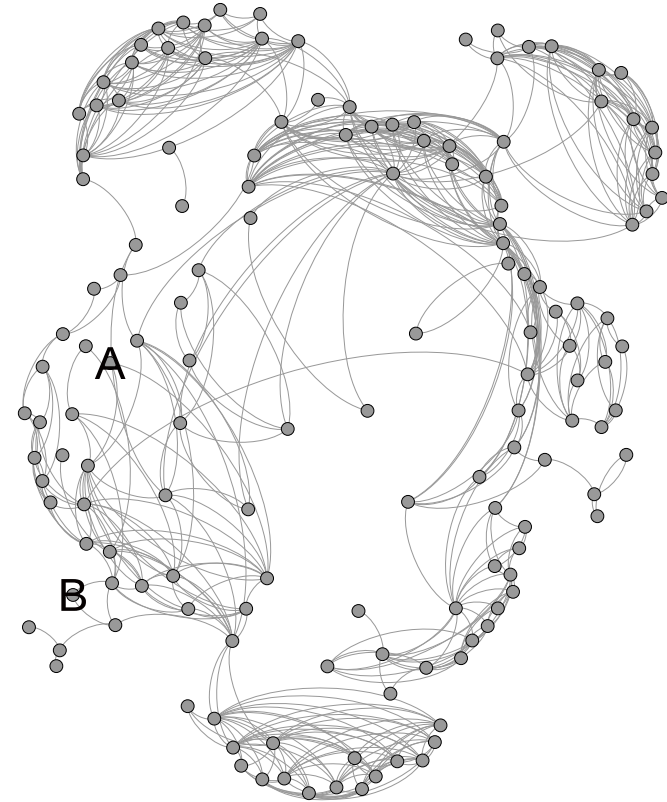
We can generate networks with **different levels of triadic closure**, as observed empirically

Different type of networks



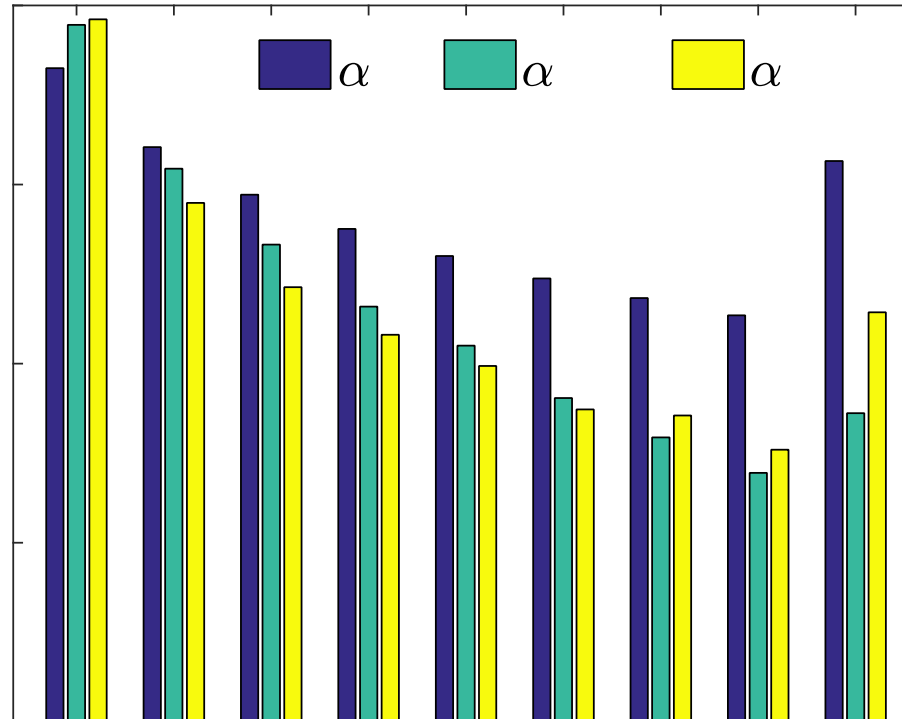
**Erdos-Renyi, β
= 0**

**Our model allows us to generate networks
with very different structure**



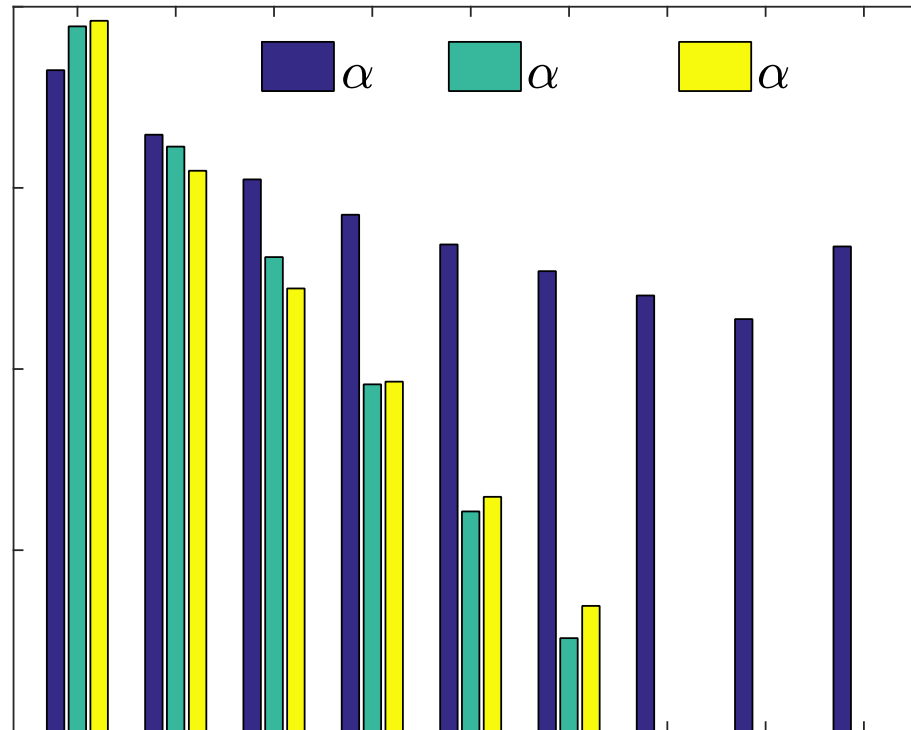
**Scale-free network, $\beta =$
0.8**

Cascade patterns: size



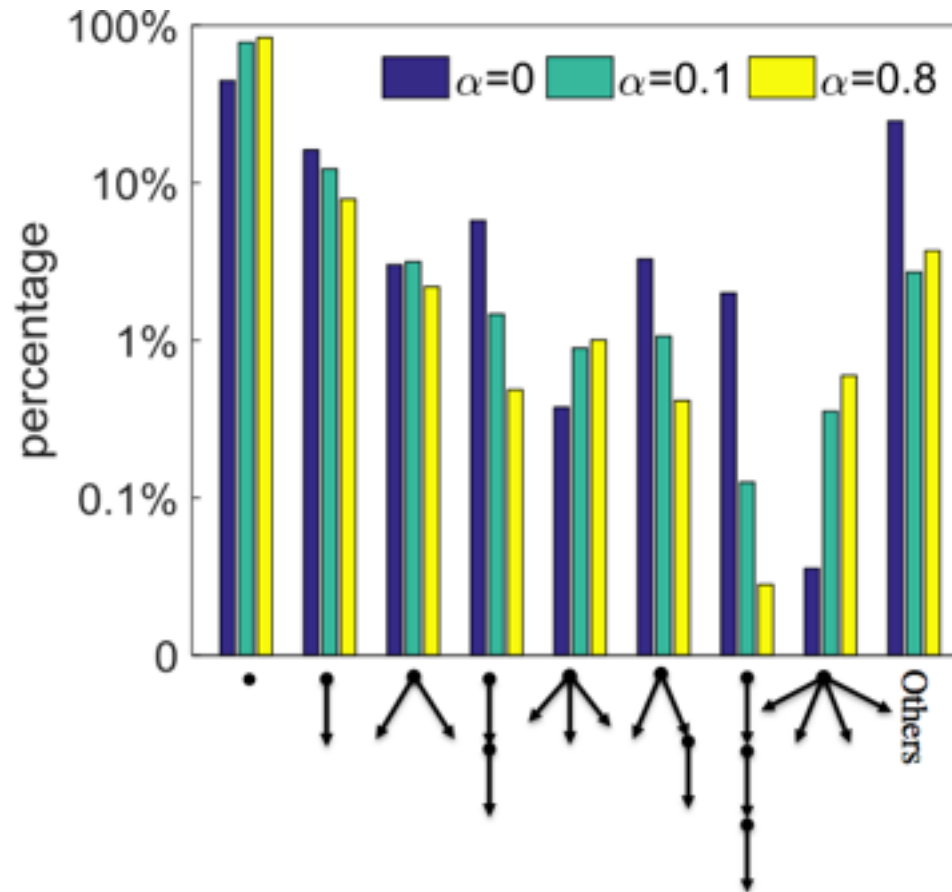
As α (or β) increases, longer cascades become more seldom.

Cascade patterns: depth



As α (or β) increases, **deeper cascades are more seldom**, as observed in real cascade data.

Cascade patterns: structure



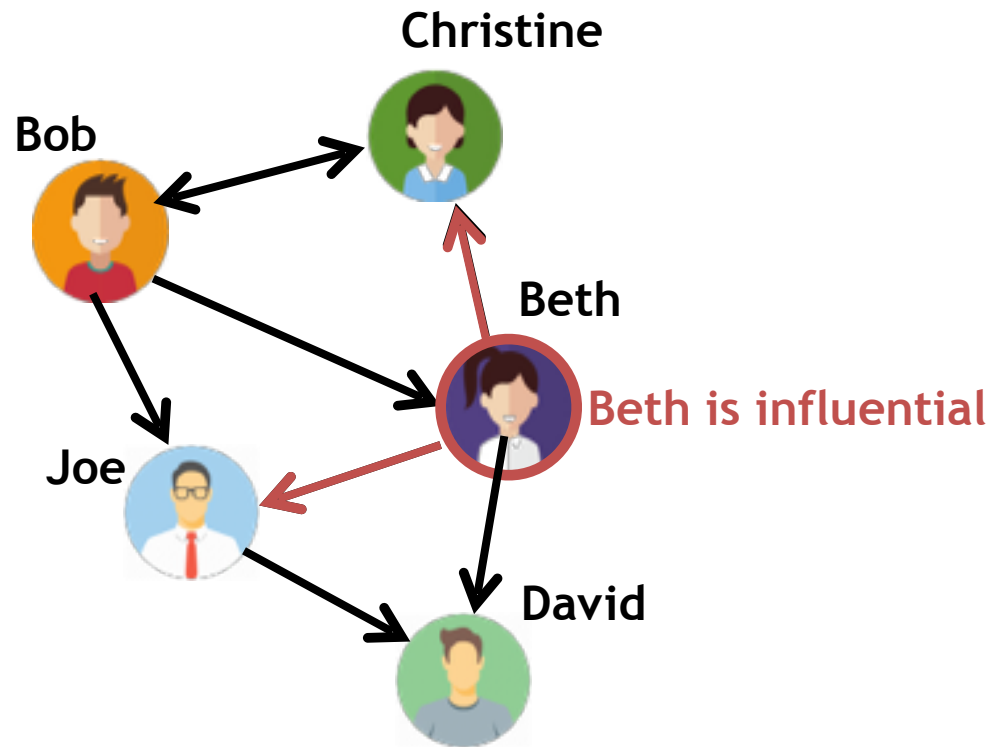
The structure of the generated cascades becomes *more realistic* as α (or β) increases.

Applications: Models

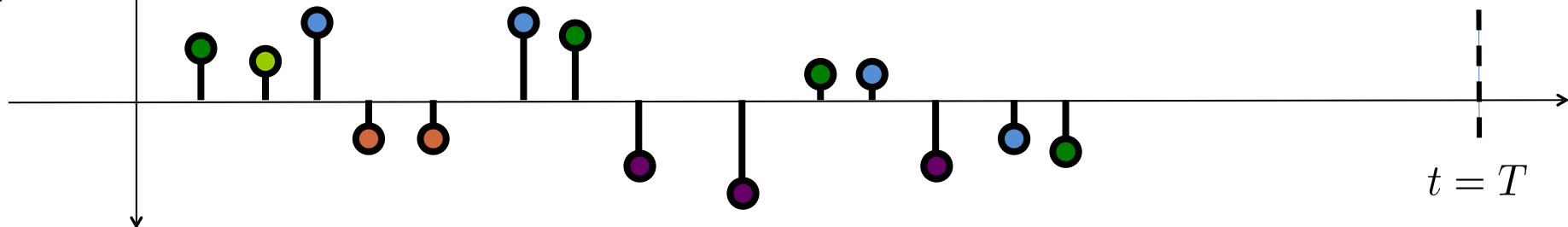
1. Information propagation
- 2. Opinion dynamics**
3. Information reliability
4. Knowledge acquisition

Opinion dynamics: an example

$S \rightarrow D$
means
D follows S

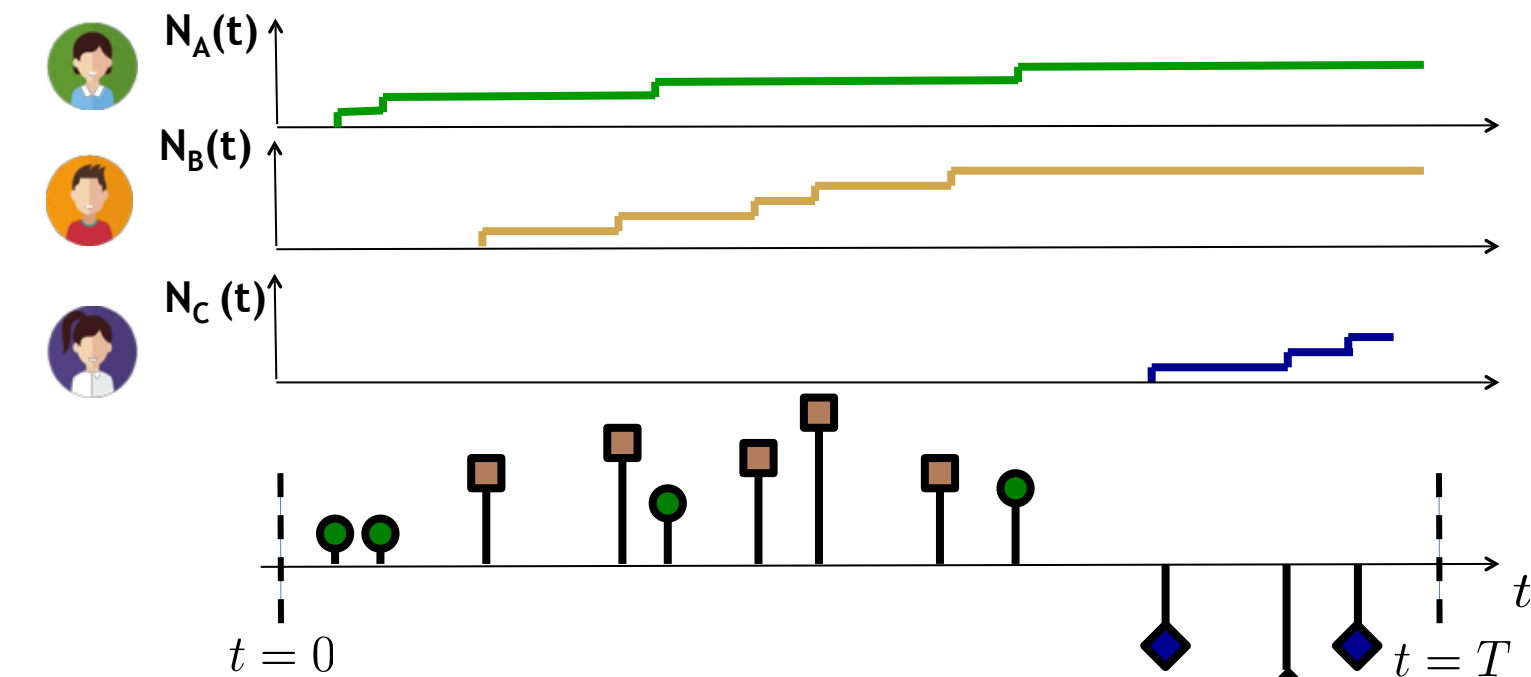


Expressed
opinions



Message representation

We represent messages using marked temporal point processes:

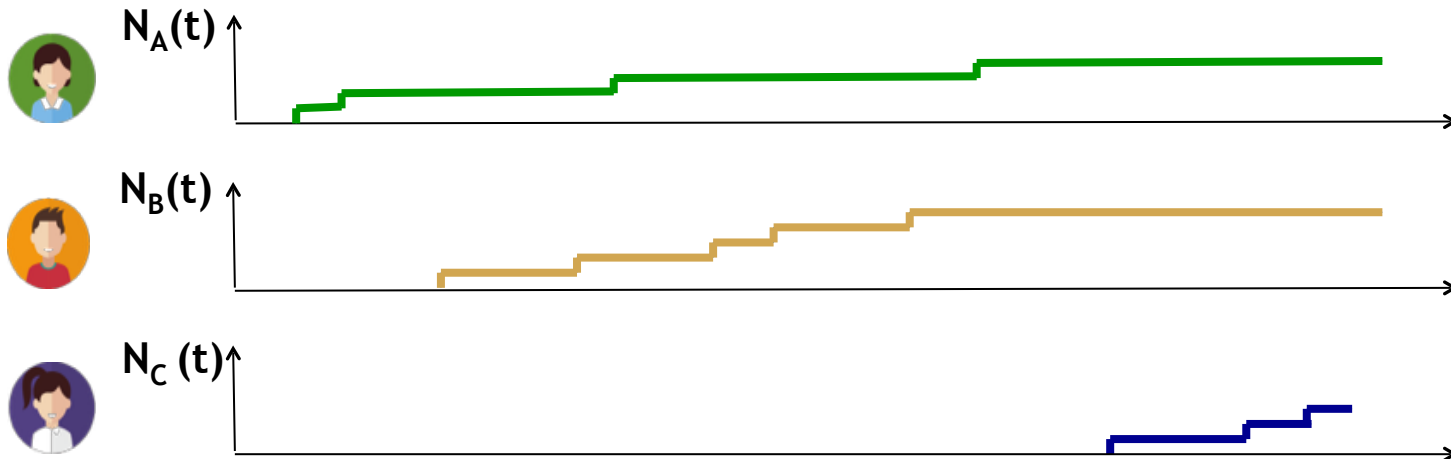


Message: (u_i, m_i, t_i)

User \swarrow
Sentiment \downarrow
(mark) \searrow Time

Noisy observation of latent opinion

Message intensity



$$\underbrace{\lambda_u^*(t)}_{\text{User's intensity}} = \underbrace{\mu_u}_{\text{Messages on her own initiative}} + \sum_{v \in u \cup \mathcal{N}(u)} b_{vu} \underbrace{\sum_{e_i \in \mathcal{H}_v(t)} \kappa(t - t_i)}_{\text{Previous messages by user } v}$$

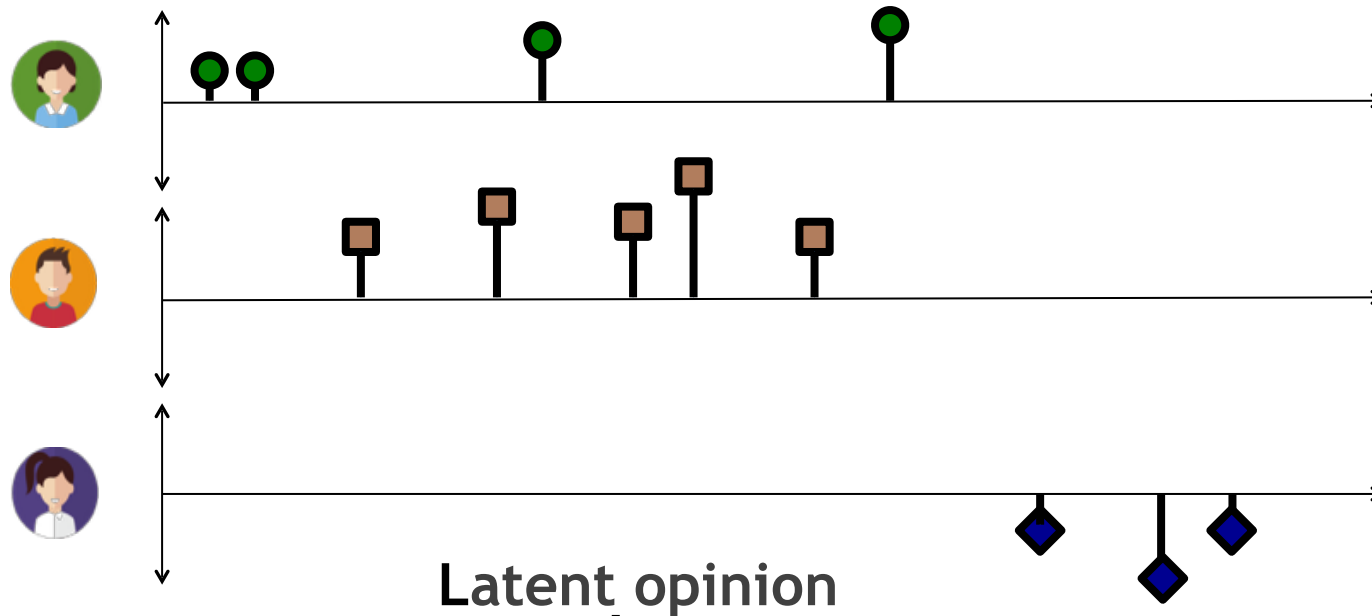
} **process** } **Hawkes**

Memory

33

[De et al., NIPS 2016]

Sentiment distribution



Sentiment: $m_u \sim p(m|x_u^*(t))$

It depends on
the
recorded data

Continuous (based on sentiment analysis):
 $p(m|x_u^*(t)) = \mathcal{N}(x_u(t), \sigma_u)$

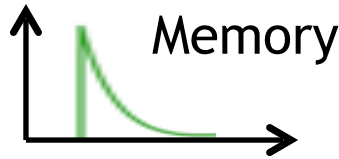
Discrete (based on upvotes/

$p(m|x_u^*(t)) = 1/(1 + \exp(-m \cdot x_u(t)))$

Stochastic process for (latent) opinions

$$\underbrace{x_u^*(t)}_{\text{User's latent opinion}} = \underbrace{\alpha_u}_{\text{User's initial opinion}} + \sum_{v \in \mathcal{N}(u)} a_{vu} \underbrace{\sum_{e_i \in \mathcal{H}_v(t)} m_i g(t - t_i)}_{\text{Previous sentiment by user v}}$$

influence from user v on user u



Opinion model as Jump SDEs

Proposition. The tuple $(\mathbf{x}^*(t), \lambda^*(t), \mathbf{N}(t))$ is a Markov process, whose dynamics are defined by the following marked jumped stochastic differential equations (SDEs)

Latent opinions
↓

Informational influence
↓

Expressed opinions
↙

$$d\mathbf{x}^*(t) = \omega(\boldsymbol{\alpha} - \mathbf{x}^*(t))dt + \mathbf{A}(\mathbf{m}(t) \odot d\mathbf{N}(t))$$
$$d\lambda^*(t) = \nu(\mu - \lambda^*(t))dt + \mathbf{B} d\mathbf{N}(t)$$

Message intensities
↑

Temporal influence
↑

Network!

Network!

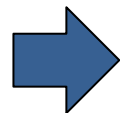
Model inference from opinion data

**Events
likelihood**

$$\underbrace{\sum_{e_i \in \mathcal{H}(T)} \log p(m_i | x_{u_i}^*(t_i))}_{\text{Message sentiments (marks)}} + \underbrace{\sum_{e_i \in \mathcal{H}(T)} \log \lambda_{u_i}^*(t_i) - \sum_{u \in \mathcal{V}} \int_0^T \lambda_u^*(\tau) d\tau}_{\text{Message times}}$$

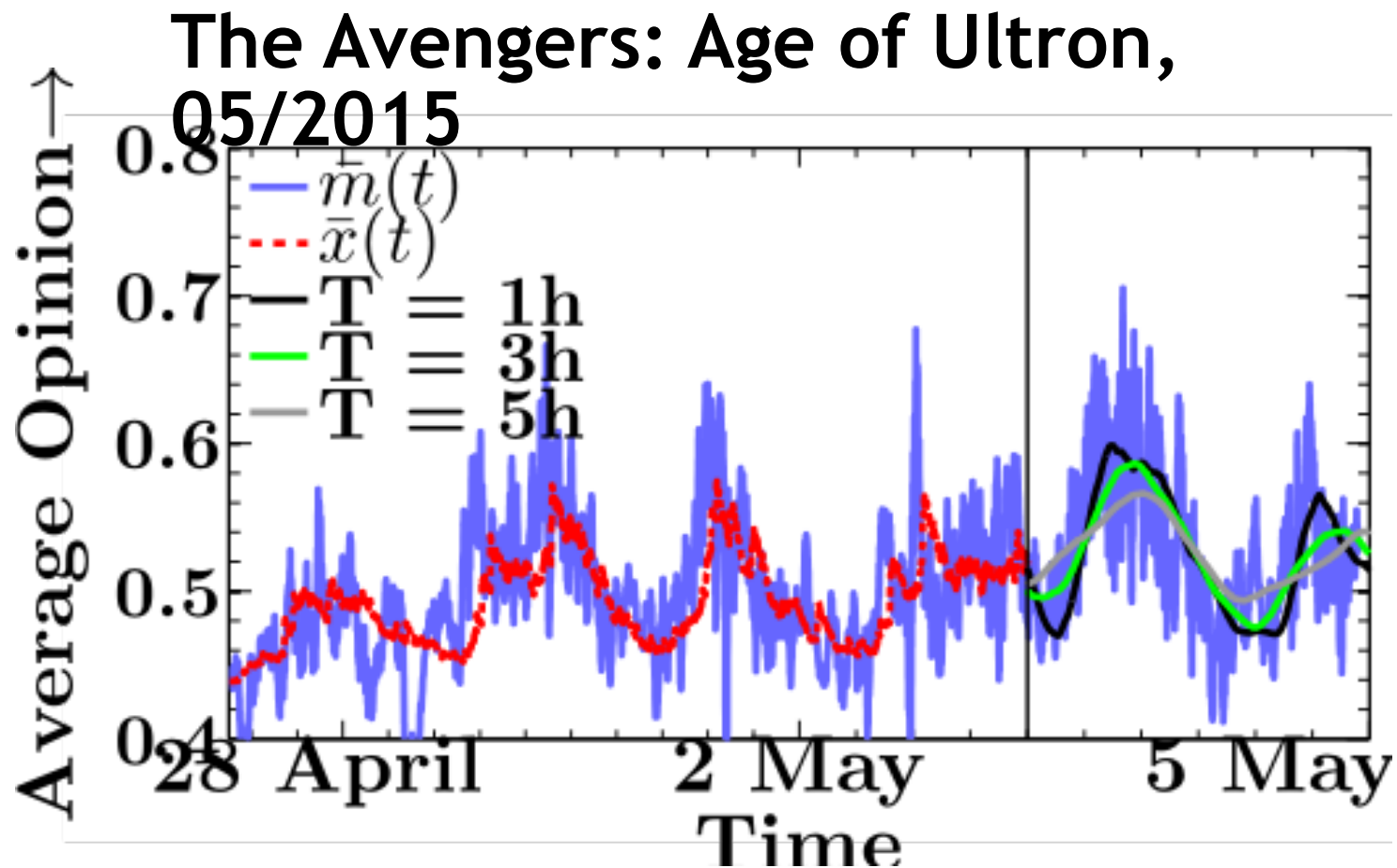
Theorem. The maximum likelihood problem is convex in the model parameters.

Markov
property



Sums and
integrals
in linear time!

Opinion forecasting



The forecasted opinion becomes less accurate as T increases, as one may expect.

Applications: Models

1. Information propagation
2. Opinion dynamics
- 3. Information reliability**
4. Knowledge acquisition

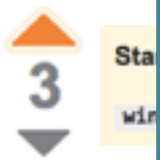
Information reliability: an example

Learning from the crowd ('crowdlearning') has become very popular:

Users learn from the

Knowledge is reviewed

Refutations and verifications depend on the source trustworthiness



Barack Obama

From Wikipedia, the free encyclopedia

"Barack" and "Obama" redirect here. For his father, see Barack Obama Sr. For other uses of "Barack", see Barack (disambiguation). (disambiguation).

Barack Hussein Obama II (/ˈbərəkˈhuːseɪnˈoʊbɑːmɑː/ born August 4, 1961) is an American politician who is the 44th and current President of the United States. He is the first African continental United States. Born in Honolulu, Hawaii, Obama was president of the *Harvard Law Review*. He was a civil rights attorney and taught constitutional law at the University of Chicago. He represented the 13th District in the Illinois Senate from 2005 to 2008 and the United States House of Representatives in 2009 against incumbent Barack Obama.

Barack Obama: Revision history

03:41, 28 November 2016	Ranze (talk contribs) .. (301,105 bytes) (+18) .. (E
03:32, 28 November 2016	Xin Deui (talk contribs) .. (301,087 bytes) (-68) .. (
00:57, 28 November 2016	SponkBot (talk contribs) at .. (301,155 bytes) (-37)
07:03, 27 November 2016	Saiph121 (talk contribs) .. (301,192 bytes) (+25) ..

03:21, 20 September 2016

is a Kenyan politician



possible vandalism by MLM2016

is an American politician

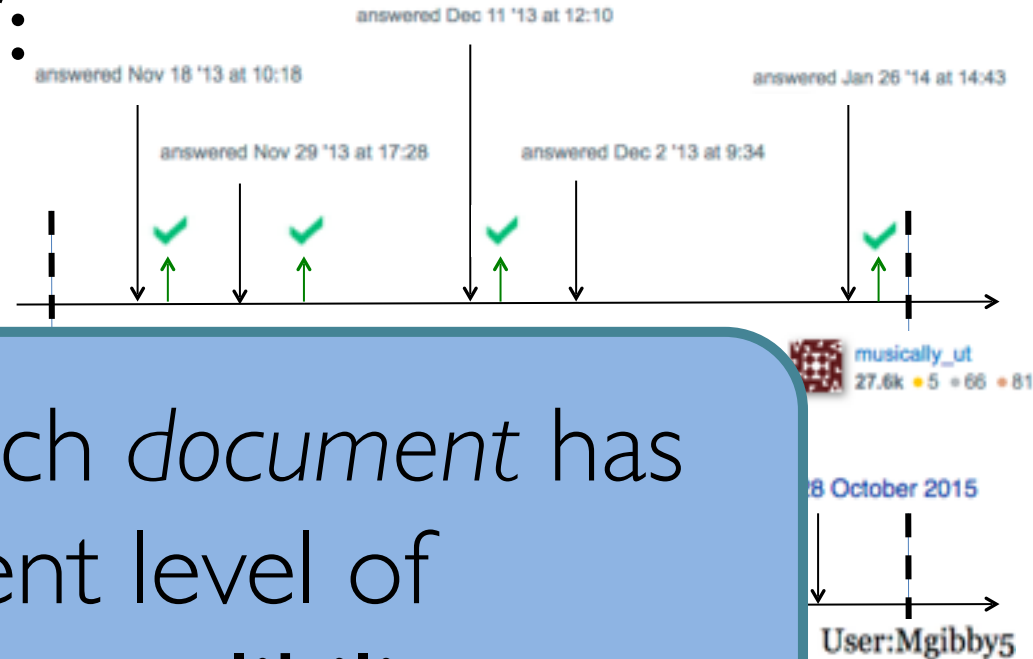
Information reliability: key, simple idea

A source is trustworthy if:

Its contributions are
verified more

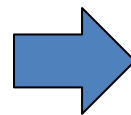
Its c
refu

Over time, each *document* has
a different level of
inherent unreliability



Challenge

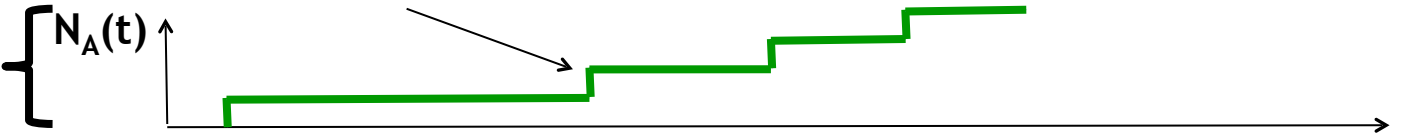
At a time t , a
document may be
disputed



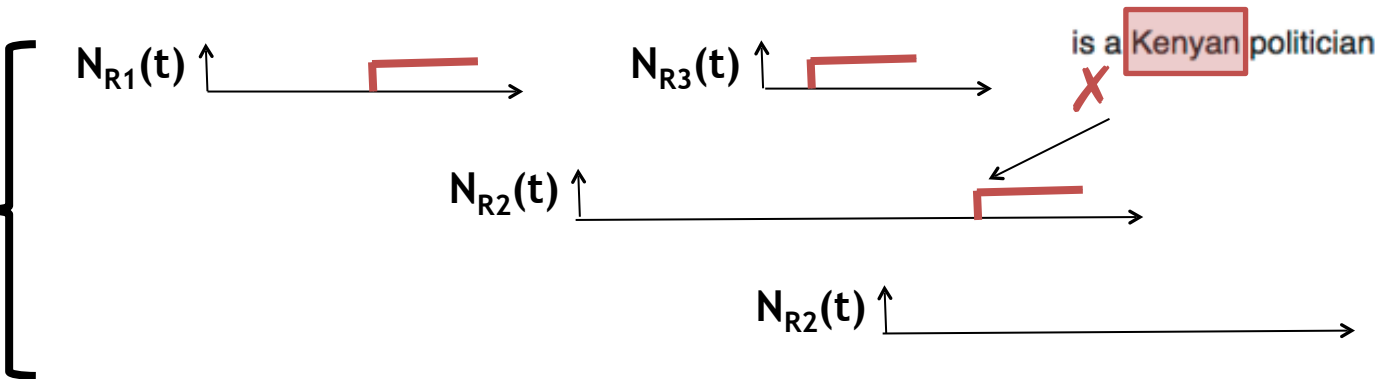
Verifications: rarer
Refutations: more
frequent

Representation: temporal point processes

Statement additions
(one process per document)



Statement refutations
(one process per statement)



Barack Obama

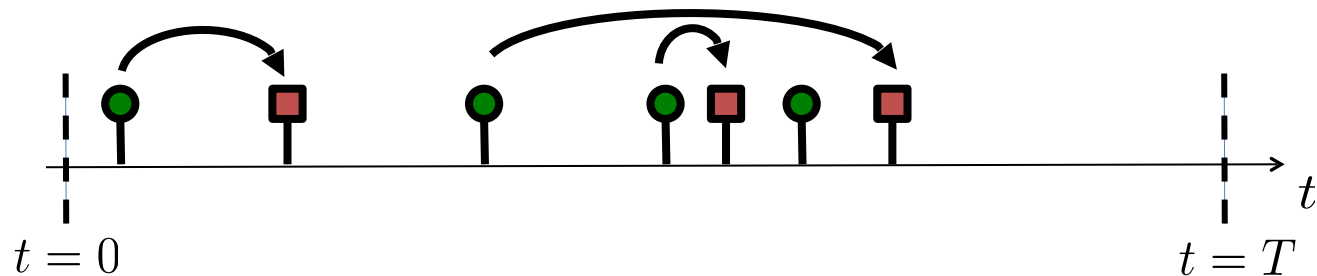
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Barack Hussein Obama II (current President of the United States; Bar was president of the Harvard civil rights attorney and taught representing the 13th District States House of Representat

Barack Obama: Revision history

03:41, 28 November 2016	Ranize (talk contribs)	.. (301,105 bytes) (+18) .. (E
03:32, 28 November 2016	Xin Deui (talk contribs)	.. (301,087 bytes) (-68) .. (E
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07:03, 27 November 2016	Saiph121 (talk contribs)	.. (301,192 bytes) (+25) ..



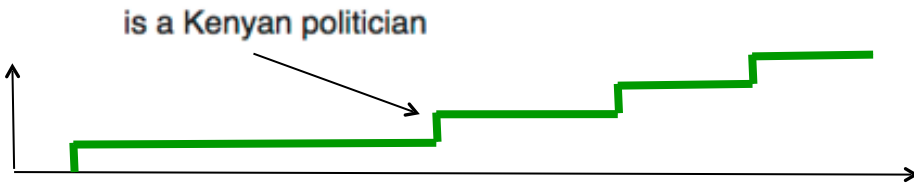
Statement: $e = (s, t, \tau)$

source \downarrow s refutation time \downarrow t

addition time \uparrow τ

Intensity of statement additions

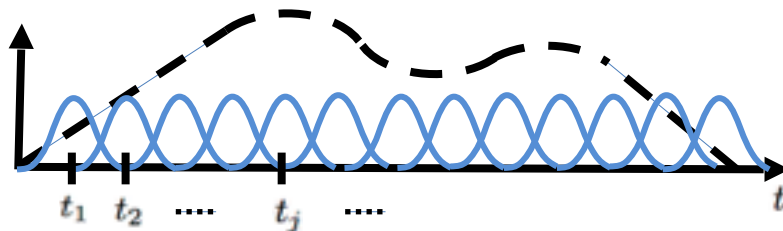
Statement additions
(one process per article) $\left\{ N_A(t) \right\}$



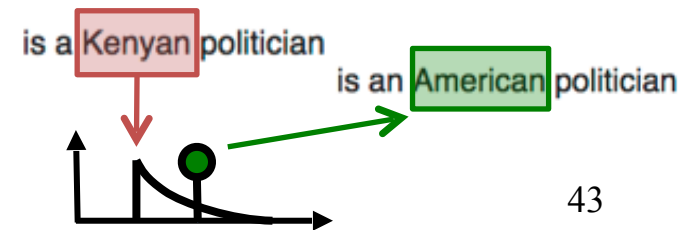
$$\lambda_d(t) = \underbrace{\sum_j \phi_{d,j} k(t - t_j)}_{\text{Article unreliability}} + \underbrace{\sum_{e_i \in \mathcal{H}_d(t)} \mathbf{w}_d^\top \gamma_{s_i} g(t - \tau_i)}_{\text{Effect of past refutations}}$$

Intensity or rate (Statements per time unit) Article unreliability (Mixture of Gaussians) Effect of past refutations (topic dependent; topic weight w_d)

Temporal evolution of the *intrinsic* reliability of the article



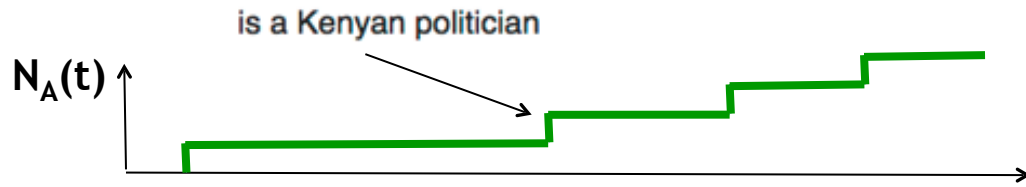
Refuted statements trigger the arrival of new statements to replace them



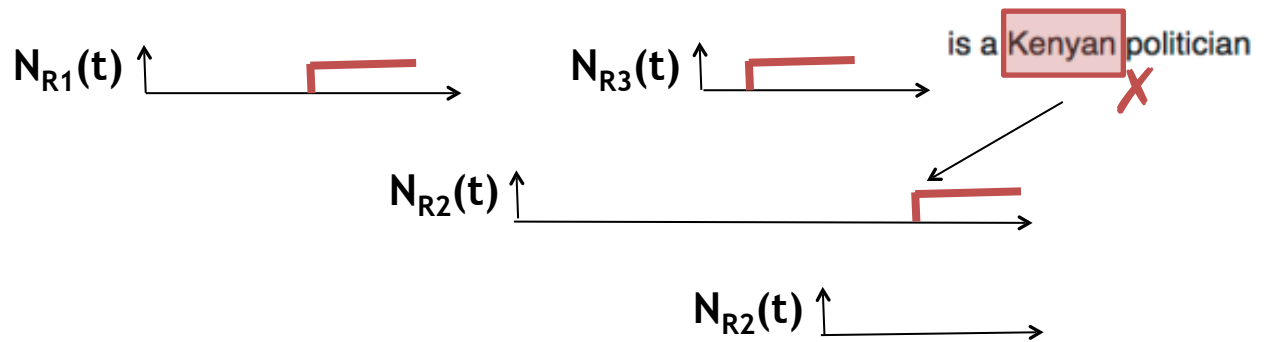
[Tabibian et al., WWW 2017]

Intensity of statement refutations

Statement additions
(one process per article)



Statement refutations
(one process per statement)



$$\mu_i(t) = (1 - N_i(t)) \left[\sum_j \beta_{d,j} k(t + t_i - t_j) + \mathbf{w}_d^\top \boldsymbol{\alpha}_{s_i} \right]$$

Refutations happen only once

Article unreliability
(Mixture of Gaussians)

Source trustworthiness
(topic dependent; topic weight w_d)

Intensity or rate
(Statements per time unit)

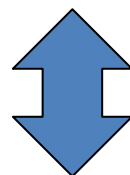
Shared across statements of an article!

The higher the parameter α_{s_i} , the quicker an article gets refuted

Model inference from event data

Conditional intensities

$$\{\lambda_d(t)\} \quad \{\mu_i(t)\}$$

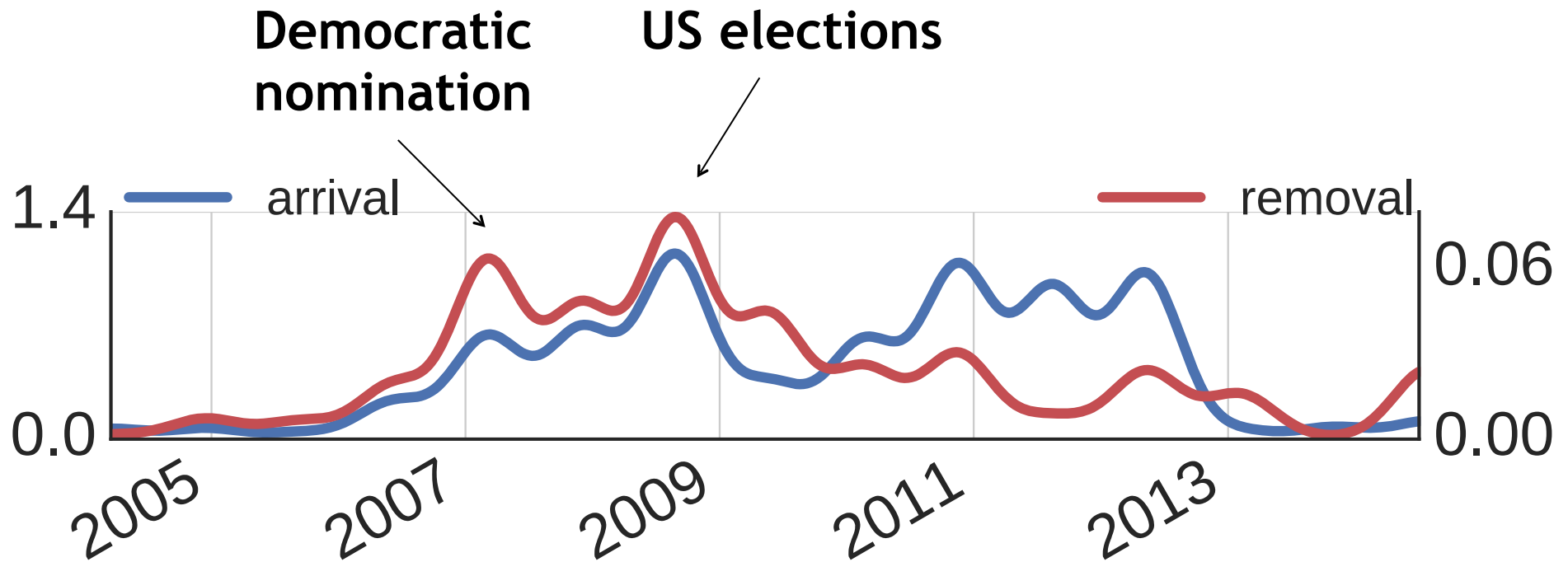


Events

$$\sum_{d=1}^{|\mathcal{D}|} \sum_{i:e_i \in \mathcal{H}_d(T)} \underbrace{\log p(t_i | \mathcal{H}_d(t_i), \phi_d, \{\gamma_s\}, \mathbf{w}_d)}_{\text{statements additions}} + \sum_{d=1}^{|\mathcal{D}|} \sum_{i:e_i \in \mathcal{H}_d(T)} \underbrace{\log p(\Delta_i | t_i, \beta_d, \{\alpha_s\}, \mathbf{w}_d)}_{\text{statements evaluations}}$$

Theorem. The maximum likelihood problem is convex in the model parameters.

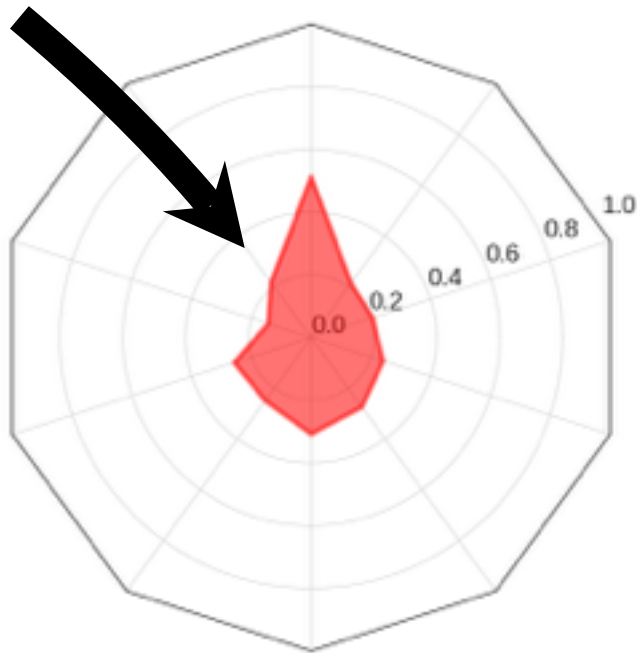
Wikipedia article reliability



**Barack Obama's Wikipedia Article
(Arrival of information vs intrinsic unreliability)**

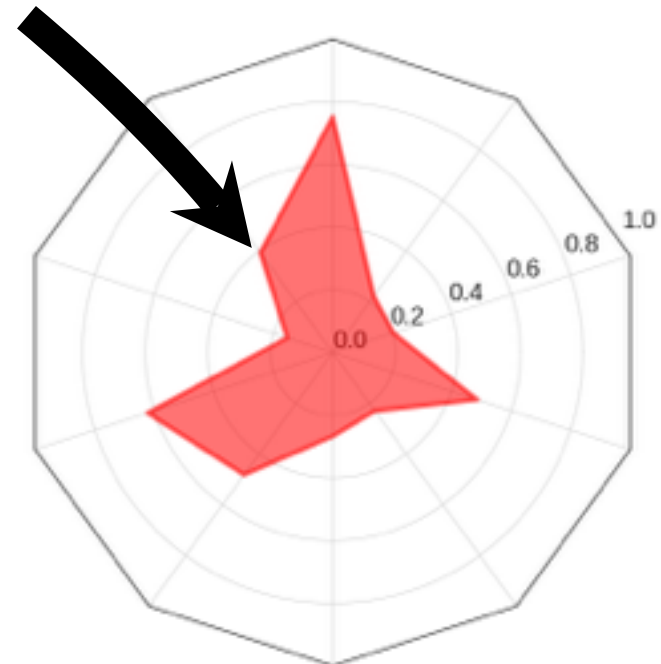
Source trustworthiness

Politics



bbc.co.uk

Politics



breitbart.com

Probability of refutation within 6 months
in a *stable* Wikipedia article

Applications: Models

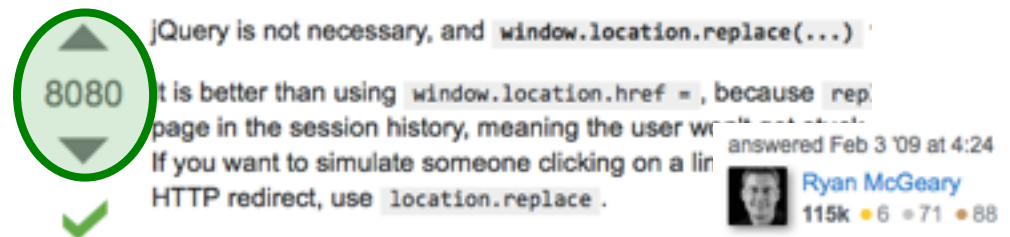
1. Information propagation
2. Opinion dynamics
3. Information reliability
- 4. Knowledge acquisition**

Crowdlearning: Learning from the crowd

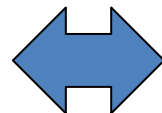
Learning from the crowd ('crowdlearning') has become very popular in the Web and social media



COMMON FUNCTIONALITY:



Users learn from the knowledge other users contribute



Knowledge is reviewed by users using assessment measures such as **upvotes or likes**

Our Goal: Uncover Learning and Knowledge

Can we design a data-driven model of crowdlearning?

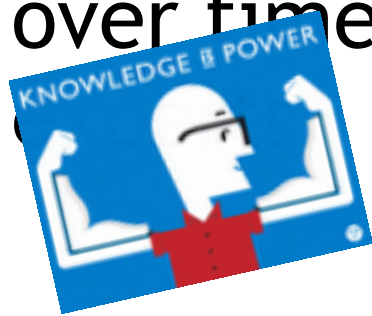


Why this goal?

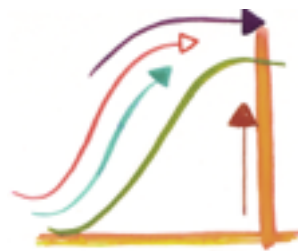
Understand how people learn

over time and become

Identify questions and answers with high knowledge value



Key Idea



upvotes from users



jQuery is not necessary, and `window.location.replace(...)` is better than using `window.location.href =`, because `replace` does not add a new page in the session history, meaning the user won't get stuck. If you want to simulate someone clicking on a link, use `location.href`. For an HTTP redirect, use `location.replace`.

Every time a **user learns** from a **contribution** by other users

She may increase her **expertise**

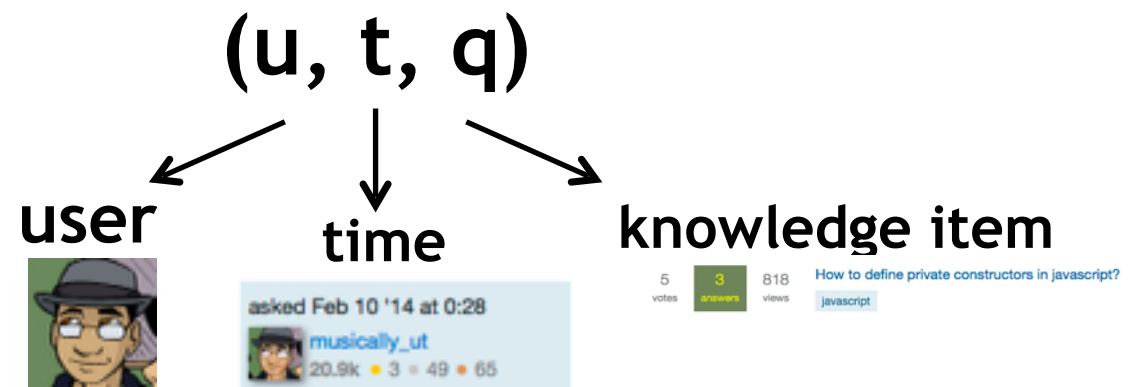
Her **contributions** become **more knowledgeable** and **assessed more highly**

Learning and contributing events

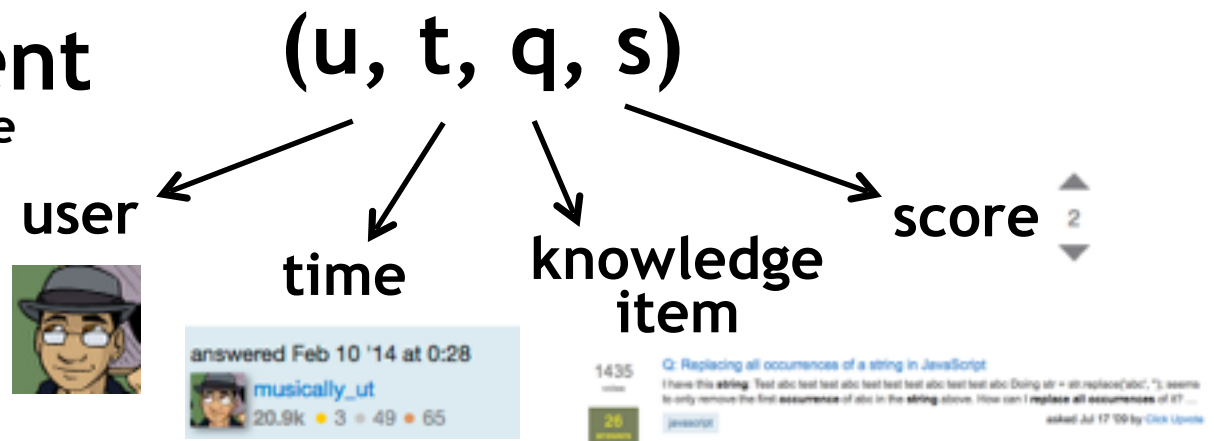
A knowledge item
(smallest quantum of knowledge)



A learning event
(user learns from a knowledge item)



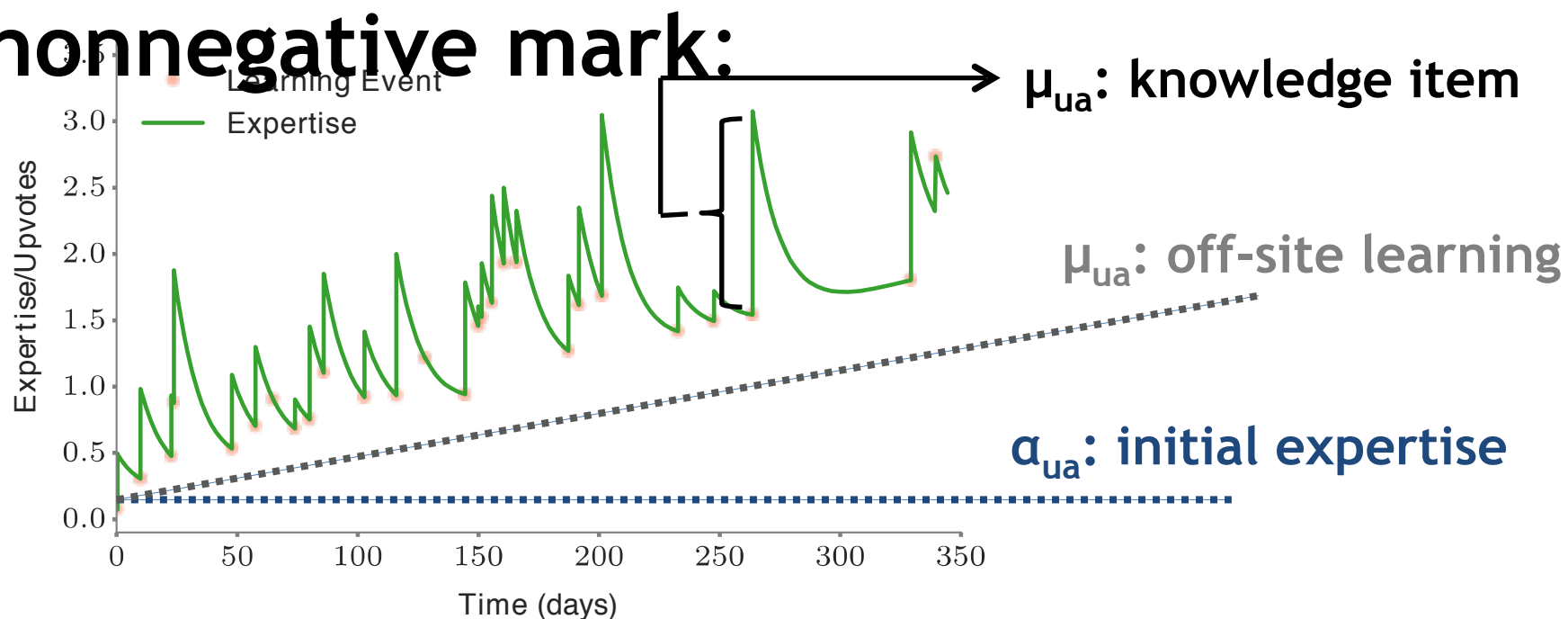
A contributing event
(user contributes to a knowledge item)



Stochastic process for expertise (I)

Expertise of a user u on a topic a at time t as

real nonnegative mark:

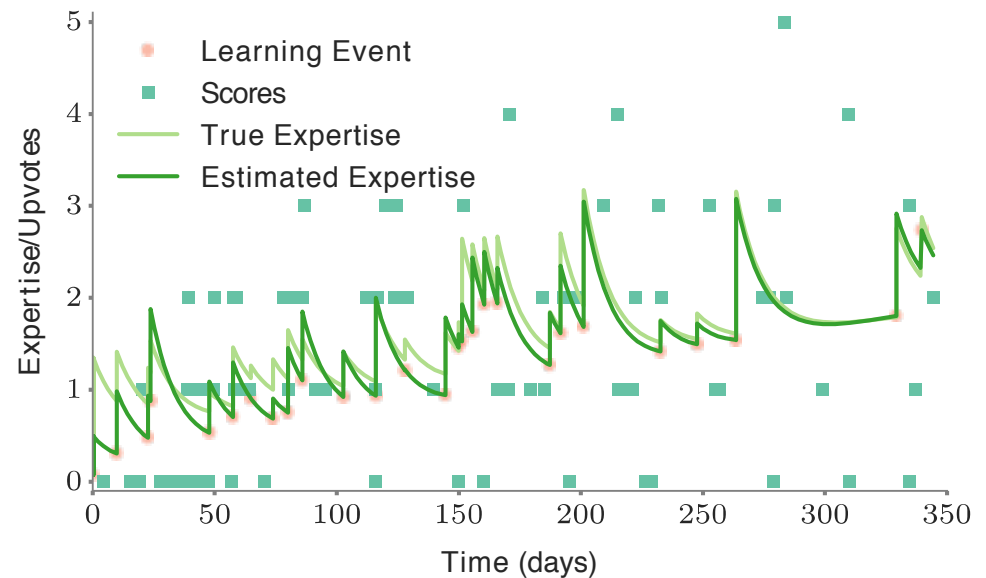


Expertise:

$$e_{ua}^*(t) := \underbrace{\alpha_{ua}}_{\text{initial expertise}} + \underbrace{\mu_{ua} \cdot t}_{\text{off-site learning}} + \underbrace{\sum_{i: q_i \in \mathcal{H}_u^l(t)} k_{q_i a} \cdot \underbrace{\kappa_\omega(t - t_i)}_{\text{forgetting}}}_{\text{on-site learning}}$$

Stochastic process for expertise (II)

Score a user's contribution received **at time t** depends on her expertise $e^*_{ua}(t)$



KEY IDEA

Use recorded scores to uncover:

→ Her expertise $e^*_{ua}(t)$

→ Knowledge values k_{qa} of the items she learns

Score distribution

The particular choice of score distribution depends on the recorded data, e.g.,

55 people learned from this answer



▲
55
▼

For the sake of completeness, I got to thinking about which method I should use to do this. There are basically two ways to do this as suggested by the other answers on this page.

Regular Expression Based Implementation

```
String.prototype.replaceAll = function(search, replacement) {  
  var target = this;  
  return target.replace(new RegExp(search, 'g'), replacement);  
};
```

Split and Join (Functional) Implementation

```
String.prototype.replaceAll = function(search, replacement) {  
  var target = this;  
  return target.split(search).join(replacement);  
};
```

Discrete non-negative scores

Contribution topics (tags)

$$\Rightarrow p(s|\mathcal{A}_q, e_u^*(t)) \sim \text{Poisson} \left(\frac{w_q^T e_u^*(t)}{w_q^T \mathbf{1}} \right)$$

User's expertise per topic (or tag)

Maximum Likelihood Estimation (MLE)

Given a collection of (million of) learning and contributing events:

Maximum likelihood estimation
(MLE)

$$\underset{\alpha \geq 0, \mu \geq 0, k \geq 0}{\text{maximize}} \sum_{(u,t,q,s) \in \mathcal{H}^c(T)} s \cdot \log \left(\frac{w_q^T e_u^*(t)}{w_q^T \mathbf{1}} \right) - \frac{w_q^T e_u^*(t)}{w_q^T \mathbf{1}}$$

Initial expertise \nearrow $\alpha \geq 0$ Off-site learning \nearrow $\mu \geq 0$ Knowledge items \nearrow $k \geq 0$

\nwarrow Contribution s

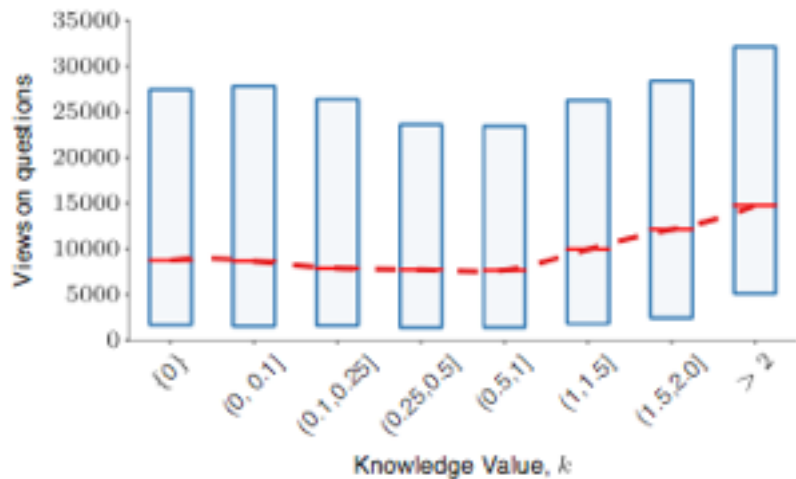
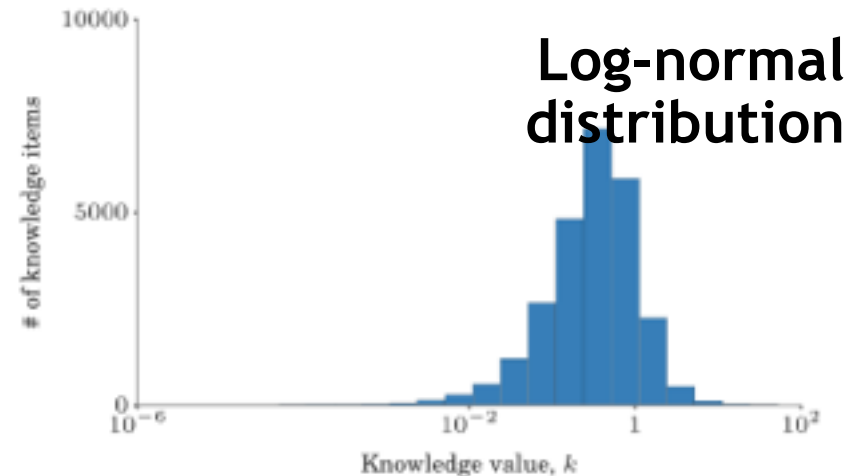
The problem is **jointly convex** on all parameters 

Convex solver finds optimal parameters **efficiently**

Distribution of knowledge

How is knowledge distributed?

10% of the items account for 60% of the knowledge!

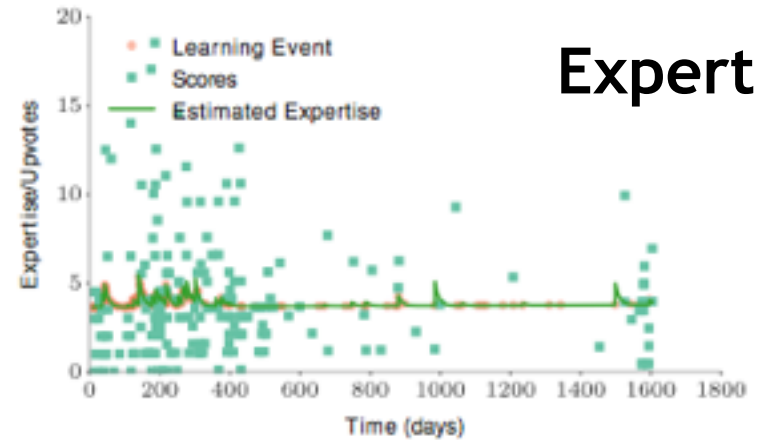
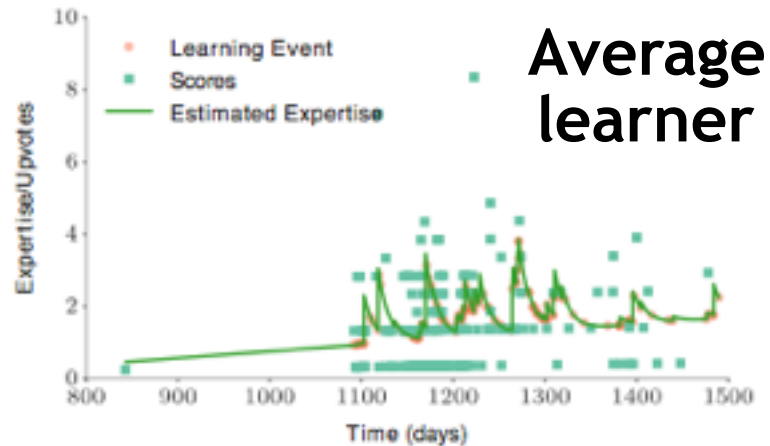


Does popularity mean high knowledge?

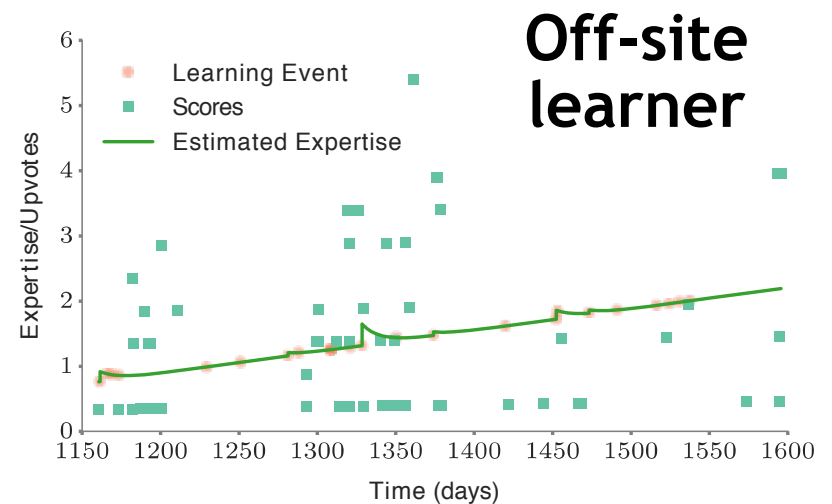
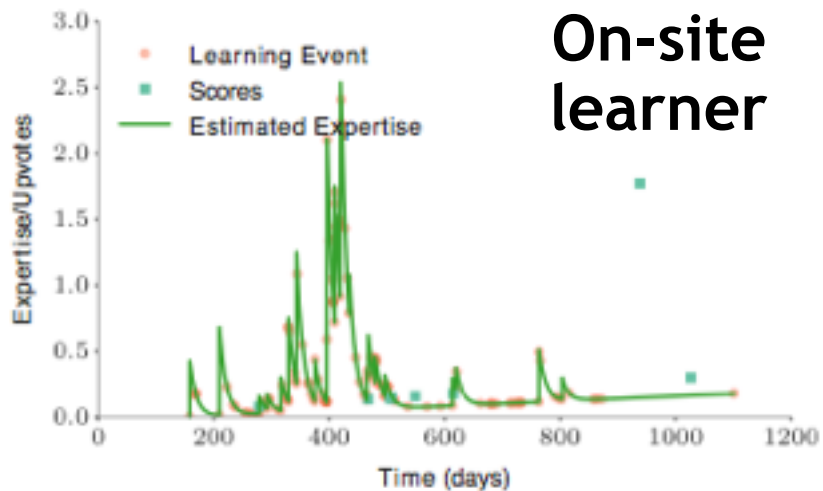
Not always - Two different knowledge regimes:

popularity is constant
it increases at a steady rate

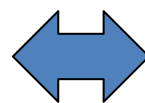
Types of learners: examples



Avg. knowledge/contribution: 0.005 \longleftrightarrow Avg. knowledge/contribution: 0.034



On-site learning 55%

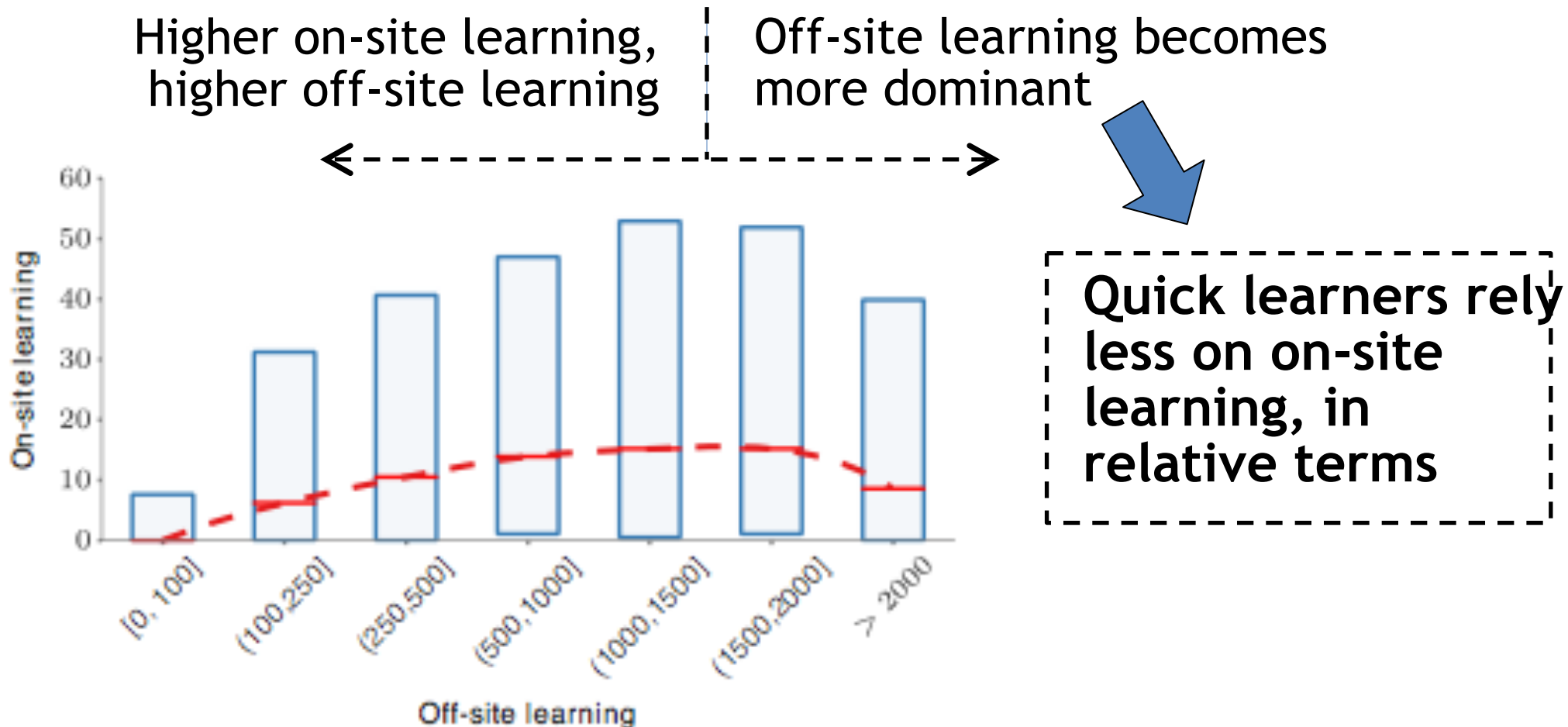


On-site learning: 0.4%

58

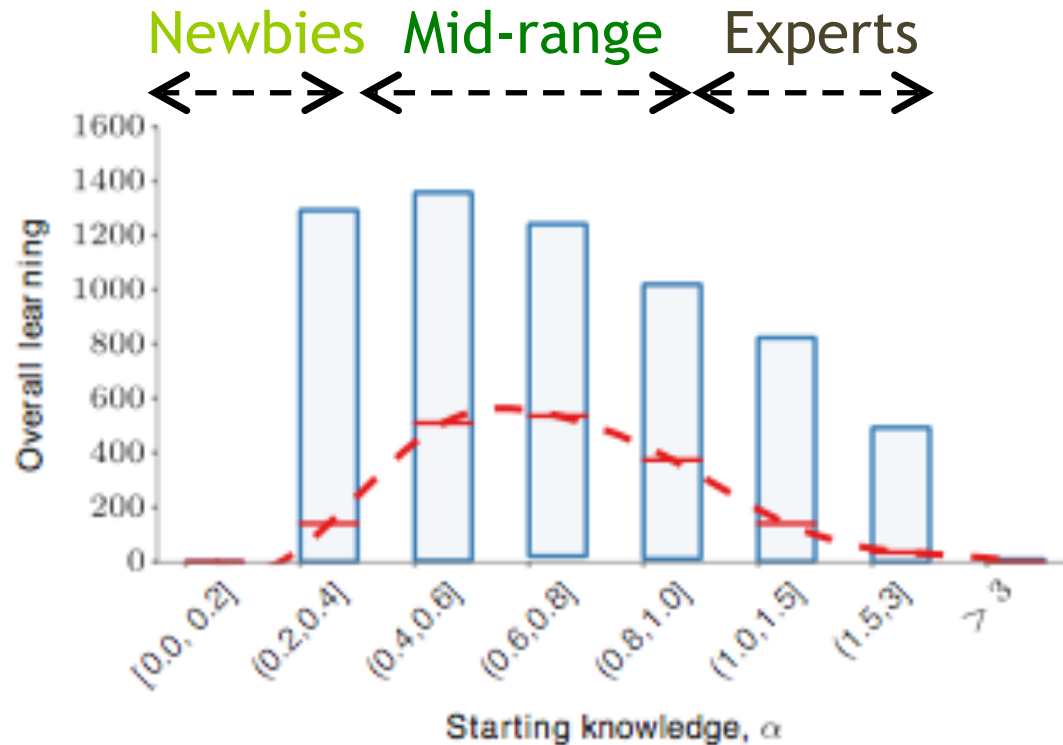
[Upadhyay et al., WSDM 2017]

Interplay between on-site and off-site learning



Learning: aggregate number of up-votes users would have received if they were posting answers only due to either their on or off-site learning

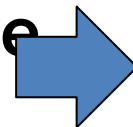
Which users learn the most?



Newbies and experts tend to increase their knowledge the least. Mid-range users tend to increase it the most.

Coherent with previous research:

If there is only positive reinforcement



Gain in expertise: sigmoidal shape

Learning patterns: An example

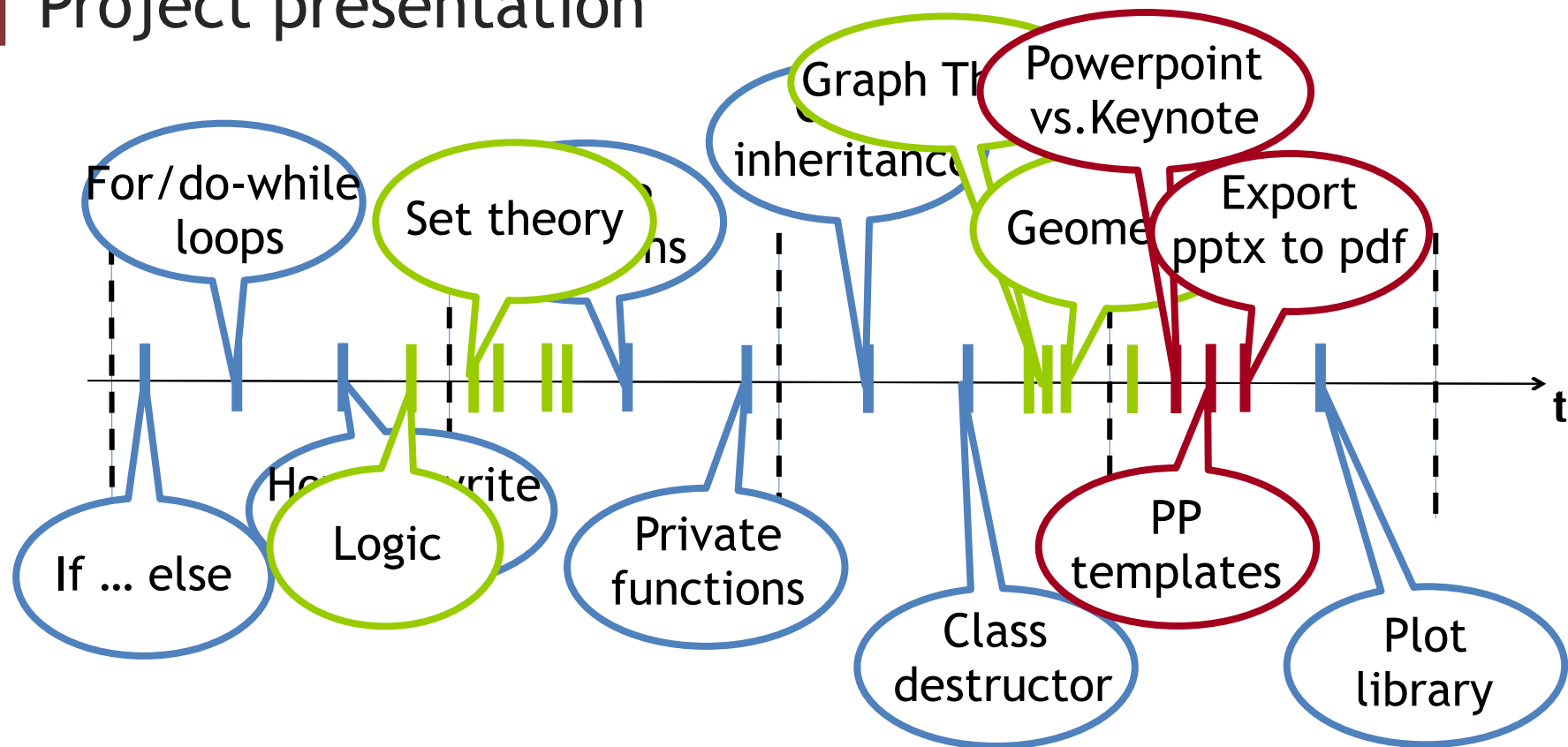
1st year computer science

student

Introduction to programming

Discrete math

Project presentation



Learning patterns: content + dynamics

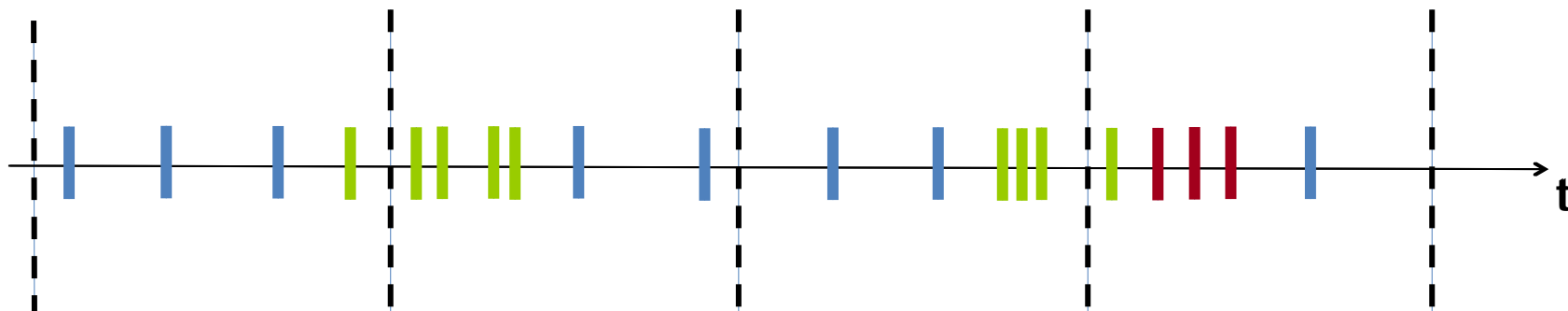
1st year computer science

student

Introduction to programming

Discrete math

Project presentation



Content + Dynamics = *Learning pattern*

programming + semester

math + semester

presentation + week

People share same learning patterns

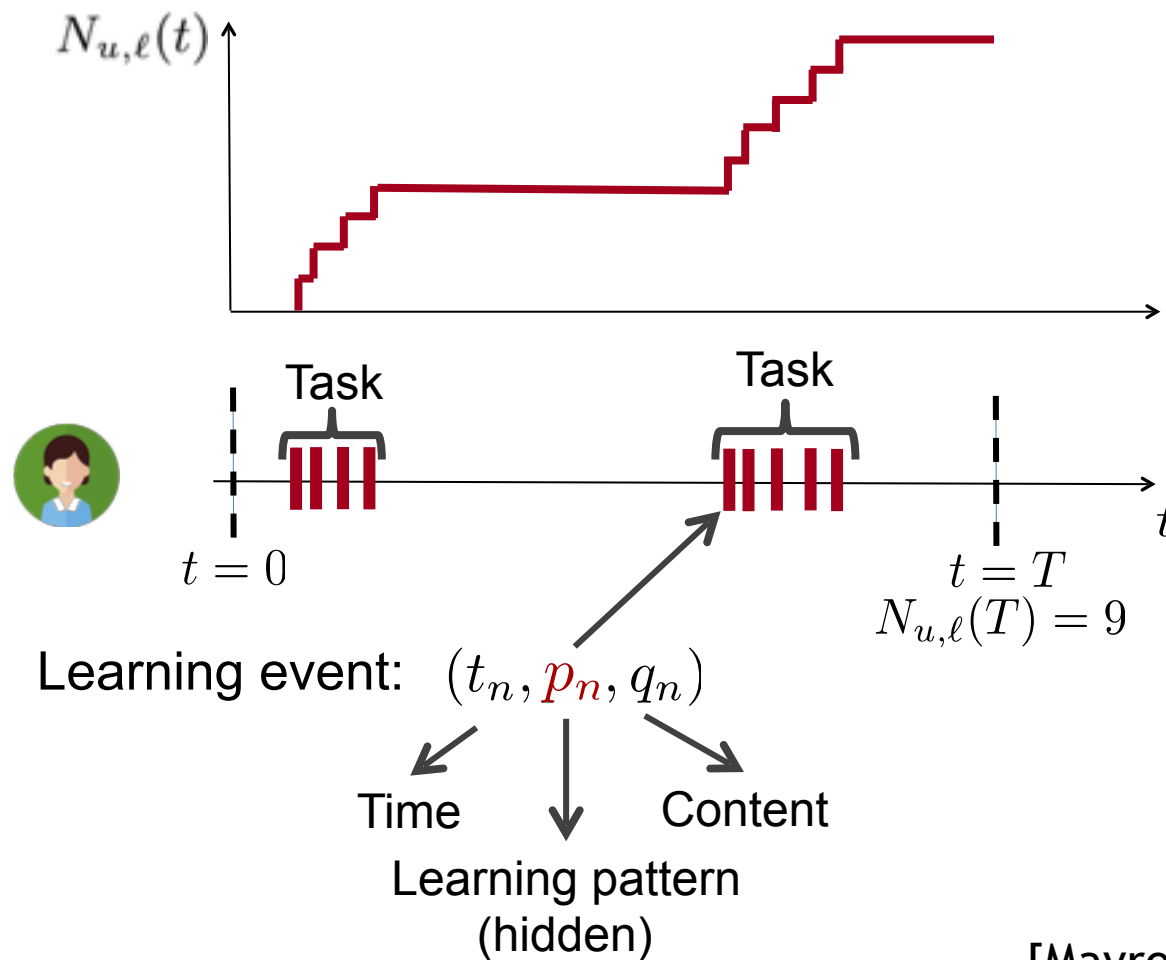
- Introduction to programming
- Discrete math
- Pr

How can we identify the learning pattern each event belongs to?

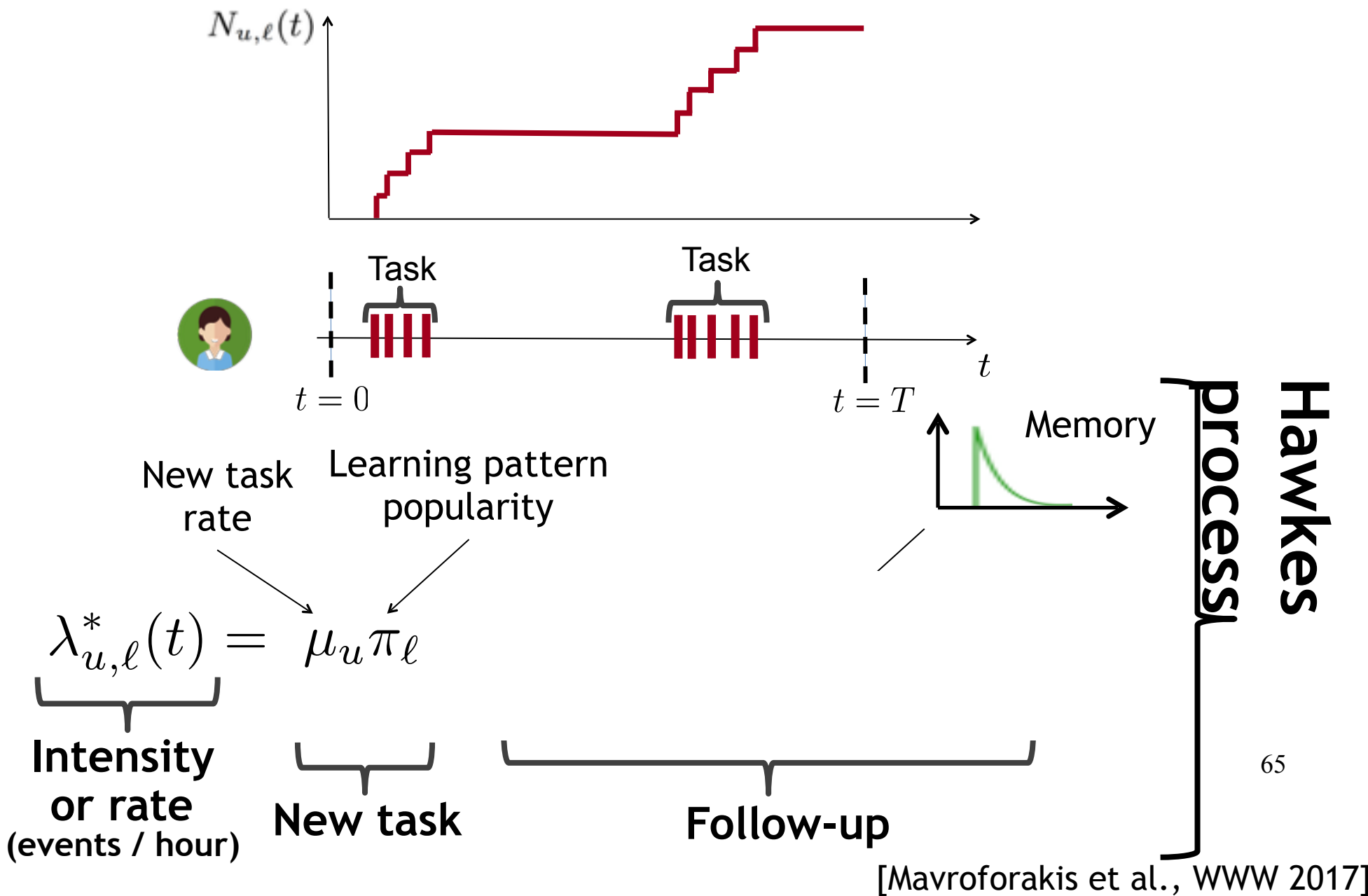


Learning events representation

We represent the learning events using marked temporal point processes:

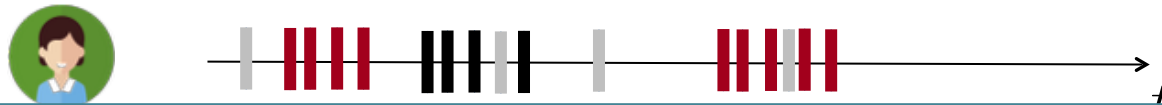


Learning pattern intensity



User learning events intensity

Users adopt more than one learning pattern:



of learning patterns is infinite.
Efficient model inference using
Sequential Montecarlo!

Details in the
reference
below!

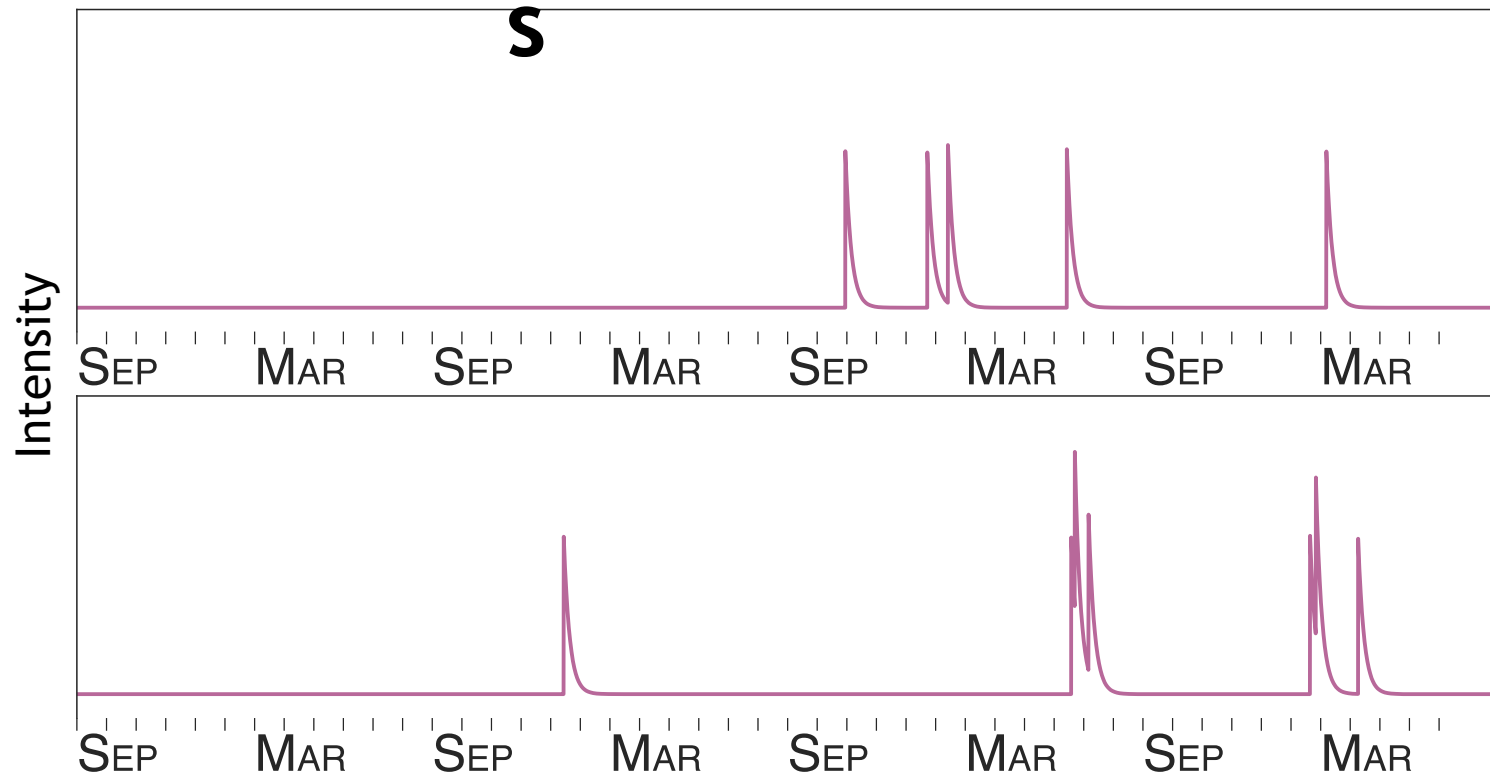
Content $\rightarrow q_n = \omega \quad \omega_j \sim \text{Multinomial}(\theta_p)$

Learning pattern (I): Version Control

Content

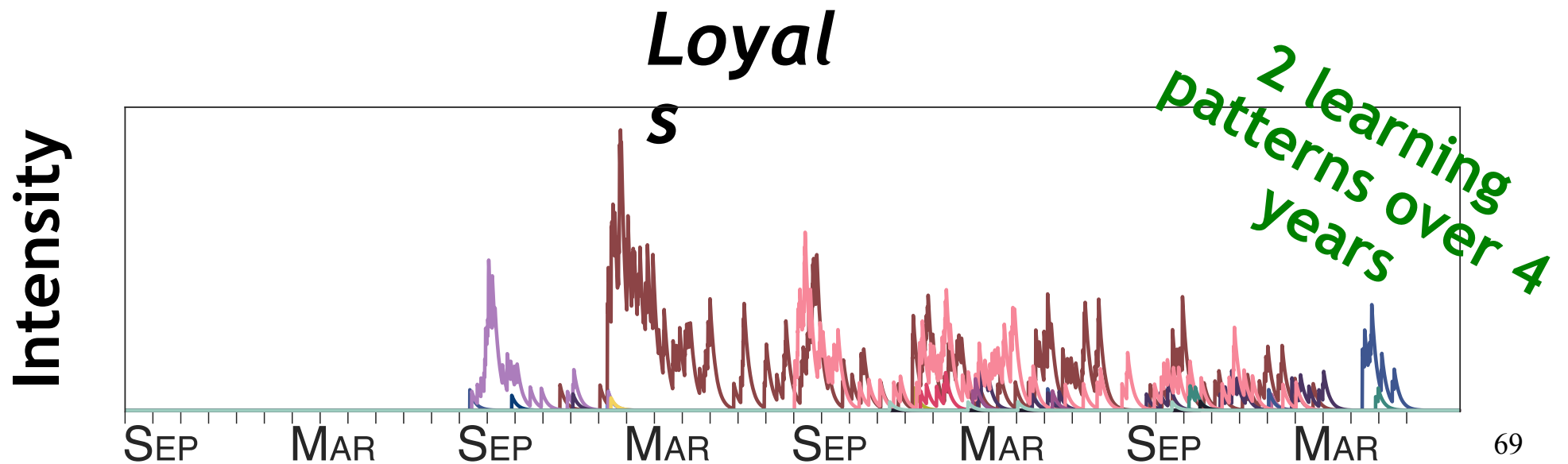
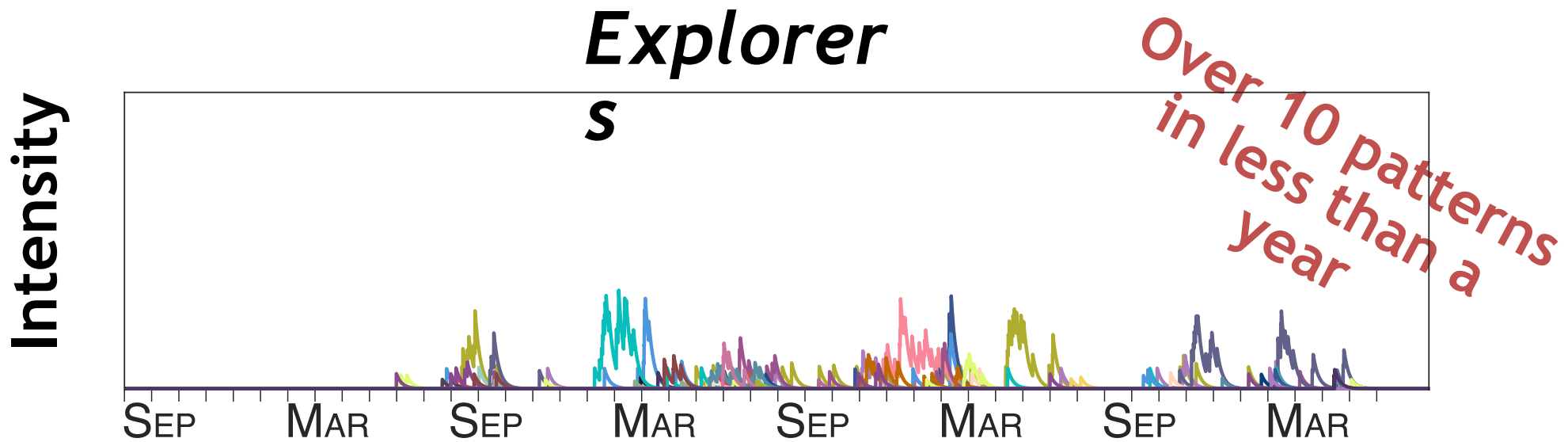


Intensities



Version control tasks tend to be specific, quickly solved after performing few questions

Types of users



REPRESENTATION: TEMPORAL POINT PROCESSES

1. Intensity function
2. Basic building blocks
3. Superposition
4. Marks and SDEs with jumps

APPLICATIONS: MODELS

1. Information propagation
2. Opinion dynamics
3. Information reliability
4. Knowledge acquisition

APPLICATIONS:

CONTROL

1. Influence maximization
2. Activity shaping
3. When to post
4. When to fact check

**This
lecture**

**Next
lecture**