

Linear Systems I



Generally a problem of computing solution to a BVP is converted to the problem of solving a system of linear equations.

- discretization of domain
- collocation

Linear Algebra

$$Ax = b$$

$$A \in \mathbb{R}^{m \times n}$$

$$b \in \mathbb{R}^{m \times 1}$$

To find $x \in \mathbb{R}^{n \times 1}$ such that

$$Ax = b$$

For us today, $m = n$. (A is square)

Given $Ax = b$, compute x .

A is invertible $\Rightarrow x$ is unique.

$$x = A^{-1}b$$

Question: If A and b are
NOT EXACTLY known, what is
the effect on the solution we
obtain?!

Plan:

- Introduce the concept of distance on the vectors and matrices.
- Condition number.
- Sensitivity analysis.

Vector norm :

$\| \cdot \| \rightarrow \mathbb{R}^n \rightarrow \mathbb{R}$ which satisfies

i) $\|x\| \geq 0$, $\|x\| = 0$ iff $x = 0$.

ii) $\|\alpha x\| = |\alpha| \|x\|$; $\alpha \in \mathbb{R}$

iii) $\|x+y\| \leq \|x\| + \|y\|$

~~*~~
How far x is from y , $\|x-y\|$

Examples

i) $\|x\|_2 = \left(\sum_{i=1}^n |x_i|^2 \right)^{1/2}$; $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

ii) $\|x\|_\infty = \max_{i=1, \dots, n} |x_i|$ $\leftarrow \infty \text{ as } p \rightarrow \infty$

iii) $\|x\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p}$ $p > 1$

Matrix - norms:

$$\| \cdot \| : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$$

i) $\|A\| > 0$, and $\|A\| = 0$ iff $A = 0$.

ii) $\|\alpha A\| = |\alpha| \|A\|$ for $\alpha \in \mathbb{R}$
 $A \in \mathbb{R}^{n \times n}$

iii) $\|A+B\| \leq \|A\| + \|B\|$

iv) $\|AB\| \leq \|A\| \|B\|$

Example :

$$\|A\|_F = \left(\sum_{j=1}^n \sum_{i=1}^n |a_{ij}|^2 \right)^{1/2}$$

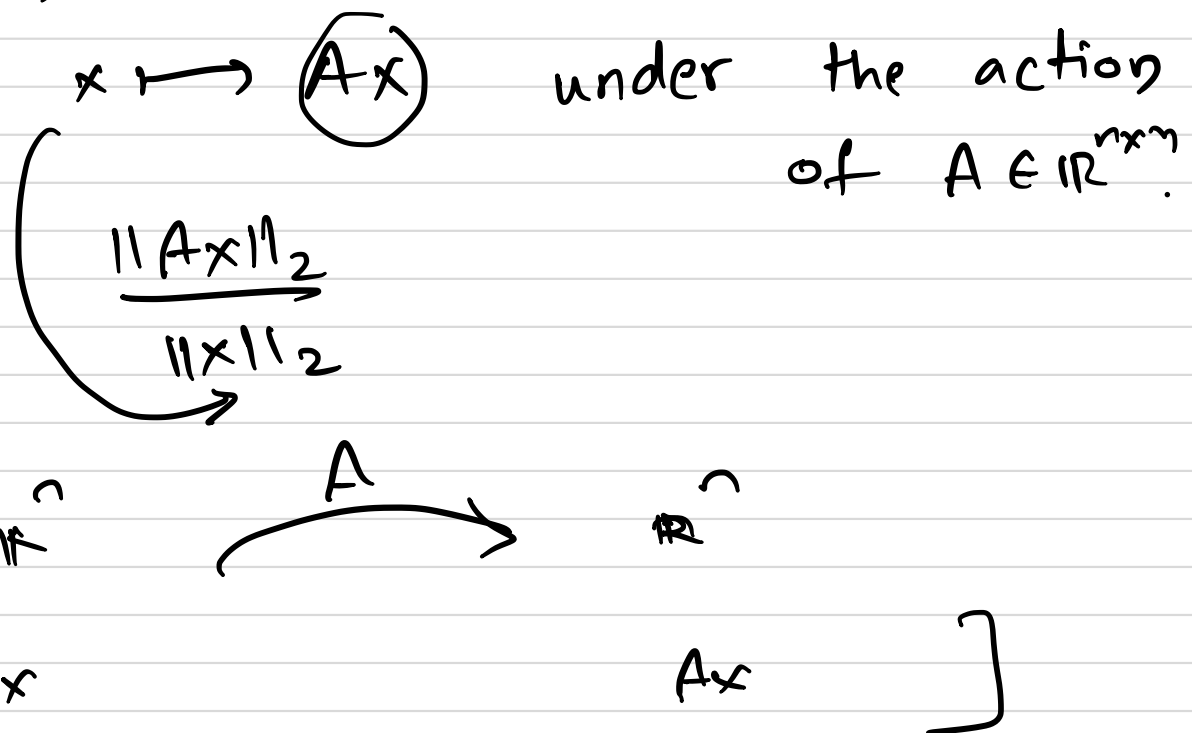
where $A = [a_{ij}]_{i=1, j=1}^n$

Frobenius - norm of A .

Induced - matrix norms:

$$\|A\|_2 = \max_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2}$$

Matrix as a linear function from $\mathbb{R}^n \rightarrow \mathbb{R}^m$



$$\|A\|_2 = \max_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2}$$

$$\text{let } \alpha = \|x\|_2 \quad = \max_{x \neq 0} \left\| A \frac{x}{\alpha} \right\|_2$$

$$= \max_{x \neq 0} \left\| A \frac{x}{\|x\|_2} \right\|_2$$

Geometric meaning of induced norm

$$\|A\|_2 = \max_{\|y\|_2=1} \|Ay\|_2$$

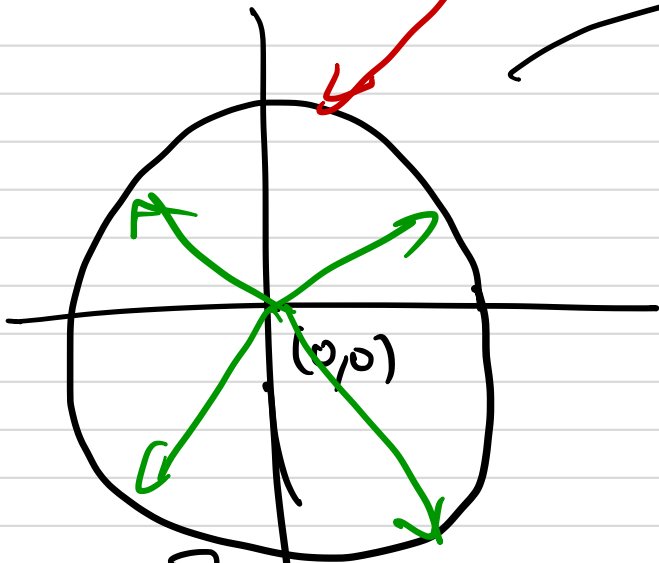
$$\|Ay\|_2$$

$$y = \frac{x}{\|x\|_2}$$

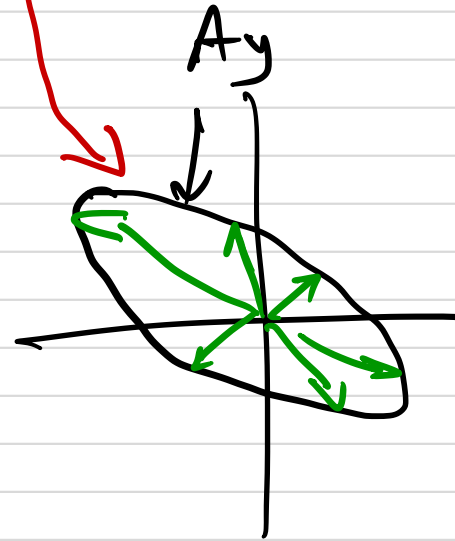
$$x \neq 0$$

$$A \in \mathbb{R}^{2 \times 2}$$

$$\mathbb{R}^2$$



$$\|y\|_2 = 1$$



We want to solve $Ax = b$

Note that the matrices A & b

may not be known exactly.

↔ Understand the effect of this on the computed solution.

Case (1) Assume A is known exactly. However b is not known exactly.

$$\left[\begin{array}{c} \text{---} \\ | \quad | \quad | \quad | \quad | \quad | \quad | \quad | \quad | \quad | \\ x_1 \quad x_2 \quad x_3 \quad \dots \quad x_i \quad \dots \quad x_n \\ \text{---} \end{array} \right]$$

$$\frac{d^2 y}{dx^2} = f$$

$$y(a) = \dots$$

$$y(b) = \dots$$

$$\frac{y(x_{i+1}) - 2y(x_i) + y(x_{i-1}))}{(x_{i+1} - x_i)^2} = f(x_i)$$

$$Ax = b \quad \text{--- (1)}$$

b not known exactly.

$$A\hat{x} = b + \delta b$$

where \hat{x} is an exact solution. A
 $A\hat{x} = b + \delta b$

Denote by $\hat{x} = x + \delta x$

$$A(x + \delta x) = b + \delta b \quad \text{--- (2)}$$

Subtracting (1) from (2)

$$A\delta x = \delta b$$

$$\Rightarrow \delta x = A^{-1} \delta b$$

$$\Rightarrow \|\delta x\|_2 = \|A^{-1} \delta b\|_2$$

$$\leq \|A^{-1}\|_2 \|\delta b\|_2 \quad \text{--- (*)}$$

$$\text{From (1), } \|b\|_2 \leq \|A\|_2 \|x\|_2$$

$$\Rightarrow \frac{1}{\|x\|_2} \leq \|A\|_2 \frac{1}{\|b\|_2} \quad \text{--- (**)}$$

From (*) & (**)

$$\frac{\|\delta x\|_2}{\|x\|_2} \leq \|A\|_2 \|A^{-1}\|_2 \frac{\|\delta b\|_2}{\|b\|_2}$$

Definition: Let $A \in \mathbb{R}^{n \times n}$ be an invertible matrix. Then condition number of A w.r.t. induced 2-norm is defined as

$$k_2(A) = \|A\|_2 \cdot \|A^{-1}\|_2$$

Exercise:

$$\|I\|_2 = 1.$$

For any invertible matrix A

$$I = AA^{-1}$$

$$\underbrace{1 = \|I\|_2}_{\text{LHS}} = \|AA^{-1}\|_2 \leq \|A\|_2 \|A^{-1}\|_2 = k_2(A)$$

$$\Rightarrow k_2(A) \geq 1$$

Take $A = I$

$$1 = \|I\|_2 = \|II^{-1}\|_2 \leq \|I\|_2 \|I^{-1}\|_2 = 1$$

$$\Rightarrow k_2(I) = 1$$

Example: b is not exactly known.

$$\frac{\|\delta b\|_2}{\|b\|_2} \approx 10^{-4}$$

$$k_2(A) \approx 10^2$$

$$\frac{\|\delta x\|_2}{\|x\|_2} \leq k_2(A) \frac{\|\delta b\|_2}{\|b\|_2}$$
$$10^2 \cdot 10^{-4}$$

$$\frac{\|\delta x\|_2}{\|x\|_2} \leq 10^{-2}$$

Ex: $A = \begin{bmatrix} 1000 & 999 \\ 999 & 998 \end{bmatrix}$

$$b = \begin{bmatrix} 1999 \\ 1997 \end{bmatrix}$$

$$x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

$$b + \delta b = \begin{bmatrix} 1998.99 \\ 1997.01 \end{bmatrix}$$

$$; \delta b = \begin{bmatrix} -0.01 \\ 0.01 \end{bmatrix}$$

$$A \hat{x} = b + \delta b$$

$$\hat{x} = x + \delta x = \begin{bmatrix} 20.97 \\ -18.99 \end{bmatrix}$$

Check:

$$A^{-1} = \begin{bmatrix} -998 & 999 \\ 999 & -1000 \end{bmatrix}$$

$$k_2(A) = 3.992 \times 10^6$$

$$\frac{\| \delta x \|_2}{\| x \|_2}$$

$$\leq k_2(A)$$

$$10^6$$

$$\frac{\| \delta b \|_2}{\| b \|_2}$$

$$10^{-5}$$

$$b + \delta b = \begin{bmatrix} 1999.01 \\ 1997.01 \end{bmatrix}$$

$$A \hat{x} = \begin{bmatrix} 1999.01 \\ 1997.01 \end{bmatrix}$$

$$\hat{x} = \begin{pmatrix} 1.01 \\ 0.99 \end{pmatrix}$$

magnification:

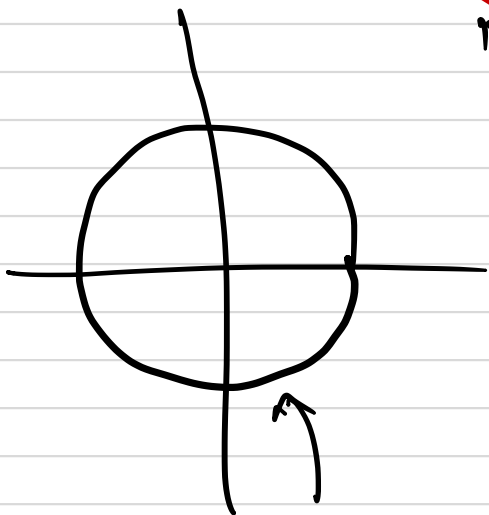
maximum magnification of A :

$$\text{magmax}(A) = \max_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2} = \|A\|_2$$

minimum magnification of A :

$$\text{min mag}(A) = \min_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2}$$

$$= \min_{\|x\|_2 = 1} \|Ax\|_2$$



unit circle

$$\|x\|_2 = 1$$

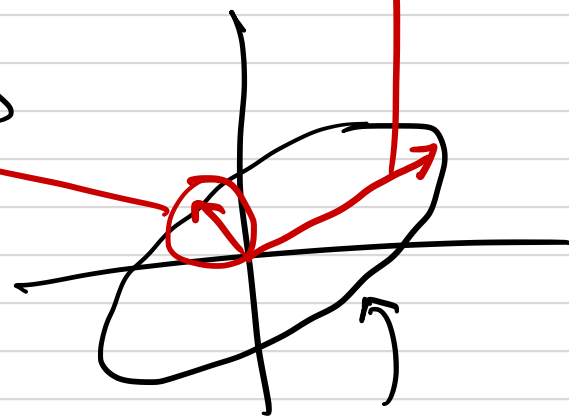
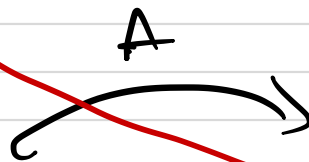


image of the
unit circle

Ax

Exercise: For an invertible matrix

$A \in \mathbb{R}^{n \times n}$, prove that

$$\max \text{mag}(A) = \frac{1}{\min \text{mag}(A^{-1})}$$

$$\max \text{mag}(A^{-1}) = \frac{1}{\min \text{mag}(A)}$$

Consequence of the exercise:

$$k_2(A) = \|A\|_2 \|A^{-1}\|_2$$

$$= \max \text{mag}(A) \cdot \max \text{mag}(A^{-1})$$

$$k_2(A) = \frac{\max \text{mag}(A)}{\min \text{mag}(A)}$$

Exercise:

$$\text{Let } A = \begin{pmatrix} 1/\epsilon & 0 \\ 0 & \epsilon \end{pmatrix}$$

where ϵ is such that $|\epsilon|$ is very close to zero. but $\epsilon \neq 0$.

Fundamentals of matrix computations

- David Watkins

Numerical linear algebra and applications

- Biswa Nath Datta

Matrix Computations

- Golub, Van Loan

Proof, refer the books.

Sensitivity result.

$$\text{Let } Ax = b \text{ and } (A + \delta A)(x + \delta x) = (b + \delta b).$$

$$A \text{ is non-singular and } \frac{\|\delta A\|_2}{\|A\|_2} < \frac{1}{k_2(A)}.$$

then

$$\frac{\|\delta x\|_2}{\|x\|_2} \leq \frac{k_2(A) \left[\frac{\|\delta A\|_2}{\|A\|_2} + \frac{\|\delta b\|_2}{\|b\|_2} \right]}{1 - k_2(A) \left(\frac{\|\delta A\|_2}{\|A\|_2} \right)}$$

Understanding ill-conditioned matrices.

$A \in \mathbb{R}^{n \times n}$ with a very high

condition number.

$$A = \begin{pmatrix} 1 & 0 \\ 0 & \varepsilon \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ \varepsilon \end{pmatrix}$$

$$Ax = b \Rightarrow x = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$1 \leq k_2(A) = \frac{\max \text{mag}(A)}{\min \text{mag}(A)} = \frac{1}{\min \text{mag}(A)}$$

$$\Rightarrow k_2(A) \gg 1$$

$$\Rightarrow \min \text{mag}(A) \ll 1$$

\exists a ^{unit vector} $c \in \mathbb{R}^n$ such that

$$\|Ac\| \ll 1$$

$$\min_{\|c\|=1} \|Ac\| = \min \text{mag}(A)$$

$$Ac = \sum_{i=1}^n a_i c_i$$

$$A = \begin{bmatrix} a_1 & a_2 & \dots & a_n \\ \vdots & \vdots & & \vdots \end{bmatrix}$$

$$c = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$

\Rightarrow Columns of A are

"almost" linearly dependent.

Similarly, I can prove, rows of A are

"almost" linearly dependent.

$$A = \begin{bmatrix} 1000 & 999 \\ 999 & 998 \end{bmatrix}$$

$$\therefore \kappa_2(A) \approx 10^6$$

$$Ax = b + \delta b$$

$$b = \begin{bmatrix} 1999 \\ 1997 \end{bmatrix}$$

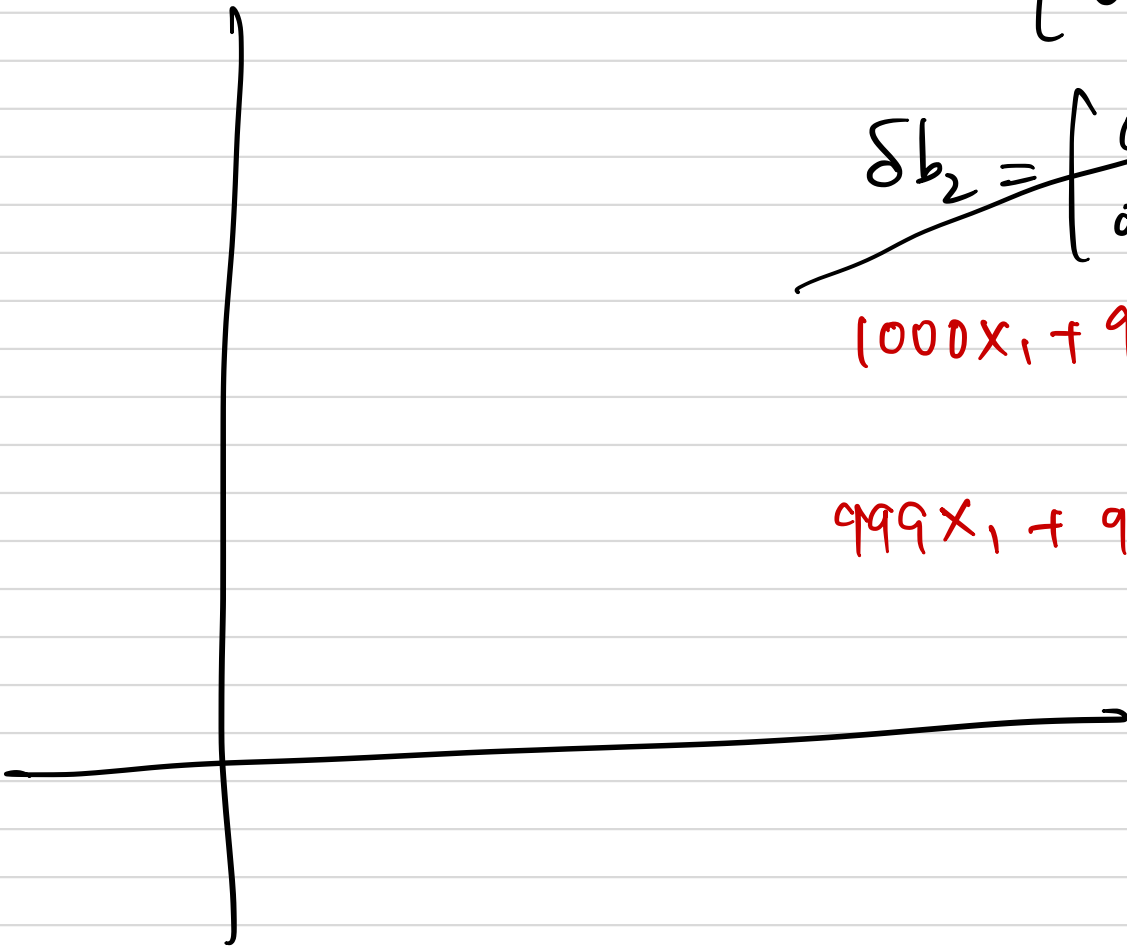
$$\begin{cases} 1000x_1 + 999x_2 = 1999 \\ 999x_1 + 998x_2 = 1997 \end{cases}$$

$$\delta b = \begin{bmatrix} -0.01 \\ 0.01 \end{bmatrix}$$

~~$$\delta b_2 = \begin{bmatrix} 0.01 \\ 0.01 \end{bmatrix}$$~~

$$\begin{aligned} 1000x_1 + 999x_2 & \\ &= 1998.01 \end{aligned}$$

$$\begin{aligned} 999x_1 + 998x_2 & \\ &= 1997.01 \end{aligned}$$



Hilbert matrix

$$A = \begin{pmatrix} 1 & 1/2 & 1/3 & 1/4 \\ 1/2 & 1/3 & 1/4 & 1/5 \\ & & & \dots \end{pmatrix}$$

Hilb(n)

Singular Value Decomposition (1930)

Let $A \in \mathbb{R}^{m \times n}$. Then there exist orthogonal matrices $U \in \mathbb{R}^{m \times m}$ and $V \in \mathbb{R}^{n \times n}$ and numbers $\sigma_1^2 \geq \sigma_2^2 \geq \dots \geq \sigma_r^2 > 0$ where $r \leq \min\{m, n\}$ such

that

$$A = U \Sigma V^T$$

where $\Sigma = \begin{pmatrix} \sigma_1^2 & & & 0 \\ & \ddots & & \\ 0 & & \sigma_r^2 & \\ & & & 0 \end{pmatrix}_{m \times n}$

$$r = \text{rank}(A)$$

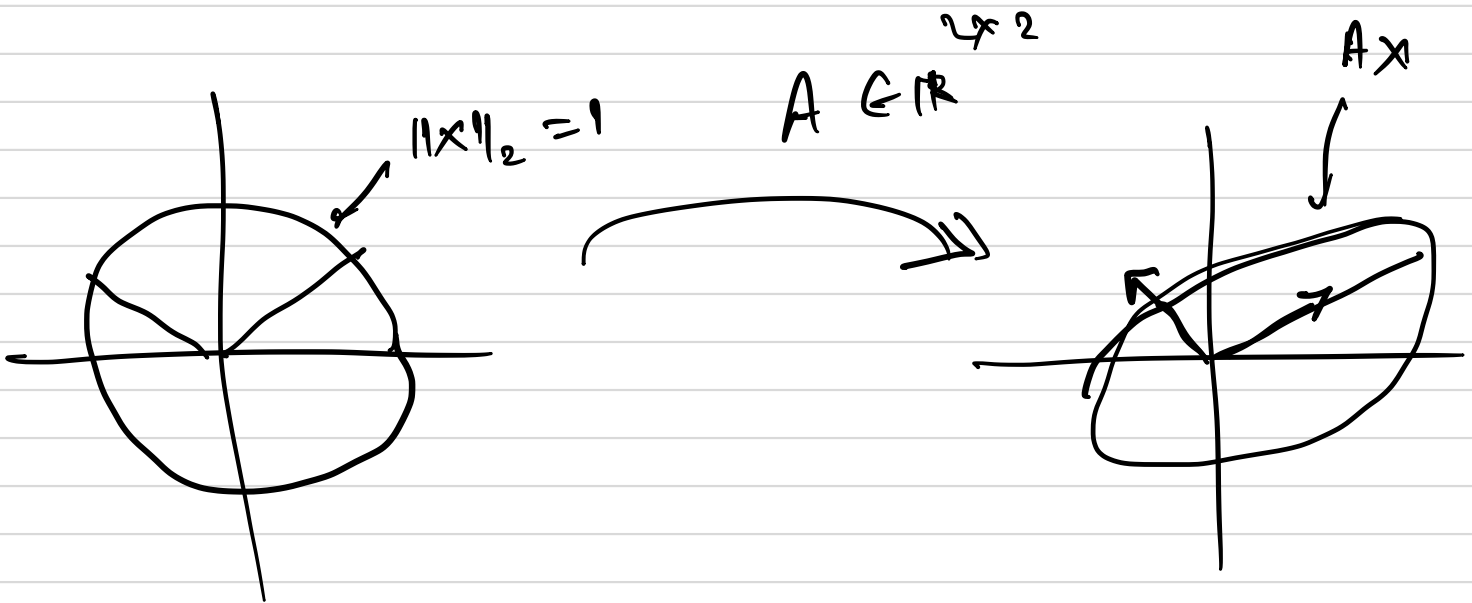
$$U = \begin{bmatrix} | & & | \\ u_1 & \dots & u_m \\ | & & | \end{bmatrix}$$

$$V = \begin{bmatrix} | & & | \\ v_1 & \dots & v_m \\ | & & | \end{bmatrix}$$

$$A = \underbrace{\sigma_1^2 u_1 v_1^T}_{\text{maxmag}(A)} + \sigma_2^2 u_2 v_2^T + \dots + \sigma_r^2 u_r v_r^T$$

maxmag(A)

minmag(A)



$$[U, S, V] = \text{svd}(A)$$

$$A = U S V^T$$