

Dynamic Analysis of Transmission System

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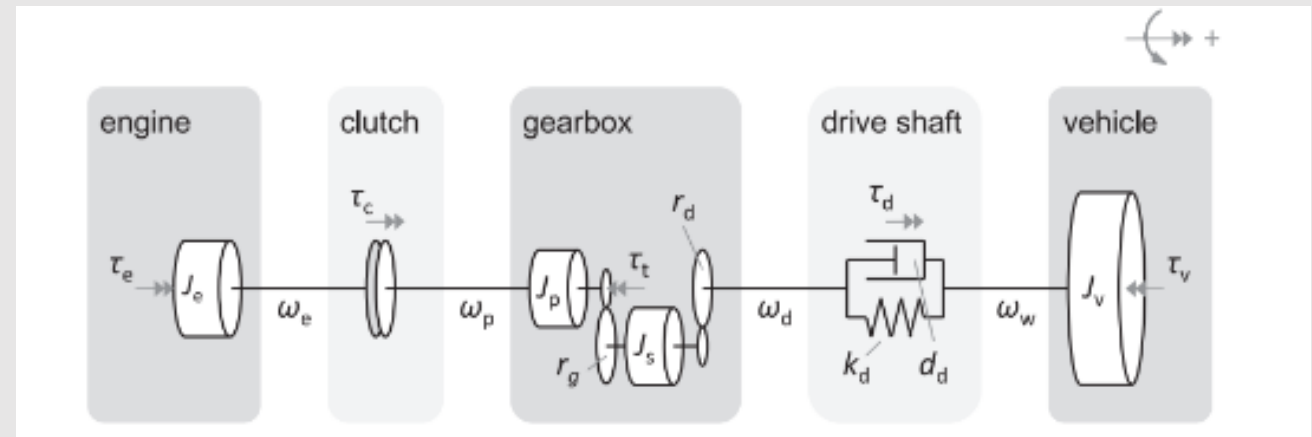
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Drive Train

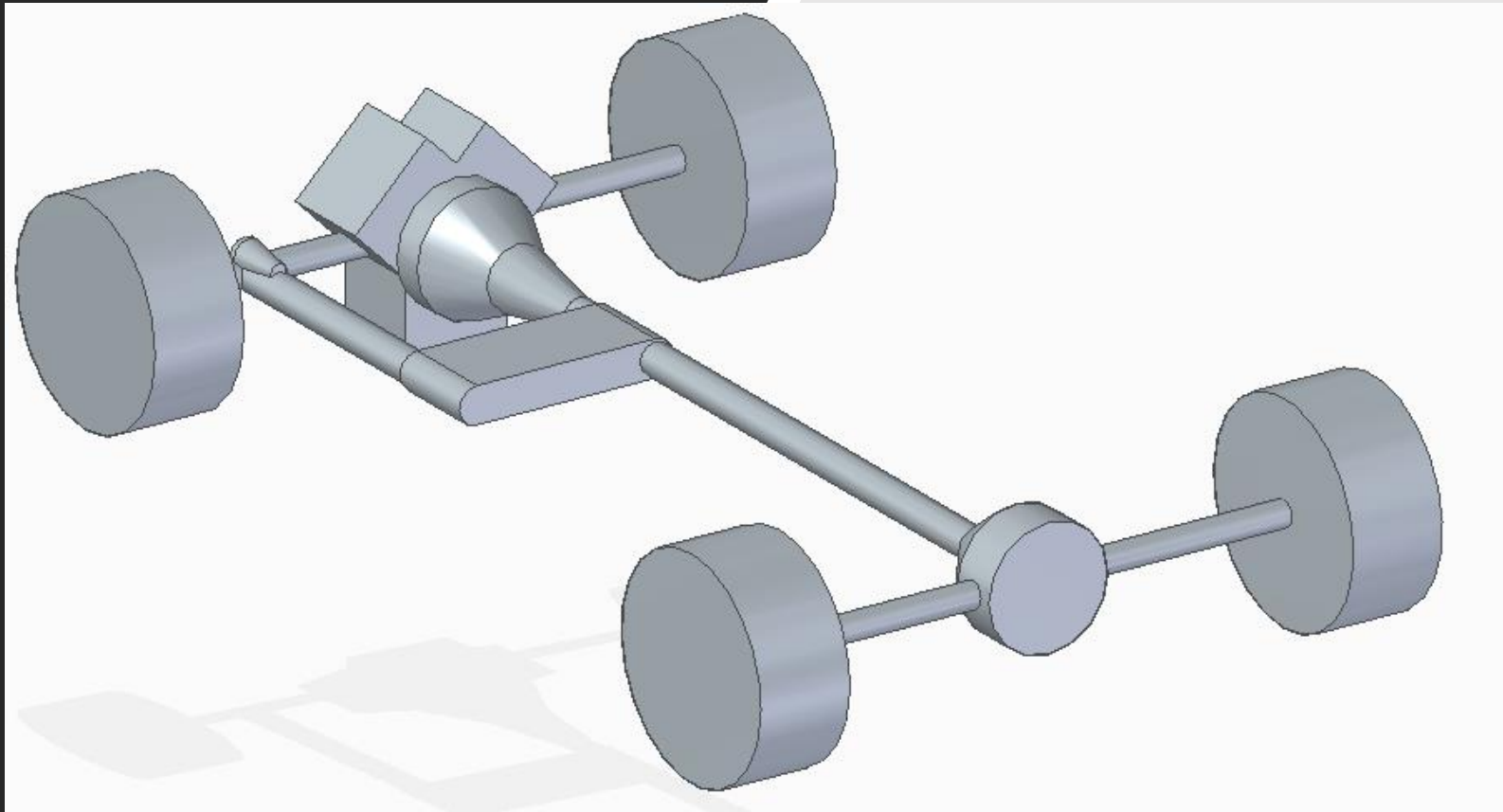
Components of Drive Train

- Engine
- Clutch
- Gear/Transmission System
- Propeller Shafts
- Final Drive
- Drive Shaft
- Wheel



“It’s a system to transfer engine torque to the wheel.”

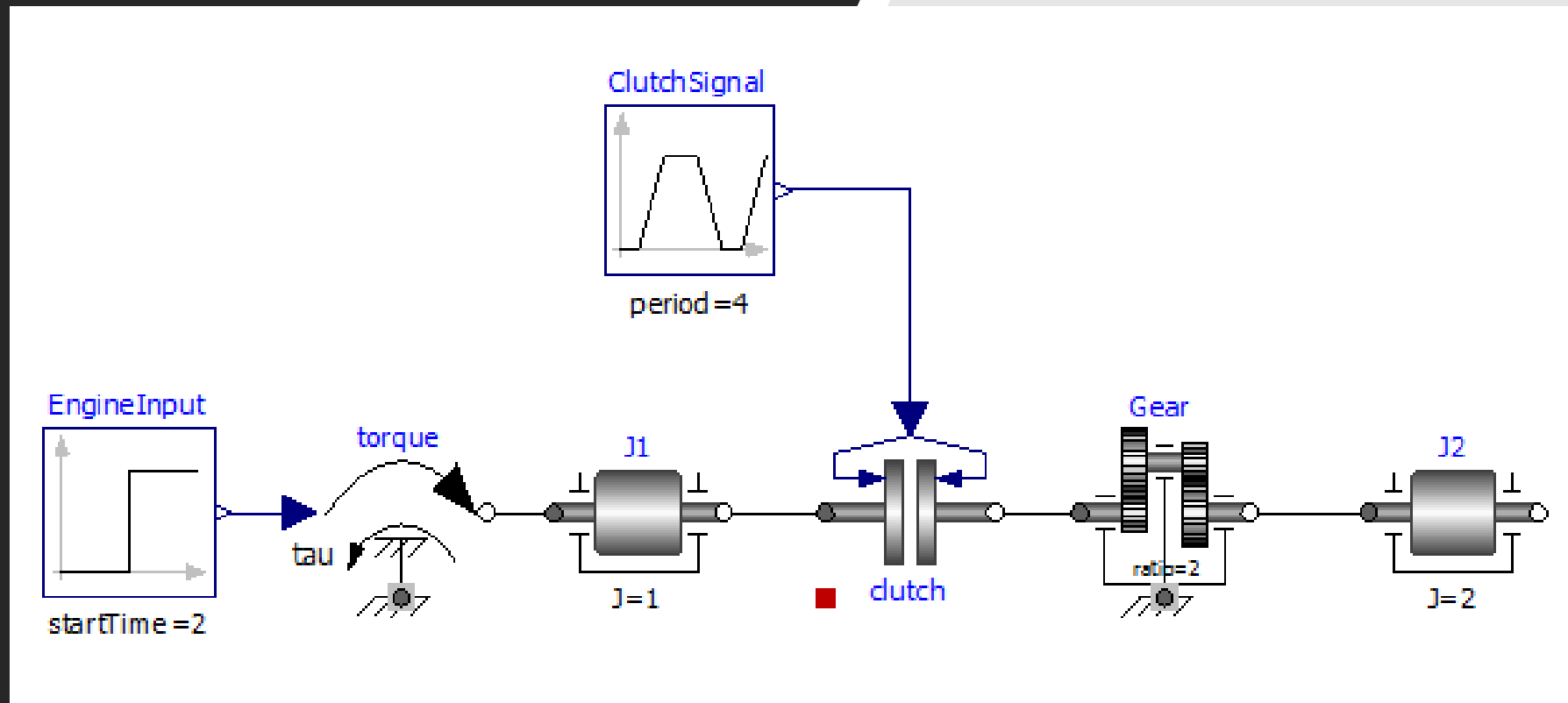
CAD MODEL



CAD MODEL



Model of Clutch in Modelica



Clutch (Equations)

$F_c = F_{c,max} u_c$, where $F_{c,max}$ (the maximum possible normal force F_c)

$$M_{c,k} (u_c, \omega_{rel}) = M_{c,k,max} (\omega_{rel}) u_c$$

$$M_{c,k,max} (\omega_{rel}) = n \frac{r_o + r_i}{2} \mu_c (\omega_{rel}) F_{c,max}$$

The equations that describes this are

$$J_e \dot{\omega}_{c,in} = M_e - M_c$$

$$J_v \dot{\omega}_{c,out} = M_c - M_v$$

The torque transferred through the clutch is

$$M_c (\omega_{rel}) = M_{c,k} (u_c, \omega_{rel}) \operatorname{sgn} (\omega_{rel})$$

where sgn is the signum function. The equations above are valid when $\omega_{rel} \neq 0$.

$$(J_e + J_v) \dot{\omega}_{c,in} = M_e - M_v$$

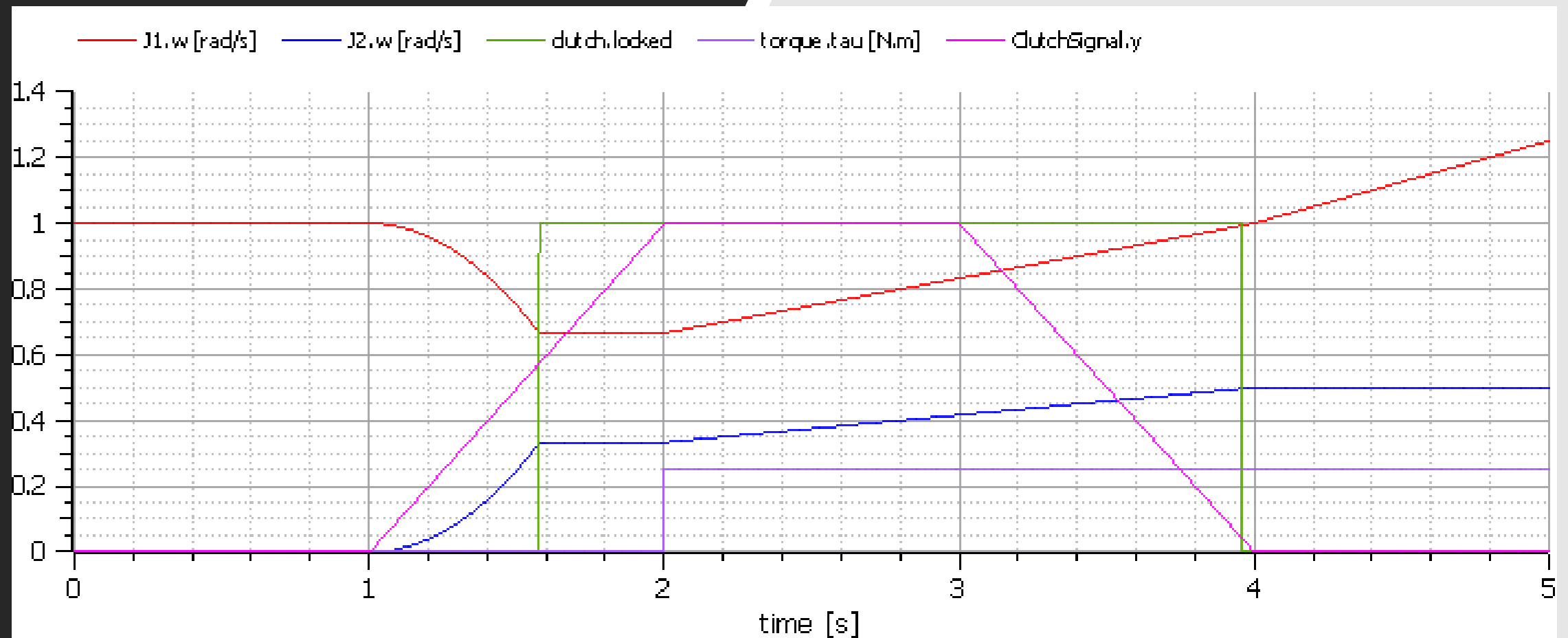
$$\omega_{c,in} = \omega_{c,out}$$

$$M_{c,locked} = M_e - J_e \dot{\omega}_{c,in}$$

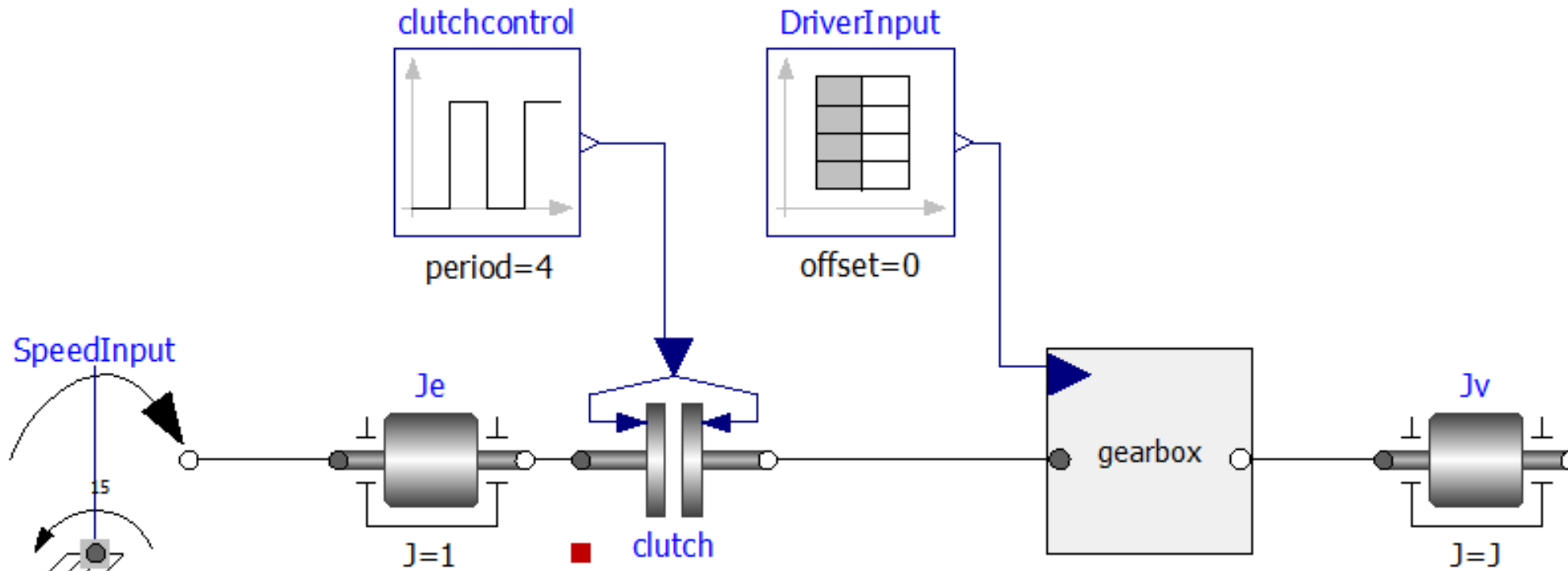
Clutch (Parameters)

- 1) Step torque (0.25Nm) from the engine.
- 2) Trapezoidal Signal is fed to the Clutch.
- 3) Signal 1 – Engaged and Signal 0- Disengaged.
- 4) Gear ratio is 2.
- 5) J_1 and J_2 are engine and vehicle inertias respectively
- 6) Initial angular velocity of engine is 15rad/sec and initially the vehicle is at rest.

Engaging Clutch



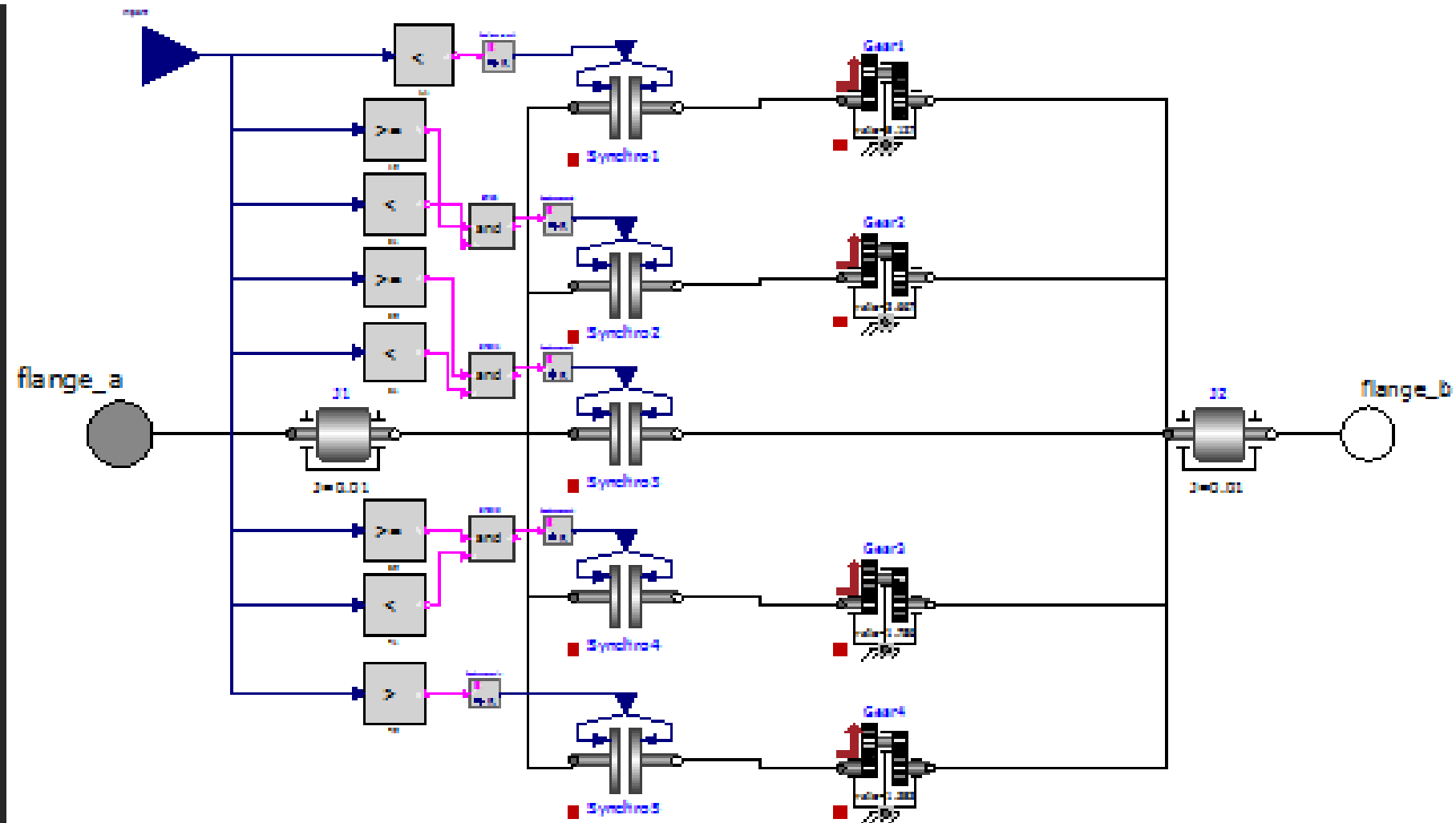
Model of Gearbox-Clutch in Modelica



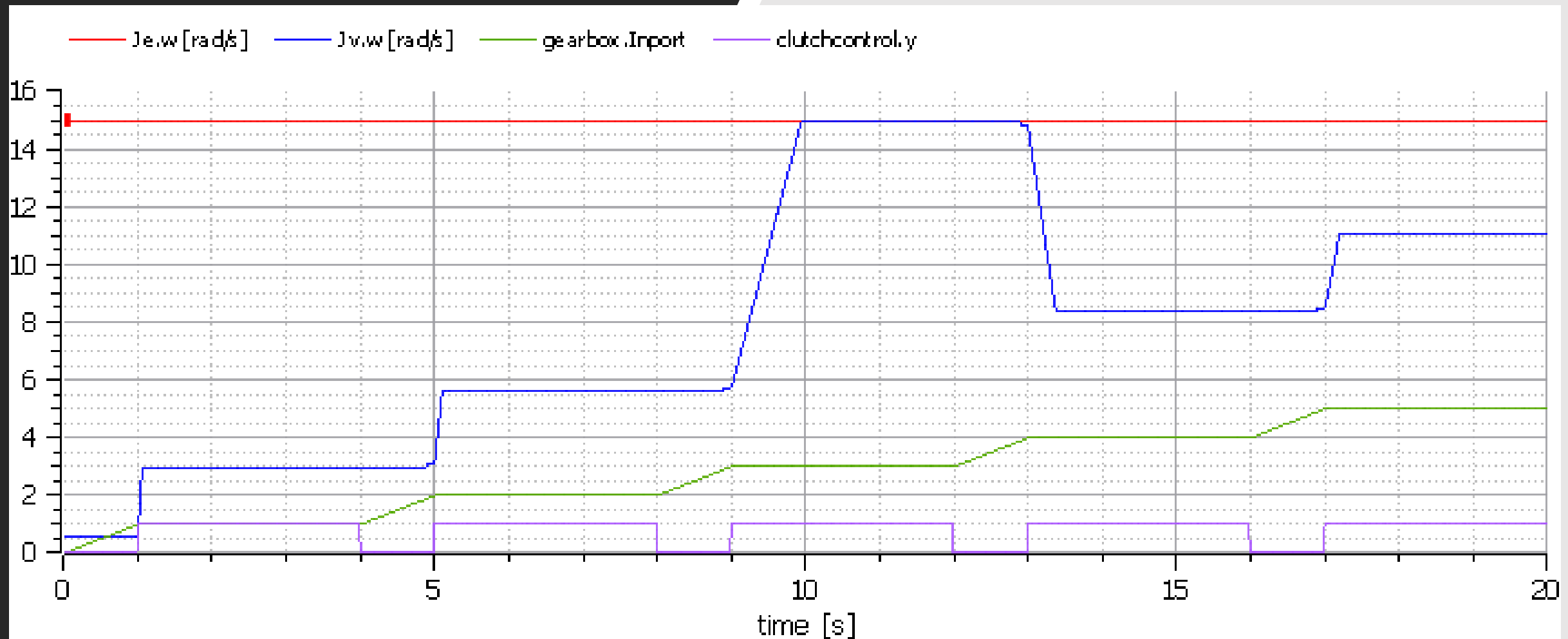
Clutch and Gearbox (Parameters)

- 1) Constant velocity of 15rad/sec at engine shaft, irrespective of the torque
- 2) We want to analyze the velocity variations with shifting gears.
- 3) The vehicle initially is at idle.
- 4) While shifting the gears, the clutch signal is applied to disengage the clutch.
- 5) The clutch signal and gear shifting signal is synchronized.

Model of Gearbox in Modelica



Model of Gearbox in Modelica



References

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