Introduction to Machine-Independent Optimizations

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NPTEL Course on Compiler Design

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- What is code optimization?
- Types of code optimizations
- Illustrations of code optimizations

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Machine-independent Code Optimization

- Intermediate code generation process introduces many inefficiencies
 - Extra copies of variables, using variables instead of constants, repeated evaluation of expressions, etc.
- Code optimization removes such inefficiencies and improves code
- Improvement may be time, space, or power consumption
- It changes the structure of programs, sometimes of beyond recognition
 - Inlines functions, unrolls loops, eliminates some programmer-defined variables, etc.
- Code optimization consists of a bunch of heuristics and percentage of improvement depends on programs (may be zero also)

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Examples of Machine-Independant Optimizations

- Global common sub-expression elimination
- Copy propagation
- Constant propagation and constant folding
- Loop invariant code motion
- Induction variable elimination and strength reduction
- Partial redundancy elimination
- Loop unrolling
- Function inlining
- Tail recursion removal
- Vectorization and Concurrentization
- Loop interchange, and loop blocking

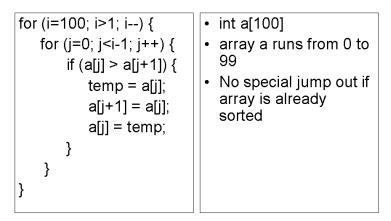
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Code optimization needs information about the program

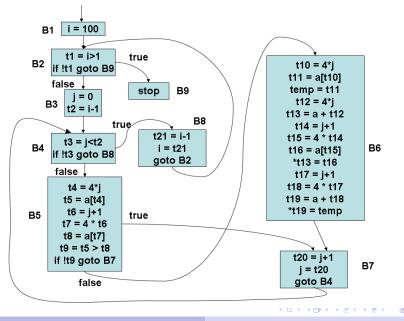
- which expressions are being recomputed in a function?
- Which expressions are partially redundant?
- which definitions reach a point?
- Which copies and constants can be propagated? Etc.
- All such information is gathered through data-flow analysis

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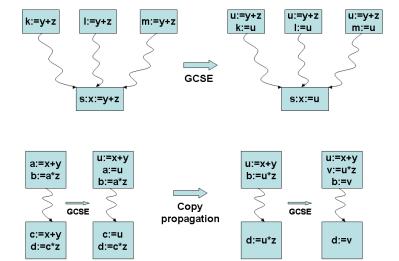
Bubble Sort



Control Flow Graph of Bubble Sort



GCSE Conceptual Example



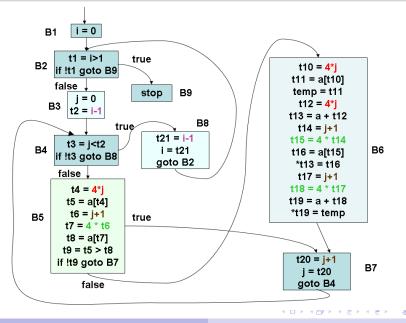
Demonstrating the need for repeated application of GCSE

Y.N. Srikant Introduction to Optimizations

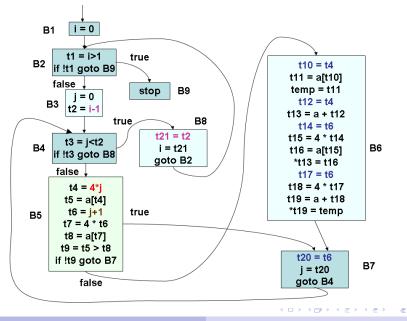
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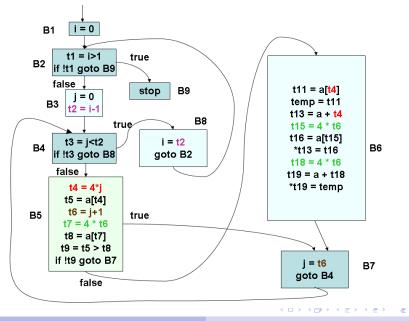
GCSE on Running Example - 1



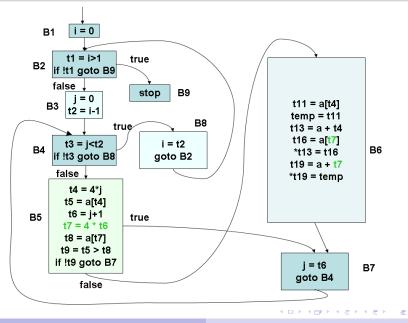
GCSE on Running Example - 2



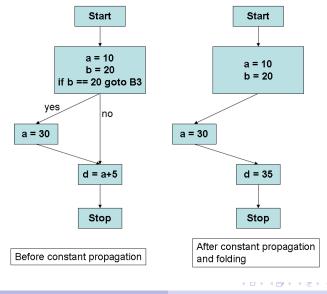
Copy Propagation on Running Example



GCSE and Copy Propagation on Running Example



Constant Propagation and Folding Example



Loop Invariant Code motion Example

$$t1 = 202$$

i = 1
L1: $t2 = i > 100$
if $t2$ goto L2
 $t1 = t1-2$
 $t3 = addr(a)$
 $t4 = t3 - 4$
 $t5 = 4*i$
 $t6 = t4+t5$
* $t6 = t1$
i = i+1
goto L1
L2:

Before LIV code motion

$$t1 = 202$$

i = 1
t3 = addr(a)
t4 = t3 - 4
L1: t2 = i>100
if t2 goto L2
t1 = t1-2
t5 = 4*i
t6 = t4+t5
*t6 = t1
i = i+1
goto L1
L2:

After LIV code motion

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Strength Reduction

$$t1 = 202$$

i = 1
t3 = addr(a)
t4 = t3 - 4
L1: t2 = i>100
if t2 goto L2
t1 = t1-2
t5 = 4*i
t6 = t4+t5
*t6 = t1
i = i+1
goto L1
L2:

Before strength reduction for t5

$$t1 = 202$$

i = 1
t3 = addr(a)
t4 = t3 - 4
t7 = 4
L1: t2 = i>100
if t2 goto L2
t1 = t1-2
t6 = t4+t7
*t6 = t1
i = i+1
t7 = t7 + 4
goto L1
L2:

After strength reduction for t5 and copy propagation

Induction Variable Elimination

$$t1 = 202$$

i = 1
t3 = addr(a)
t4 = t3 - 4
t7 = 4
L1: t2 = i>100
if t2 goto L2
t1 = t1-2
t6 = t4+t7
*t6 = t1
i = i+1
t7 = t7 + 4
goto L1
L2:

Before induction variable elimination (i)

$$t1 = 202$$

$$t3 = addr(a)$$

$$t4 = t3 - 4$$

$$t7 = 4$$

L1: $t2 = t7 > 400$
if $t2 \text{ goto } L2$

$$t1 = t1-2$$

$$t6 = t4+t7$$

* $t6 = t1$

$$t7 = t7 + 4$$

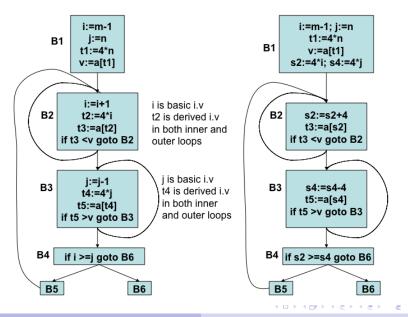
goto L1
L2:

After eliminating i and replacing it with t7

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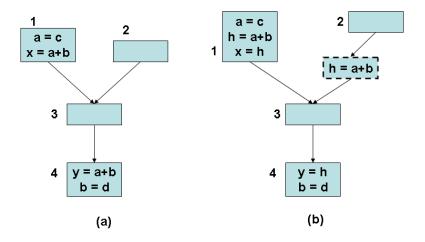
Induction Variable Elimination and Strength Reduction



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Introduction to Optimizations

Partial Redundancy Elimination



```
for (i = 0; i<N; i++) { S_1(i); S_2(i); }
for (i = 0; i+3 < N; i+=3) {
   S_1(i); S_2(i);
   S_1(i+1); S_2(i+1);
   S_1(i+2); S_2(i+2);
// remaining few iterations, 1,2, or 3:
// (((N-1) mod 3)+1)
for (k=i; k < N; k++) \{ S_1(k); S_2(k); \}
```

Unrolling While and Repeat loops

repeat { S_1 ; S_2 ; } until C; while (C) { S_1 ; S_2 ; } repeat { while (C) { S₁; S₂; $S_1; S_2;$ if (C) break; if (!C) break; $S_1; S_2;$ S₁; S₂; if (C) break; if (!C) break; S₁; S₂; S₁; S₂; } until C; }

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```
int find greater(int A[10], int n) { int i;
   for (i=0; i<10; i++){ if (A[i] > n) return i; }
// inlined call: x = find greater(Y, 250);
int new i, new A[10];
new A = Y:
for (new i=0; new i<10; new i++) {
   if (new A[new i] > 250)
     \{x = new i; goto exit;\}
}
exit:
```

```
void sum (int A[], int n, int* x) {
    if (n==0) *x = *x+ A[0]; else {
       x = x + A[n]; sum(A, n-1, x);
   }
}
// after removal of tail recursion
void sum (int A[], int n, int* x) {
  while (true) { if (n==0) {*x=*x+A[0]; break;}
                else{ x=x + A[n]; n=n-1; continue;
  }
```

Vectorization and Concurrentization Example 1

```
for I = 1 to 100 do {
   X(I) = X(I) + Y(I)
}
can be converted to
X(1:100) = X(1:100) + Y(1:100)
or
forall I = 1 to 100 do X(I) = X(I) + Y(I)
```

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```
for I = 1 to 100 do {
    X(I+1) = X(I) + Y(I)
}
```

cannot be converted to

```
X(2:101) = X(1:100) + Y(1:100)
or equivalent concurrent code
```

because of dependence as shown below

```
X (2) = X (1) + Y (1)

X (3) = X (2) + Y (2)

X (4) = X (3) + Y (3)
```

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Loop Interchange for parallelizability

```
for I = 1 to N do {
for J = 1 to N do {
S: A(I+1,J) = A(I,J) * B(I,J) + C(I,J)
}
```

Outer loop is not parallelizable, but inner loop is

Less work per thread

for J = 1 to N do { for I = 1 to N do { S: A(I+1,J) = A(I,J) * B(I,J) + C(I,J) } Outer loop is parallelizable but inner loop is not

More work per thread

```
forall J = 1 to N do {
for I = 1 to N do {
S: A(I+1,J) = A(I,J) * B(I,J) + C(I,J)
}
}
```

```
{ for (i = 0; i < N; i++)
   for (j=0; j < M; j++)
      A[i, I] = B[i] + C[i];
}
// Loop after blocking
{ for (ii = 0; ii < N; ii = ii+64)
   for (ii = 0; ii < M; ii = ii+64)
      for (i = ii; i < ii+64; i++)
        for (i=i); i < ii+64; i++)
           A[i, l] = B[i] + C[i];
}
```